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# TECHNICAL REPORT

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DESIGN AND INSTALLATION OF

A SHIP RESPONSE INSTRUMENTATION SYSTEM

ABOARD THE CONTAINER VESSEL

S.S. BOSTON

PROGRESS REPORT NO. 1 13 DECEMBER 1968

**TELEDYNE MATERIALS RESEARCH COMPANY** 

A TELEDYNE COMPANY

DEPARTMENT OF THE NAVY NAVAL SHIP SYSTEMS COMMAND WASHINGTON, D. C. 20360

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DESIGN AND INSTALLATION OF A SHIP RESPONSE INSTRUMENTATION SYSTEM ABOARD THE CONTAINER VESSEL S.S. BOSTON

Progress Report No. 1

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R. A. Fain, J. Q. Cragin and B. H. Schofield

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TELEDYNE MATERIALS RESEARCH 303 BEAR HILL ROAD WALTHAM, MASSACHUSETTS 02154

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#### SUMMARY

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Progress during this reporting period consisted of design, procurement, and installation of a ship response instrumentation system aboard the container vessel S.S. BOSTON. Included in this report are the following: a detailed description of the system, consisting of the parameters to be measured; the type and location of the transducers installed; components and functional operation of the data acquisition and recording system; data analysis procedures; and equipment specifications.

In addition, a description of the procedure and the results of the first transducer calibration attempt are presented. vi

#### ADMINISTRATIVE INFORMATION

The effort reported herein is being performed under Naval Ship Systems Command, Contract N00024-68-C-5486, Project Serial No. F-35422306, Task 2022, SR 182. Teledyne Materials Research internal project number is 1123/136. Contract control is by the Naval Ship Engineering Center, NAVSEC 6132, Department of the Navy, Washington, D. C. 20360. Mr. John Vasta is the Contract Administrator.

Teledyne Materials Research professional personnel performing this effort are Messrs. F. C. Bailey, B. H. Schofield, J. Q. Cragin, H. G. LaMontagne and R. A. Fain. The primary goal of this investigation is to obtain stress and motion data on this class of vessel and to supplement comparable investigations performed or now being performed on other types of vessels by the same sponsoring agency, i.e., Contract N00024-68-C-5231, Project Serial No. S-F013 0304, Task 2022, SR-153 and SR-172 Ship Response Statistics and Slamming Studies.

### 1.0 INTRODUCTION

The S.S. BOSTON represents a relatively new species of ocean-going vessel which emerged concomitantly with the novel container mode of cargo transportation. Of particular significance is the manifest departure in structural configuration of container ships from the conventional class of cargo ships; notably, the virtual lack of main deck support structure. Because of this structural anomaly, there is considerable interest in the effect such a change will produce in the behavioral characteristics of such vessels. The following sections describe the progress to date of the fabrication and installation of the instrumentation system designed to measure the stress and motion characteristics of the container vessel S.S. BOSTON.

The S.S. BOSTON, Figure 1, is owned and operated by Sea-Land Service Incorporated. Formerly this vessel was the S.S. GENERAL M.M. PATRICK, a C4-SA2 personnel carrier, and was subsequently converted to a C4-X2 container ship by Todd Shipyards Corporation, Galveston Division.

The basic design criteria for this system are twofold:

- 1.1 Create a semi-automatic data collection system to be used for manned voyages on the North Atlantic during the 1968-1969 season.
- 1.2 Provide data in a format compatible with the data collected from other instrumented vessels.

Design of the instrumentation system was initiated June 27, 1968. Installation of transducer components commenced in mid-July, 1968, at Todd's Galveston Yard with final check out and initial data collection originally scheduled for the ship's first European voyage in late October, 1968.

Presumably because of shipyard construction priorities and urgency in the delivery of the vessel to the owner, a substantial portion of the instrumentation cabling, which was to be performed by the yard, was not The vessel was immediately placed into service on a Newark, completed. New Jersey-San Juan, Puerto Rico run. During the loading operations for this voyage a substantial portion of the Teledyne recording equipment was anchored in position in the instrument room. Teledyne engineers then accompanied the ship on one voyage with the intention of completing the shipyard cabling; however, time was not sufficient to finish the work. Subsequently, and upon a few hours' notice the vessel was rescheduled from the New Jersey-San Juan route to a European run. During this latter voyage an agreement was reached with Sea-Land for the completion of the shipyard cabling and final instrumentation wiring on the following European trip. On November 26, 1968, two TMR engineers boarded the vessel to undertake the cabling and place the instrumentation into operation.

At the present time all instrumentation, with the exception of the wave buoy system, is aboard the S.S. BOSTON and all wiring is completed with the exception of the midship transducers (accelerometer and pendulums). Because of the risk involved working the midship area while at sea, the latter will be connected during a port visit.

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### 2.0 GENERAL

Both the recording and signal-conditioning equipment, assembled in a console unit, are located in an instrument room port side, upper deck, just forward of frame 195. Adjacent space has been modified to provide living quarters for personnel operating the equipment. Transducers are located at selected sites throughout the ship, Figure 2A. The location, type, and function of each are more fully discussed in the following sections. Semipermanent cabling running from the vicinity of transducers to the instrument room via junction boxes provide the necessary interconnections. Figure 2B shows a layout plan of the personnel and equipment accommodations aboard the S.S. BOSTON.

#### 3.0 TRANSDUCERS

The transducers in this system are divided into two categories. The first class consists of stress gages arranged in bridge circuits to provide the desired stress for a specific moment orientation relative to the ship, i.e., vertical or horizontal moment. Stress gages are located in housings (see Drawing D-2700) on both the top side and under deck surfaces of the main deck approximately 14-1/2" inboard of the side plate and 15 inches aft of frame 105. Gages in these housings are formed into two bridge circuits which provide outputs induced by vertical and horizontal longitudinal bending moments. See Figures 3A and 3B. The use of gages on both surfaces of the deck plate precludes a possible error due to plate unfairness in the gaging area. The bridge circuits also contain temperature compensation

- 3 -

gages to prevent thermal variations from biasing the data. In addition, each stress gage element is self-temperature compensating for steel applications.

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Torsional shear gages are located in housings positioned on the inboard side of both the port and starboard side plate 20.3 feet above the keel line and 15 inches aft of frame 105. The gages themselves are 2-arm, 45 degrees from vertical, strain gages combined into a single 4-element bridge circuit in a configuration sensitive to torsional stress. A discussion of the torsion transducer installation is presented in Appendix A. See Appendix B and Figure 3C for further details of the torsion transducer.

Additional gages are located in the starboard and port tunnels to measure stresses at local areas. These units are not in housings but are single active gage elements with an associated temperature-compensating gage welded to the area of interest; the elements are then waterproofed and covered. These gages are read as half-bridges with bridge completion resistors located in the instrument room. Finally, two additional stress gages are located on the main deck, starboard side forward in the vicinity of #2 hatch coaming. These gages were incorporated into the data system in order to obtain a measure of the level of shear flow in the structure at the point where the open channel section of the hull terminates into the typical box beam section.

The second class of transducers are those located throughout the ship to provide information as to the structural or physical response of the vessel to the operational environment simultaneously with the measurement and recording of the structural stresses. These transducers provide vertical and horizontal (athwartship) acceleration at the bow, midships and stern, and pitch and roll angle midships. An equally significant portion of this class of transducers is the wave height buoy measuring system. This system consists of two basic items: 1) free floating wave buoys and, 2) a receiver-recorder system. The free floating buoys contain an accelerometer transducer and a radio transmitter unit with associated whip antenna. Figure 4 shows an outline sketch of such a buoy. As the buoy translates vertically with the waves, after launching from the ship, a signal is transmitted to the receiver unit aboard ship and recorded on magnetic tape. Subsequent analysis of these data provides an accurate measure of the wave height environment which is obtained for correlation with the data acquired from other transducers.

Two additional transducers are located in the tunnels; one port, one starboard, on the underdeck between frames 105 and 106. These devices measure longitudinal displacement of the deck over a 30-inch gage length to supplement the data obtained from the stress gages mounted in this vicinity.

A functional block diagram (Drawing D2749) is included to show the manner in which transducers are assembled to form a recording system.

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The functional flow diagrams (Drawings D2750 SH1-SH6) included show the actual signal path from transducer to the instrument room and tape deck. Appendix B provides additional information as to the transducers used aboard this vessel.

#### 4.0 INSTRUMENT ROOM EQUIPMENT

With the exception of the transducers, junction boxes and cabling, the remainder of the Teledyne Instrument System is located in the instrument room. Various units are packaged into a five-bay console unit which is the dominant feature of this room. Drawings D2751 SH1-SH3 included in this document, outline the various units found in the console. The equipment selected performs one of two functions i.e. it is directly involved in the excitation, conditioning or monitoring of transducer signals, or it is check out equipment used in the set-up, calibration and maintenance of the entire system. Additional portable instrumentation has been placed aboard the vessel to assist in system maintenance. Power to the console is supplied from the ship's hotel service in the form of four 20-ampere circuits of 115 V, 60 Hz from four circuit breakers in power panel C-TM1. This power is distributed throughout the console to various units. The console contains adequate protection of each active circuit as well as visual indications as to the status of each circuit (pilot lamps). (See SH3 Drawing D2751).

A key item in this system is the Ampex Model FR 1300, 14-channel FM tape recorder mounted on the right side of the console. (See Figure 5). A copy of the specifications of this unit is found in Appendix C.

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The data channel assignment is as shown on the recording system block diagram, Drawing D2749. It is envisioned that most recording will be at a tape speed of 1-7/8 ips with its associated frequency response of 0 to 625 Hz. In the event that frequencies of higher magnitude are deemed of interest, the recording speed can be increased proportionally.

The various panels and units within the console are connected via a series of cables. Table 1 summarizes the characteristics and functions of these cables and presents an insight into the complexity of the system.

## 5.0 JUNCTION BOXES AND SHIP'S CABLING

The locations of junction boxes and their associated cabling are shown on Drawing D2699A. A comprehensive listing of junction boxes is provided in Table 2 and descriptive information on the cabling in Table 3.

#### 6.0 SYSTEM OPERATION

The system, as previously stated, is semi-automatic in design. The variety of mode operations is controlled by the programmer unit shown in Figure 6. In the automatic mode the system is turned on for a specified interval at preset hours. Initial settings have been selected for an interval of 15 minutes every four hours with the tape recorder set to run at 1-7/8 ips. During this 15-minute interval three data periods are recorded. Each data period presently consists of 15 seconds of zero; i.e., open-circuiting of transducer signal lines and removal of excitation from bridge circuits; one minute of calibration, i.e., shunting of one arm of the bridge circuits with a specified resistance, or, in the case of the

accelerometers, substitution of a calibration voltage; and a period of 3 minutes 45 seconds of data collection. During the 60 seconds of calibration the bridge-shunting resistance is cycled on and off approximately 10 times to create a series of calibration spikes which are used to trigger in-house data analysis equipment. All of the times selected are variable with the operator having complete flexibility of time settings.

In addition, upon the occurrence of a signal (from a selected bridge circuit) higher than a preset stress level, the system generates an alarm and automatically goes into a recording sequence. The length of this sequence is again controllable and is presently set for 15 minutes. At the end of this period the equipment is reset; in the event the high stress condition still exists, a repeat cycle is immediately initiated.

At any time, the operator can switch the system to manual and go into a continuous recording mode. Even in this manual mode, the zerocalibration sequence is performed at the set interval so that all data will be compatible in format.

The system starts and stops the tape recorder as required and keeps track of total time recorded.

The wave monitoring system is a separate integral unit and contains its own 2-track audio tape recorder. This system is placed into operation when a wave buoy is launched from the vessel. The transmitted information is recorded as long as signal strength permits; in the order of 30 to 40 minutes. It is planned to launch four buoys during this winter season when the sea conditions are Beaufort State 6 or above.

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In addition to data recorded on the two tape recorders, log book readings, recorded once each watch, will provide information as to ship's position and speed, the relative wind direction and speed and the conditions of the sea at that time.

7.0 ON-BOARD DATA ANALYSIS

During non-recording intervals aboard the vessel it is planned to have the operator perform "quick look" data analysis. This analysis involves placing the recorder in a play-back mode and playing the data into an oscillograph to create chart paper data traces. Up to six data channels at a time can be presented in this manner. The operator, by analyzing these traces, can determine the condition of each of his data channels. Changes in gain, calibration or general maintenance can then be accomplished to ensure that the system is in top running condition.

In addition, a time correlation with log book data will be performed to ensure that trace response is compatible with wind and sea conditions.

8.0 <u>IN-HOUSE DATA REDUCTION</u>

Since it will be possible to acquire data on a selective basis, and since the items of primary interest in this instance are maximum values and the relation of ship and container data, it is expected that the bulk of the analysis can be performed by the engineer aboard ship, who will be equipped with oscillograph playback equipment. However, if required, the probability analyzer is available in the laboratory to permit rapid searches for maximum values and for developing certain other statistical parameters of the data. At the conclusion of each voyage, the tapes and log books will be returned to Teledyne Materials Research at Waltham, Massachusetts. The tapes will be

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re-run on a compatible Ampex Model 1260 Tape Recorder (see Figure 7). The processed information is placed on a punched card suitable for computer input. In addition, ship, wind, and sea information for each data period is also punched on the card. Thus, when a reel of tape has been processed, one punched card contains the information from each data period. These cards are fed into an in-house IBM Computer. The computer printout contains the values of peak-to-peak and RMS stress levels for each stress channel corresponding to the various sea states.

The wave buoy tapes will be analyzed by a computer program in order to produce wave spectra information for correlation with the stress data.

### 9.0 S.S. BOSTON CALIBRATION

Strain gage data were recorded from the partly completed instrumentation systems on the S.S. BOSTON during the period from August 8 to 29, 1968, for the purpose of obtaining a physical calibration of the system. Strain data acquired while statically bending the ship with known loads permits a comparison with computer calculations of the structure's behavior. Specifically, the calibration was required not only to provide verification of the integrity of the measuring system in comparison to

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computed values, but to evaluate the effectiveness of strain gages on one side of a shell plate in presenting heart-of-plate data. Figure 8 shows the calibration conditions used. Conditions shown in b, e, and h were selected for the computer analysis.

Vessel calibrations are carried out, whenever possible, on calm, cloudy nights in order to minimize the effects of differential thermal distributions. Since the load conditions on the S.S. BOSTON were to be varied at a very slow rate, the calibration had to be undertaken over a 21-day period while ballast mud was being placed in the double-bottom spaces of the vessel. In an attempt to improve the possibility of salvaging meaningful data under these conditions, stress measurements were taken at frequent intervals in the hope that thermal effects could be separated from stress changes resulting from the known loads. As will be noted in the following discussions, this was not possible probably because of the numerous other factors involved, such as changes in vessel position and continued addition of structural material during the calibration.

Although some meaningful data were acquired, it is felt that the system should be recalibrated under more tightly controlled and optimized conditions. This recalibration should be performed with known weight containers and ideally performed in an overnight period to minimize thermal problems.

The strain gages themselves are matched to the coefficient of expansion of the structure but the vessel still sees "real" strains imposed by differential heating of the vessel. In many cases in the August period, the thermally-induced strains were higher than the ballast load-induced strains.

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It is also recommended that proper stiffnesses, weights and locations be used. An independent naval architect familiar with torsion of ships with large deck openings should review the analysis for adequacy.

The current Designers & Planners' data are superimposed on the heart-of-plate experimental strain data in Figures 12, 13 and 14. Agreement with this quite fundamental analysis is unacceptable, as well as some unexplainable scatter within the sets of gages at any particular location that should all sense the same strain magnitude.

The Designers & Planners' calculated starboard deck data are compression in sense due to the large contribution of what they term "deck stress due to torsion." This value is added to port and subtracted from starboard deck stress, greatly influencing, somewhat questionably, the value and sign of the deck stress.

A recalibration of the system should be performed for the following reasons:

- Too many extreme thermal cycles in the August period tend to mask the load-induced strain data.
- Wiring of the system is now completed; thus the problems with temporary cabling will not be repeated.
- All future data generated by the system will be based upon the results of a good calibration.

This vessel recalibration and predicted stress correlation should have the following ground rules:

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Typical of any transducer application of strain gages, exercise of the system improves its performance. A study of the back-to-back gages on the S.S. BOSTON shows that the inside to outside error is gradually reduced to essentially one value after as few as three cycles of thermal and/or physical strain. The final difference is approximately 5µε, equal to the minor scale division on the readout equipment. See Figures 9, 10, and 11.

Because of shipyard production problems, internal cabling of the vessel was not finalized at calibration time, so port and starboard data were acquired as one-half bridge rather than the desired full bridge configuration. As one-half bridges, the torsion transducers bonded to the side shell are sensitive to both vertical shear and torsion of the vessel. Ordinarily, these would be separable, but here, with the unknown thermal effects superimposed, it is impossible to obtain explicit values for all the contributing factors.

Designers and Planners, Inc. of New York were asked by Sea-Land to use their computer facilities to predict stresses in the gaged locations for correlation with the experimental data. An existing bending program was used without modification for the state-of-flux structural condition of the vessel. Ballast load inputs used were not from the S.S. BOSTON, but from a non-identical sister ship, the NEWARK.

It is recommended that a combined torsion and bending program be used by Designers & Planners to predict more closely calibration loading stresses.

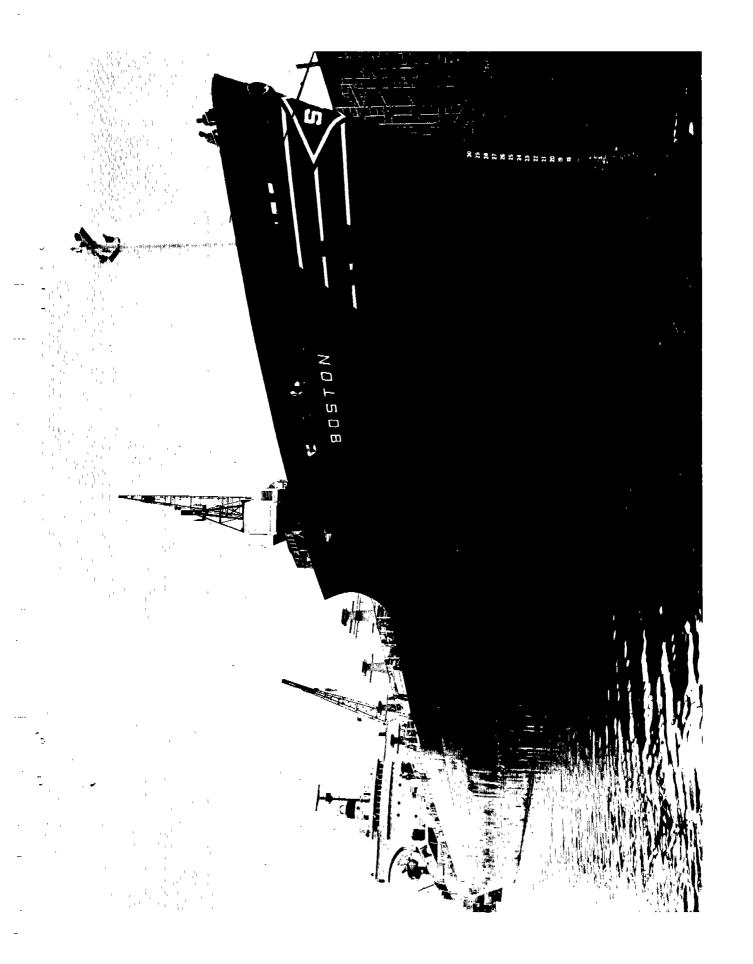
- 12 -

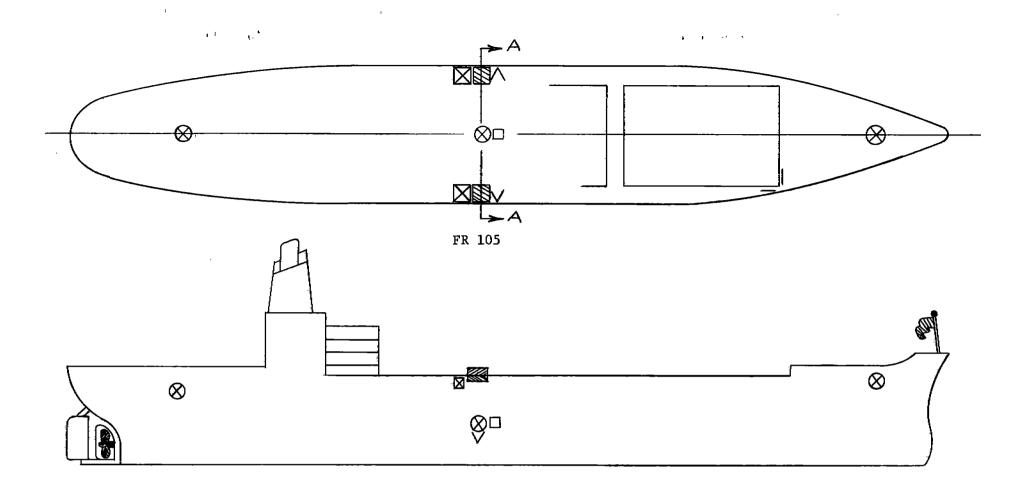
- Calibrate overnight during a period of reasonably constant temperature.
- Use containers with known loads, located at known distances from the midship datum.
- Modify the Designers & Planners' computer program to include torsion and have the technique approved by a structural specialist.
- 4. Most important is to accept the fact that a quality calibration is of prime value, and have no other major shipboard activity progressing during the calibration period.

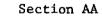
#### 10.0 CONCLUSIONS

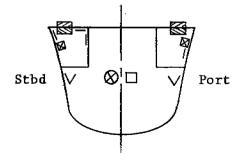
At the present time the instrumentation system has been installed aboard the S.S. BOSTON, wired, checked out and is expected to be in operation collecting data on the run from Europe beginning December 9. The only exception to completion is the final wiring of the midship accelerometers and pendulum devices as noted in the body of this report.

It is anticipated that during the next report period the midship transducers will be placed into operation, and that data analysis will be underway contemporaneously with the collection of additional data aboard the S.S. BOSTON.









Transducers at Midship Section Including Box Beam Gages

- ⊗ Bi-directional accelerometer (horizontal-vertical)
- Pendulum transducers for pitch and roll
- Stress gage transducer
- 30-inch gage length displacement transducer
- 🗸 Torsional strain gage bridge.
  - Single element stress gages, longitudinal orientation

FIGURE 2A. SCHEMATIC VIEW OF VARIOUS TRANSDUCER LOCATIONS ON SS BOSTON

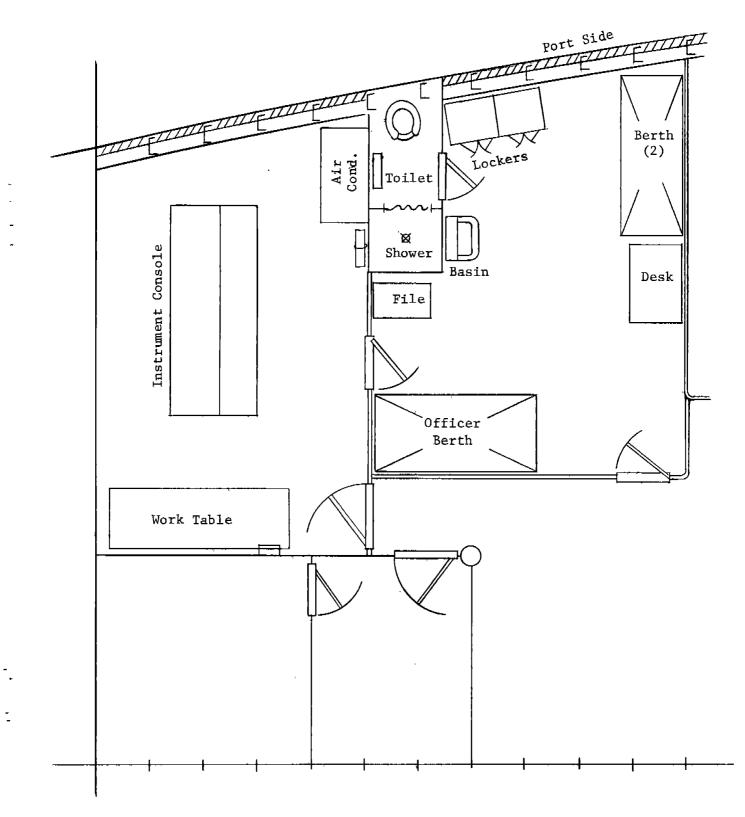
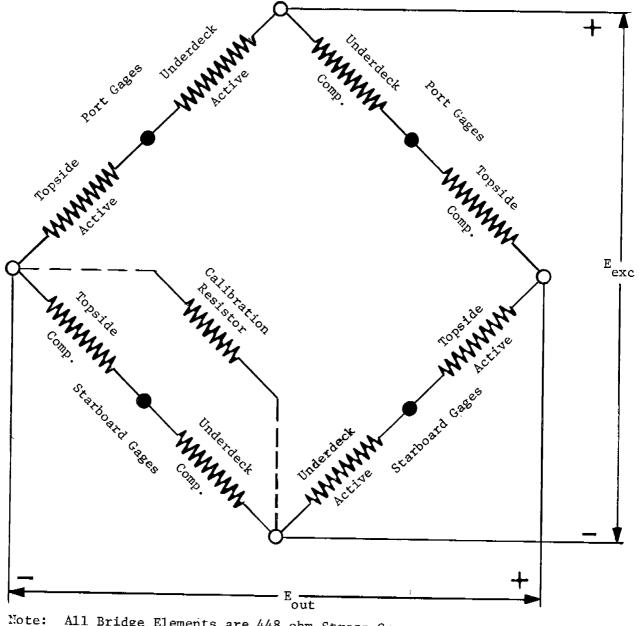
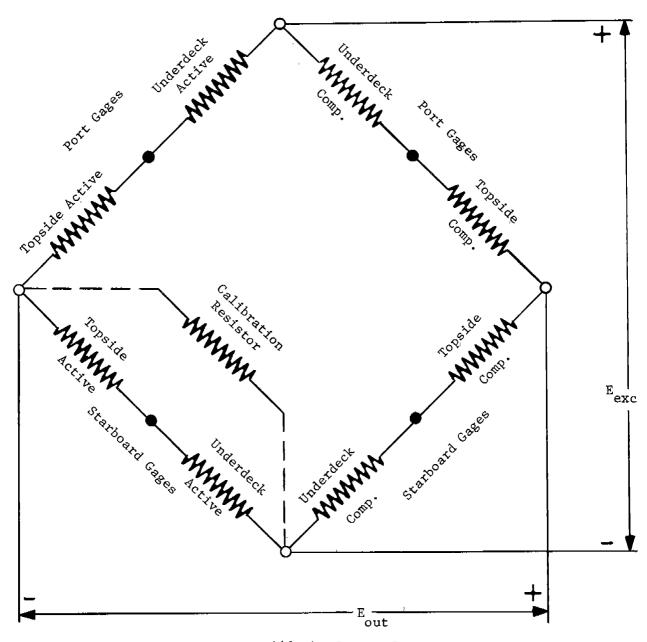


FIGURE 2B. SKETCH SHOWING LAYOUT OF INSTRUMENTATION ROOM AND SCIENTIST/OBSERVER LIVING QUARTERS ON SS BOSTON



All Bridge Elements are 448 ohm Stress Gages

FIGURE 3A. BRIDGE CIRCUIT - VERTICAL LONGITUDINAL BENDING



Note: All Bridge Elements are 448 ohm Stress Gages

FIGURE 3B. BRIDGE CIRCUIT-HORIZONTAL LONGITUDINAL BENDING

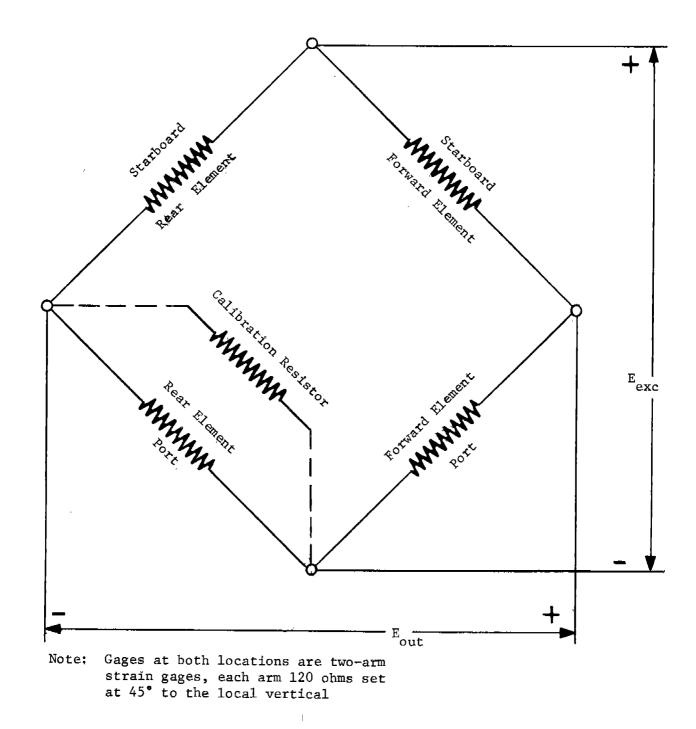
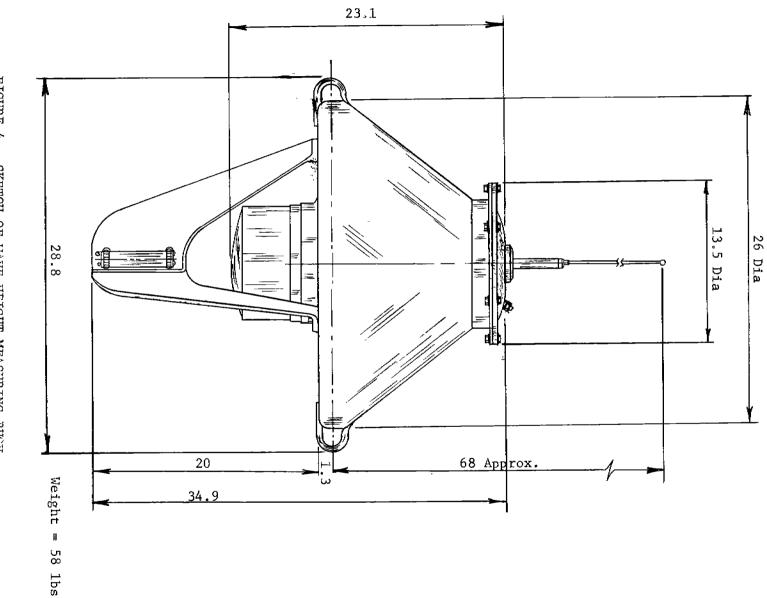


FIGURE 3C. BRIDGE CIRCUIT-TORSIONAL STRESS





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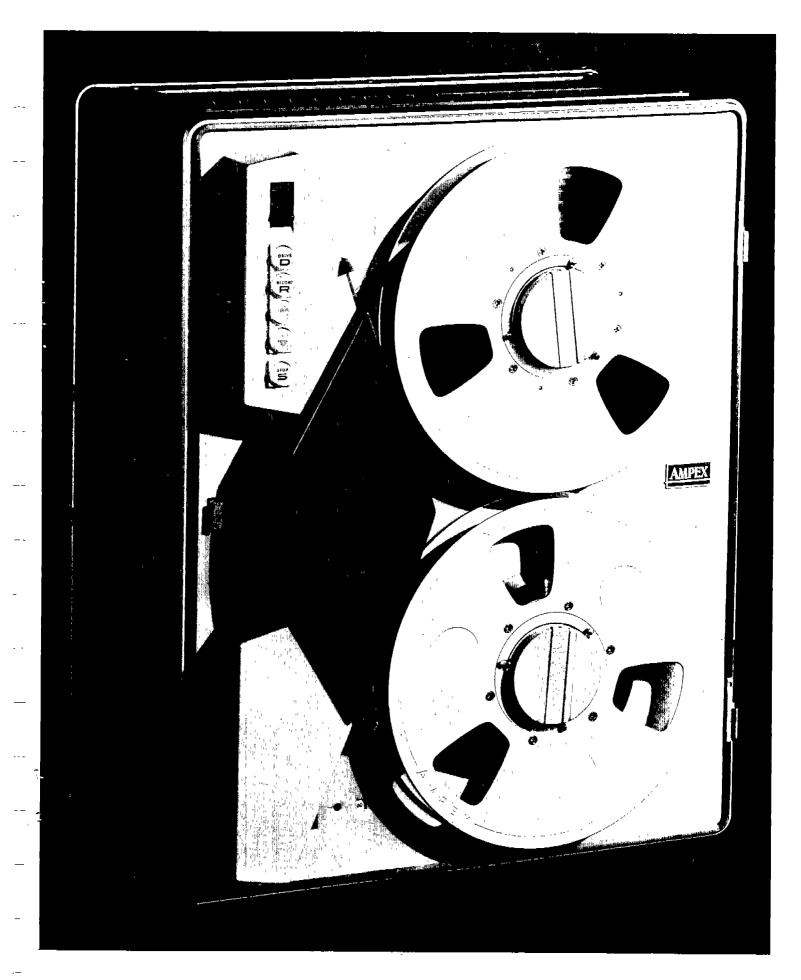
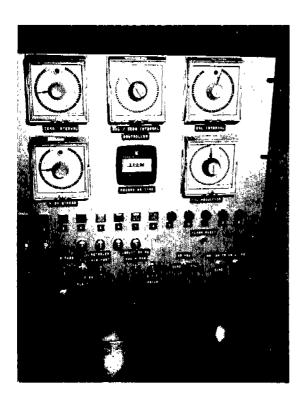
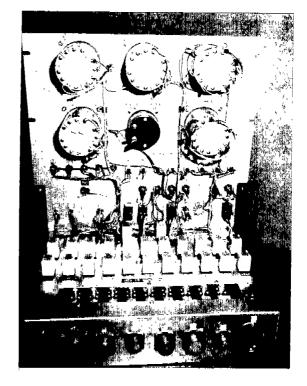


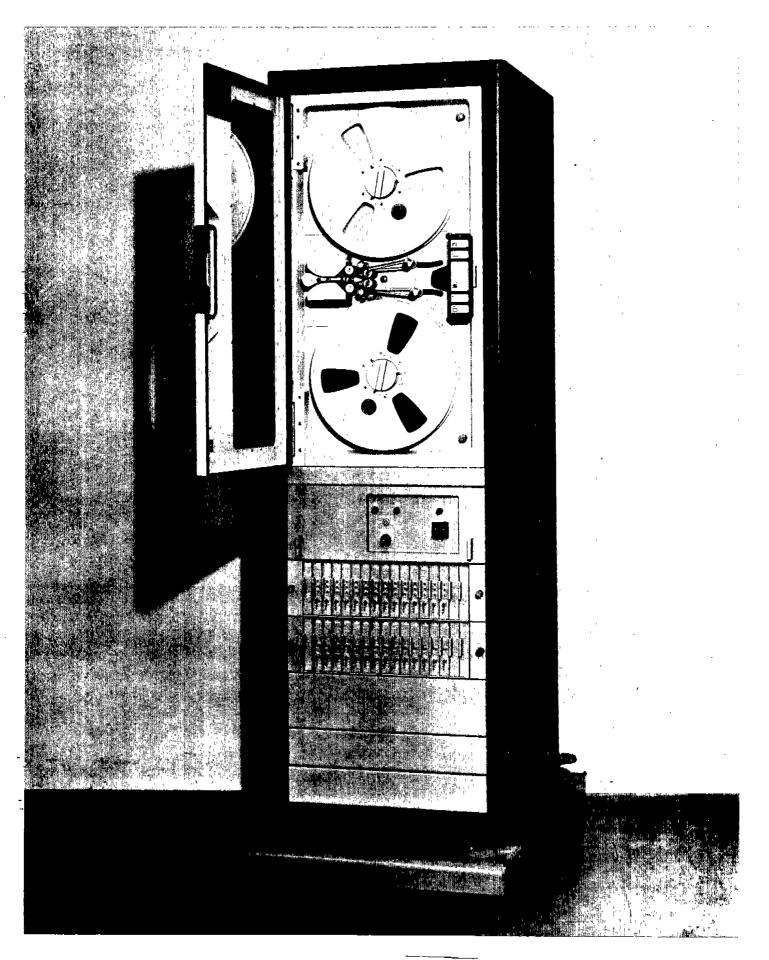
FIGURE 5. 14-CHANNEL SHIPBOARD TAPE RECORDER AMPEX MODEL FR 1300



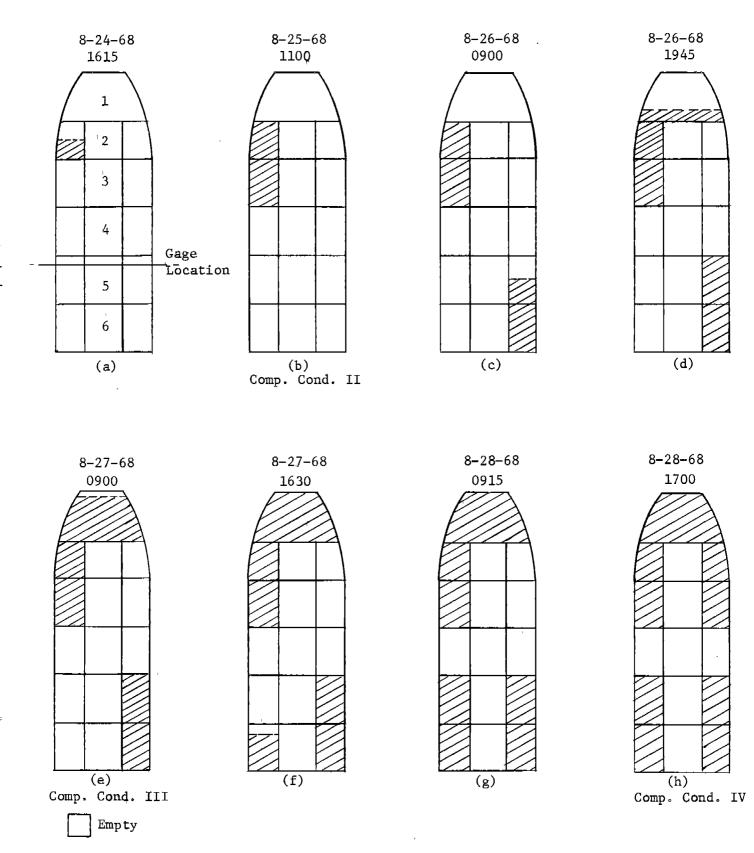
(a) Front Panel of Unit



(b) Rear View of Unit



## FIGURE 7. DATA ANALYSIS TAPE RECORDER AMPEX MODEL 1260



Full of Ballast Mud

FIGURE 8 Dockside Calibration Conditions Using Double-Bottom Tanks

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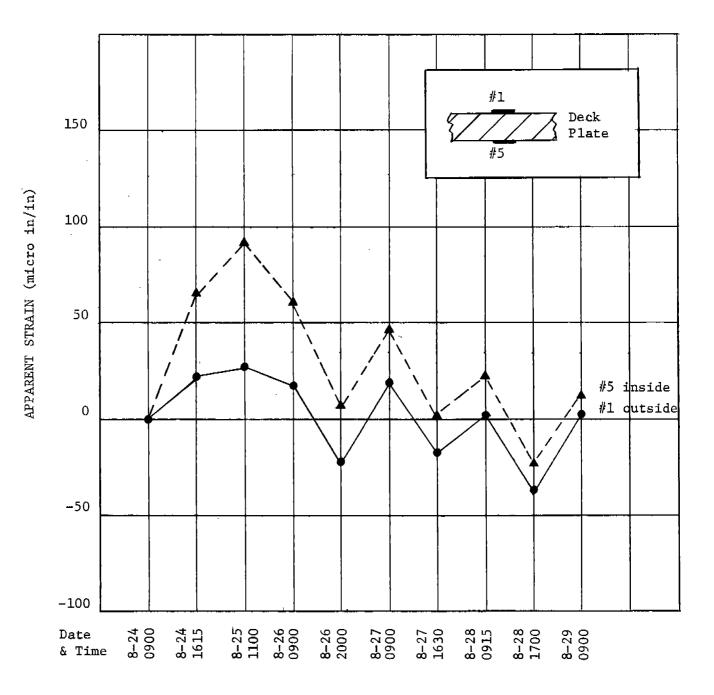


FIGURE 9

Starboard Deck Gages 1 & 5 An Example of Poor Inside-Outside Correlation

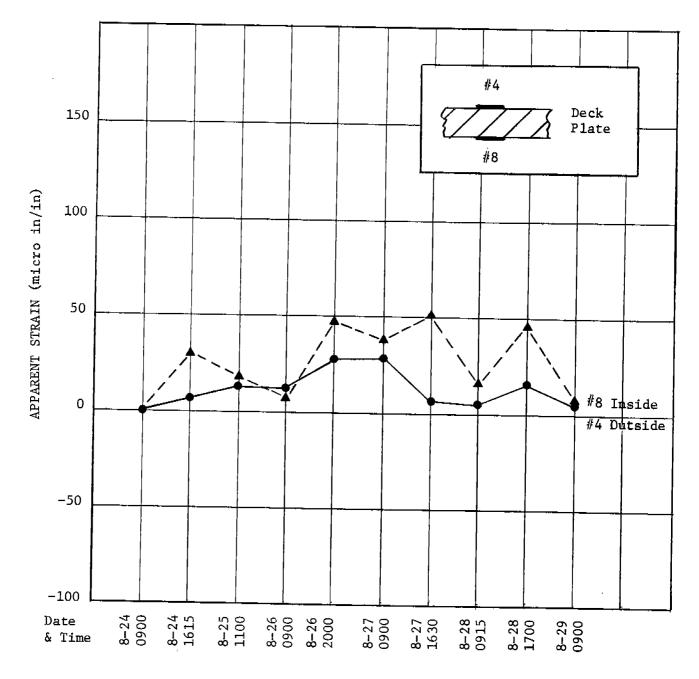


FIGURE 10

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Port Deck Gages 4 & 8 Typical Inside-Outside Correlation

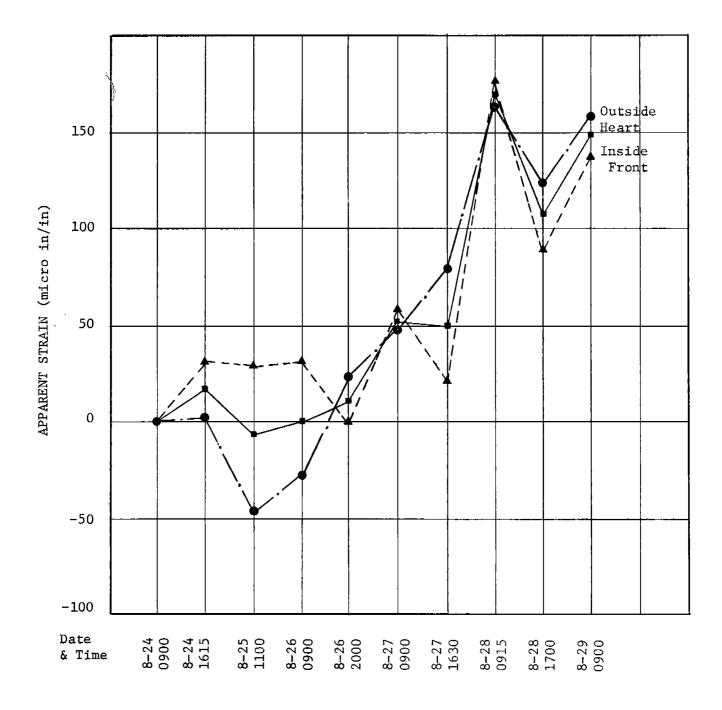


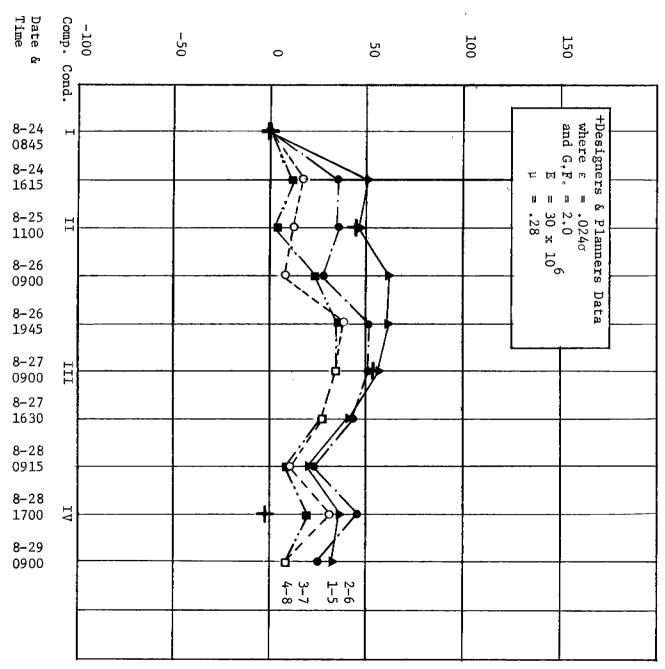
FIGURE 11

Port Shear Gages-Outside & Inside Front Poor Inside-Outside Correlation

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Heart of Plate Strains Port Deck Gages

FIGURE 12



APPARENT STRAIN (micro in/in)

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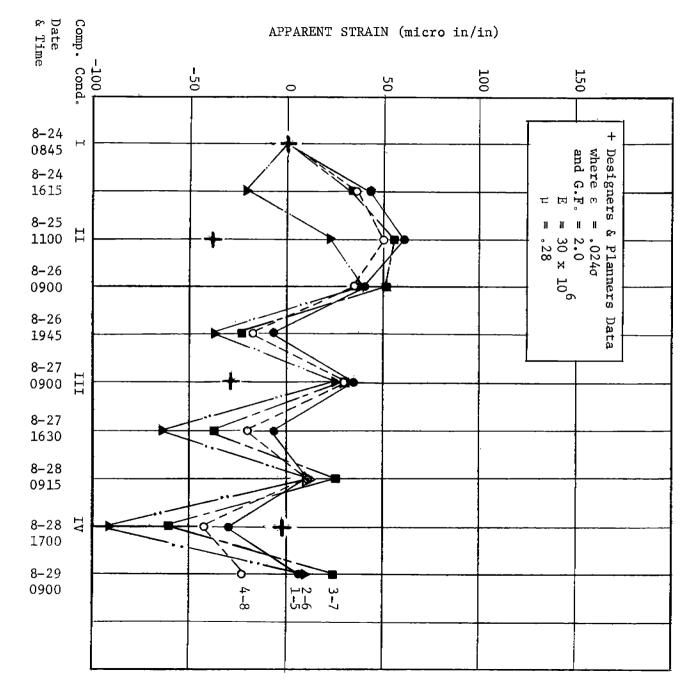
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Heart of Plate Strains Starboard Deck Gages

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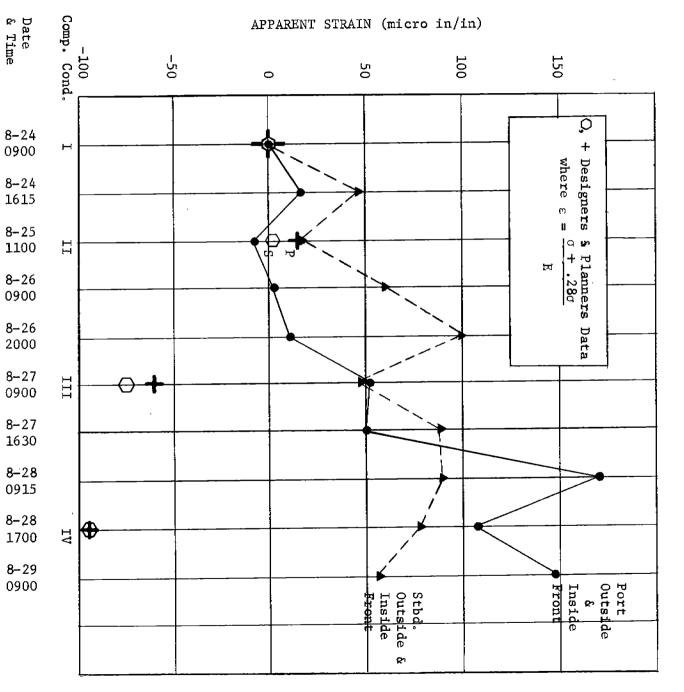
FIGURE 13



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Heart of Plate Strains Shear Gages

FIGURE 14



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Console				
Cable No.	From	То	Size/Function	Cable Type
1	24-Hr. Timer	Programmer	4 Cond. AWG #20 Timing Signals	Belden 8424
2	Programmer	Stress Monitoring Panel	8 Cond. AWG #20 Stress Signals	Belden <b>8</b> 418
3	Programmer	T <b>a</b> pe Recorder	6 Cond。 AWG #20 Control Signals	Belden 8426
4	Programmer	Signal Condítioning Equipment	6 Cond. AWG #20 Control Signals	Belden 8426
5	Power Supply #8	Programmer	4 Cond. AWG #20 DC Power	Belden 8424
6	Junction Box C-TM12	Programmer	20 Cond. AWG #20 Transducer Signals	MSV-20
7	Programmer	Junction Box C-TM 12	12 Cond. AWG #20 Calibration Com- mands	Alpha 1255/12
8 4 Req'd. 8.1, 8.2, 8.3, 8.4.	S.C. Xducer Output Jack	S.C. Amp. Input	2 Cond. AWG #20 Bridge Signals	Belden 8412
9 4 Req'd. 9.1, 9.2 9.3, 9.4.	S.C. Amp. Output Jack	Stress Monitoring Panel	2 Cond. AWG ∦20 Bridge Signals	Belden 8412
10	S.C. Monitoring Jack	Stress Monitoring Panel	2 Cond. AWG #20 Excitation Voltage	Belden 8412
$ \begin{array}{c} 11.1\\ 11.2\\ 11.3 \end{array} $	Junction Box GTM11A&B	S.C. Equip. Xducer Input CH1, CH2, CH3.	8 Cond. AWG #20 Bridge Signals	Belden 841 <b>8</b>

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## S.S. BOSTON CONTROL CONSOLE CABLING

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## S.S. BOSTON CONTROL CONSOLE CABLING

## (Continued)

Console Cable No.	From	То	Size/Function	Cable Type
11.4	Conditioning Channel Select Pane	S.C. Equip. Xducer Input CH. 4	8 Cond. AWG #20 Bridge Signals	Belden 8418
12	J.B. C-TM11B	Conditioning CH. Select Panel	6 Cond. AWG #20 Port Tunnel Signals	Belden 8426
13	J.B. C-TM11A	Conditioning CH. Select Panel	20 Cond. AWG #20 Stbd. Tunnel Signals	MSV-20
14	J.B. C-TM10	Conditioning CH. Select Panel	12 Cond. AWG #20 Bow Coaming Signals	Alpha 1255/12
15	Oscillograph Play-Back Panel	Oscillo- graph	12 Cond. AWG #20 Play-Back Signals	Alpha 1255/12
16	Junction Boxes C-TM11A & B	Displace- ment Trans- ducer Panel	4 Cond. AWG #20 Displacement Signals	Belden 8424
17	Power Supply #7	J.B. C-TM12	4 Cond. AWG #20 DC Power	Belden 8424
18	Power Supplies #1 to #4	J.B. C-TM12	20 Cond. AWG #20 DC Power	MSV-20
19	Power Supplies #5 & #6	J.B. C-TM11A & B	8 Cond. AWG #20 DC Power	Alpha 1255/8
20 2 Req <b>'</b> d.	Power Panel C-TM1	Console Power	4 Cond. AWG #10 AC Power	Types

NOTE: All cables are overall shielded with rubber or vinyl jacket.

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Junction Box Number	No. of Terminals	Physical Location
C-TM1	40	Stbd, Side FR 129
C-TM2	40	Stbd. Side FR 97
C-TM3	40	Stbd. Side FR 65
C-TM4	40	Stbd. Side FR 47
CTM5	40	Amidships FR 13
С-ТМб	40	Amidships FR 195
C-TM7	40	Amidships FR 112
С-ТМ8 С-ТМ9	Deleted Due to New Cable Rout	ing
C-TM10	40	Aft Bulkhead TMR Room
C-TM11A	80	Aft Bulkhead TMR Room
C-TM11B	80	Aft Bulkhead TMR Room
C-TM12	80	Aft Bulkhead TMR Room
C-TM13	10	Aft Bulkhead TMR Room
C-TM14	80	Port Tunnel FR 105
C-TM15	80	Stbd. Tunnel FR 105
C-TM16	10	Bridge Deck

## S.S. BOSTON JUNCTION BOX SPECIFICATIONS

NOTE: Power Panel CTM-1 is in Instrument Room.

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Cable No.	From Junction Box	To Junction Box	Size/Function	Cable Type	
C-TM1	C-TM10	C-TM1	10 AWG #18 Power Containers	MSV-10	
C-TM2	C-TM10	C-TM1	20 AWG #20 Container Measure- ments	MSV-20	
C-TM3	C-TM1	C-TM2	10 AWG ∦18 Power Containers	MSV-10	
C-TM4	C-TM1	C-TM2	20 AWG #20 Container Measure- ments	MSV-20	
C-TM5	C-TM2	C-TM3	10 AWG #18 Power Containers	MSV-10	
С-ТМб	C-TM2	C-TM3	20 AWG #20 Container Measure- ments	MSV-20	
C-TM7	C-TM3	C-TM4	10 AWG #18 Power Containers	MSV-10	
C-TM8	C-TM3	C-TM4	20 AWG #20 Container Measure- ments	MSV-20	
C-TM9	C-TM15	C-TM11A	70 AWG #20 Stbd. Signals	MSV-70	
C-TM10	C-TM14	C-TM11B	70 AWG #20 Port Signals	MSV-70	
C-TM11 C-TM12	Deleted due	Deleted due to cable rerouting.			
C-TM13	C-TM5	C-TM12	20 AWG #20's FWD. Accel.	MSV-20	
C-TM14	C-TM6	C-TM12	20 AWG #20's Stern Accel.	MSV-20	
C-TM15	C-TM7	C-TM12	30 AWG #20's Midships Motions	MSV-30	

## S.S. BOSTON SHIPBOARD CABLING

NOTE: All cables overall shielded with rubber or vinyl jacket.

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## S.S. BOSTON SHIPBOARD CABLING

## (Continued)

Cable No.	From Junction Box	Junction Box	Size/Function	Cable Type
C-TM16	C-TM16	C-TM13	6 Cond. & Shielded	TTRSA-6
C-TM17	Hotel Service	Power Panel CTM-1	PR Bridge Communi- cations as Required	TSGA-23
C-TM18	Bow Acceleration Box	C-TM5	20 AWG #20 Bow Accelerations	MSV-20
C-TM19	Stern	C-TM6	20 AWG #20 Stern Accelerations	MSV-20
C-TM20	Midships Acceleration Box	C-TM7	12 AWG #20 Heave & Sway	Alpha 1255/12
C-TM21	Midships Pendulum Box	C-TM7	20 AWG #20 Pitch-Roll	MSV-20
C-TM22	Port Topside Housing	C-TM14	12 AWG #20 Port Topside Stress	Alpha 1255/12
C-TM23	Port Under- side Housing	C-TM14	12 AWG #20 Port Underdeck Stress	Alph <b>a</b> 1255/12
C-TM24	Port Torsion Housing	C-TM14	8 AWG ∦20 Port Torsion	Belden #8418
C-TM25	Port Displace- ment Gage	C-TM14	4 AWG ∦20 Port Displacement	Belden #8424
C-TM26	Port Side Weld Gage	C-TM14	8 AWG #20 Side Weld Stress	Belden #8418
C-TM27	Stbd. Underdeck Housing	C-TM15	12 AWG #20 Stbd. Underdeck Stress	Alpha 1255/12
C-TM28	Stbd. Topside Housing	C-™15	12 AWG #20 Stbd. Topside Stress	Alpha 1255/12
C-TM29	Stbd. Under- deck and Box Beam Gages	C-TM15	12 AWG #20 Stbd. Tunnel Stresses	Alpha 1255/12
C-TM30	Stbd. Disp. Gage	C-TM15	4 AWG #20 Stbd. Displacement	Belden #8424
C-TM31	Stbd. Side Plate Gage	C-TM15	8 AWG #20 Stbd. Side Stress	Belden #8418
C-TM32	Stbd. Torsion Gage	C-TM15	8 AWG #20 Stbd. Torsion	Belden #8418
C-TM33	Bow Coaming Gages	С-ТМ4	12 Cond. AWG #20 Bow Stresses	Alpha 1255/12

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## TABLE 4 CHARACTERISTICS OF SS BOSTON

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Original Name: GEN. M.M. PATRICK Builder: Kaiser Richmond (Hull #16) Converter: Todd Shipyards Corporation Galveston Division (Hull #87) Type: C4-SA1 converted to C4-X2 Container Ship Official Number: 511585 Length Overall: 522' - 10 1/2" Length Between Perpendiculars: 496' - 0" Breadth, Molded: 71' - 6" 45' - 6" Depth, Molded to Upper Deck @Side: 35' - 0" Depth, Molded to Second Deck: Depth Molded to Tank Top: 5' - 0" Tonnage (U.S.) Gross: 11,521.77 Net: 7,607.00 Draft Scantling (Full Load): 30' - 6" Full Load Displacement: 20,250 Tons S. Water Draft Light Ship: 17' - 8" Dead Weight: 9,317 Light Load Displacement: 10,933 Tons S. Water Center of Gravity Full Load: l.c.g. 1.35' aft amidships, v.c.g. 27.04' above base line Light Ship: 1.c.g. 1.13' fwd amidships, v.c.g. 18.2' above base line Machinery: Steam Geared Turbine Shaft Horsepower - Max. Cont. 9,900 S.H.P. Propeller (1) 5 Bladed 21' - 8" Dia. Container Capacity (No.) 360 L = 35' = 0''Container Geometry: W - 8' - 0''H - 8' - 6 1/2''

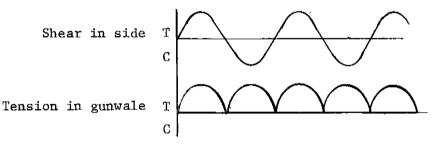
### APPENDIX A

### TORSION TRANSDUCER INSTRUMENTATION

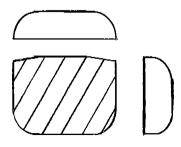
In the discussion below consideration is given to the location and electrical arrangement of the strain gage bridge installed for the measurement of the shear stress due to torsion about the longitudinal axis. The influence of the existing stresses is evaluated demonstrating the exclusion of the effect of other stresses on the torsional measurement.

### A. STRESSES PRESENT

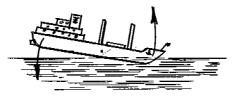
- 1. Shear
  - (a) Torsion around longitudinal axis .
    - Shear stresses present in main deck, sides and bottom;
       no shear in area of gunwales and turn of bilge.
    - (2) Gunwale and turn-of-bilge stresses tensile at twice the frequency of torsion



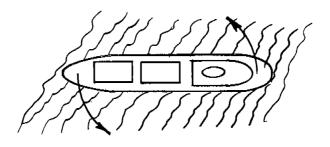
(3) Shear stresses fairly uniform, dropping sharply to zero at gunwales and turn-of-bilge.



(b) Pitching motion induces shear in sides, none in deck or bottom.

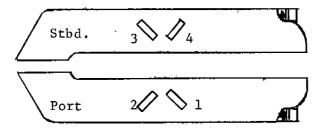


(c) Yawing induces shear in deck and bottom, none in sides.



- 2. Bending
  - (a) Longitudinal in vertical plane main deck and sides above neutral axis in compression while bottom and sides below neutral axis in tension.
  - (b) Longitudinal in horizontal plane port side and portside of deck and bottom in compression while starboard side and starboard side of deck and bottom in tension.

## B. GAGE PLACEMENT AND HOOKUP



Strain gages are mounted at midships close to neutral axis at  $45^{\circ}$  to longitudinal axis. Gages 1 and 2 are on port side, gages 3 and 4 are on starboard side. Gages mounted /\ or \/ to keep them same distance from neutral axis.

### Table 1

SUMMARY OF STRESSES INDUCED IN EACH STRAIN GAGE OF THE TORSTON BRIDGE

			- <b></b> .		-
		ST <u>RAJ</u>	N GAGE	· · · · · · · · · · · · · · · · · · ·	4
Induced Stress	1	2 Stress Di	3 rection	4	Net Stress Measured
Torsion-Long. Axis	с	T	С	Т	Torsion
Shear-Pitching	С	Т	Т	С	None
Shear-Yawing	0	0	0	0	None
Bending-Horizontal	C	<sup>+</sup> C	Т	Т	None
Bending-Vertical (neutral axis)	0	0	0	0	None
Bending Vertical (off neutral axis)	с	С	С	C .	None

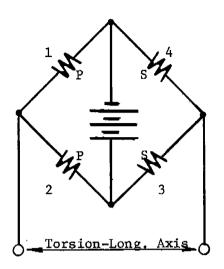
C = compression

T = tension

0 = none

Note 1: Values of T and C along horizontal rows are of equal magnitude.

Note 2: See Torsional Bridge arrangement on next page.



### C. DISCUSSION

- If gages are located on neutral axis, vertical bending stresses are zero.
- If gages are off neutral axis, vertical bending is present, but in phase. The two portside gages cancel one another as do the starboard side gages.
- In similar manner horizontal bending is self-canceling on each side.
- 4. Plating unfairness is thus not a factor with respect to bending, since gage connections will not measure bending. Hence, no requirement for gages on each side of plating.
- 5. Shear stresses due to yawing are not present in the sides.
- 6. Shear stresses due to pitching are out of phase in each side and thus additive; however, one side is subtractive from the other because of bridge hookup.
- 7. Shear stresses due to torsion around the longitudinal axis are additive on each side and from side to side giving an output four times that which could be obtained with one active gage.
- 8. The bridge is inherently temperature-compensated.

A-4

## D. CONCLUSION

The instrumentation described in paragraph B will best accomplish the stated aim of monitoring torsional shear stress independent of other stress influences.

#### APPENDIX B

#### TRANSDUCER SPECIFICATIONS

### 1. <u>Stress Gages</u>

BLH Electronics, Inc., Type FAB-28-S6

Longitudinal Gage

Resistance: 350.0 <u>+</u> 2.5 Ohms Gage Factor: 2.06 <u>+</u> 1%

Lateral Gage

Resistance:  $98.0 \pm 1.0$  Ohms Gage Factor:  $2.05 \pm 1\%$ Poisson Ratio:  $.28 \pm 1\%$ Stress Gage Factor:  $1.48 \pm 1\%$ 

## 2. <u>Torsion Gages</u>

BLH Electronics, Inc., FABD-25-12S6

Gage Factor: 2.02 <u>+</u> 1% Resistance: 120.0 + .2 Ohms

3. <u>Bow and Stern Accelerometers</u>

Setra Inc., Model 100

Range: <u>+</u> 5g Maximum Static Acceleration: <u>+</u> 100g Approximate Natural Frequency: 490 Hz Transverse Acceleration Response: <0.01g/g Excitation: 6 VDC at 20 ma Full Range Output: <u>+</u> 1.5 VDC Output Impedance: 400 Ohms

### 4. <u>Midships Accelerometers</u>

Statham Instruments, Inc., Model A3-2.5 - 350

Range:  $\pm$  2.5g Nominal Bridge Resistance: 350 Ohms Approximate Natural Frequency: 55 Hz Transverse Acceleration Response: 0.02g/g Excitation: 11 Volts DC or AC (RMS) Full-Scale Output:  $\pm$  20 mv Used with Statham Instruments Model CA9-56 Strain Gage Signal Amplifier with an output of  $\pm$  2.5 VDC.

### 5. <u>Midships Pitch-and-Roll Signals</u>

Humphrey Inc., Pendulum Transducers, Model CP17-0601-1

Range:  $\pm 45^{\circ} \pm 0.5^{\circ}$ Resistance: 2000 Ohms  $\pm 5\%$ Power Dissipation: 0.5 watt at  $130^{\circ}$ F Accuracy:  $\pm 1\%$  with straight line approximation Natural Frequency: 2 Hz

6. <u>Displacement Transducers</u>

Hewlett Packard, Model 7DCDT-050

Full-Scale Output: 1.5 VDC Range: <u>+</u> 0.050 inches Scale Factor: 30 V/in Maximum Nonlinearity: <u>+</u> 0.5% FS Excitation Voltage: 6 VDC Nominal Output Impedance: 2.2 K Ohms Frequency Response: 3 db down at 350 Hz

7. <u>Wave Data Acquisition System</u>

Eastech Limited, Windsor, Nova Scotia, Model 440

Used with Model 266 Wave Buoys. Data recorded as positive pulses approximately 3 milliseconds in duration, approximately 1.5 volts peak at 30 pulses per second at zero acceleration. APPENDIX C AMPEX FR-1300 INSTRUMENTATION RECORDER

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## Ampex FR-1300

## Instrumentation recorder

## PERFORMANCE SPECIFICATIONS

## General Description

The Ampex FR-1300 is a compact, lightweight portable recorder, available in 7 or 14-channel versions. It features an integral capstan servo system that assures speed accuracy under variable power conditions and provides electrical switching over a range of six speeds. For applications requiring precisely accurate speeds, or where it is desired to record and reproduce on different recorders under unpredictable voltage conditions, a control track generator/demodulator module can easily be added to the integral capstan servo system to provide a complete record/reproduce tape speed servo control system (Speedlock). Transport control circuitry is completely interlocked to prevent tape damage if the recorder is operated carelessly or accidentally. Interchangeability of electronics. Signal compatibility with earlier recorders using ES-100 electronics. Signal compatibility is also provided. A rack mounted version is available.

## Tape Transport

- Tape Speeds: 60, 30, 15, 7½, 3¾, 1⅓ ips standard. All six transport speeds are selected by a single front panel control. All speeds are synchronously controlled by a phase-locked servo system on capstan drive motor. Other fixed or variable speeds on special order.
- Capstan Speed Accuracy: ±0.05% maximum, long term, when üsing the internal crystal reference. Frequency standard is accurate to ±0.01%, long term.

#### Tape Speed Deviation: ±0.25%.

- Reels: The FR-1300 tape transport accommodates 10<sup>1</sup>/<sub>2</sub>-inch reels, Ampex Precision or NAB.
- Tape Specifications: Available in versions for  $\frac{1}{2}$  or 1-inch tape of 1 mit or  $\frac{1}{2}$  mil Polyester, or  $\frac{1}{2}$  mil Acetate. Stated performance guaranteed only when using recommended Ampex Instrumentation Tape.
- Controls: Illuminated pushbuttons for Record, Drive, Stop, Forward and Rewind. All functions may be remotely controlled. Control circuitry is completely interlocked so that recorder can be switched. from any mode to any other mode without damaging the tape.
- Fast Wind Time: For 101/2-inch reel, with 3600 feet of tape, approximately 3.0 minutes at 60 cycles per second (3.5 min. at 50 cps).
- Start Time: Time required from start command to meet flutter specifications is as follows:

Speed (ips)	Time
60	8 seconds
30	6 seconds
15 and lower speeds	4 seconds

Stop Time: Maximum of 1.5 seconds at 60 ips tape speed; shorter stop times with lower tape speeds.

Flutter: Maximum cumulative flutter (% peak-to-peak):

Tape Speed	Bandpass	Flutter	Bandpass	Flutter
(ips)	(cps)	(%)	(cps)	(%)
60	0.2 to 10,000	0.6	0.2 to 312	0.20
30	0.2 to 5,000	0.6	0.2 to 312	0.25
15	0.2 to 2,500	0.6	0.2 to 312	0.4
71/2	0.2 to 1,250	0.75	0.2 to 312	0.6
31/4	0.2 to 625	1.2	0.2 to 312	1.2
11/1	0.2 to 312	1.5	0.2 to 312	1.5

## Heads

- Gap Scatter: Trailing edges for record heads (or gap centers for reproduce heads) within a band 100 microinches wide (0.0001 inch).
- Gap Azimuth: All stacks within ±1 minute of arc perpendicular to head base plate.
- Track Dimensions: Track width is 0.050 inch; tape track spacing 0.070 center (IRIG Standard). Other heads on special order.
- Number of Tracks: 7 on 1/2 inch; 14 on 1 inch (IRIG Standard). Other heads on special order.

Interstack Spacing: 1.5 ±0.0005 inch, gap to gap.

## Direct Record/Reproduce System

Frequency Resp	onse:	S/N*	(db)
Tape Speed		Bandpass	
(ips)	Bandwidth	Filtered * *	Unfiltered
60	300 cps to 300 Kc $\pm$ 3 db	35	31
30	150 cps to 150 Kc $\pm$ 3 db	34	30
15	100 cps to 75 Kc ±3 db	32	27
71/2	50 cps to 38 Kc ± 3 db	30	22
33/4	50 cps to 19 Kc == 3 db	29	22
1%	50 cps to 10 Kc $\pm$ 3 db	28	22
,	* For an all Direct system only, h Direct S/N and crosstalk may be ** Measured at output of a bandow	affected.	• •

attenuation beyond limits stated.

#### RMS Signal-to-Noise Ratio: See table.

- Harmonic Distortion: Less than 1.2% total of a 1 Kc signal recorded at 60 ips.
- Input Level: 1.0 volt rms nominal (0 dbv) to produce normal recording level; operable from 0.2 to 10 volts rms by adjustment of input potentiometer.
- Input Impedance: Nominal 50 K ohms resistive, in parallel with 150 pF, unbalanced to ground.
- Output Level: 1.0 volt rms nominal (0 dbv), across a 600 ohms or greater impedance.

Output Impedance: Less than 50 ohms, unbalanced to ground.

## FM Record/Reproduce System

#### Frequency Response:

Tape Speed	Frequency Response (within 1.0 db)	S/N Ratio RMS	Harmonic
60 ips	0 to 20,000 cps	46 db	1.2%
30 ips	0 to 10,000 cps	46 db	1.2
15 ips	0 to 5,000 cps	45 db	1.2
71/2 ips	0 to 2,500 cps	45 db	1.2
3¾ ips	0 to 1,250 cps	42 db	1.5
17/ <sub>8</sub> ips	0 to 625 cps	40 db	1.8

RMS Signal-to-Noise Ratio (at center carrier): See table.

#### Harmonic Distortion: See table.

DC Drift: Less than  $\pm 0.5\%$  of full deviation over a four-hour period after warmup (10 minutes). Less than 2% in 8 hours with temperature variations between  $+40^{\circ}$ F and  $+125^{\circ}$ F.

continued

### FM Record/Reproduce System (con't)

- Record/Reproduce Voltage Linearity:  $\pm 0.75\%$  of full band, of a zero-based straight line.
- Input Level: Input of 1 volt rms (0 dbv) to produce ±40% deviation; operable from 0.5 to 25 volts rms by adjustment of input potentiometer.
- Input Impedance: Nominal 20,000 ohms resistive, in parallel with 150 pF, unbalanced to ground.
- Output Level: 1.0 volt rms (nominal) into 10 K ohms or greater load impedance.

Output Impedance: 600 ohms, unbalanced to ground.

# PDM Record/Reproduce System (IRIG Compatible)

#### System Pulse Characteristics:

Tape Speed		Duration oseconds	Pulse Accuracy in Microseconds
(ips)	Min.	Max.	Over Specified Pulse Widths
60	20	10,000	$\pm 2.0$ (30 to 900 $\mu$ sec duration)
30	30	10,000	$\pm 2.0$ (45 to 900 µsec duration)
15	60	10,000	$\pm 3.0$ (60 to 2,000 µsec duration)
71/5	120	10,000	$\pm 10.0$ (120 to 3.000 usec duration)

Input Level: 1 volt peak-to-peak rectangular wave 20 microseconds to 10,000 microseconds pulse duration, operable from 0.75 to 20 volts peak-to-peak.

- Input Impedance: 20,000 ohms nominal paralleled by 150 pF maximum, unbalanced to ground.
- Output Level: 20 to 24 voits peak-to-peak across 1000 ohms and 0.001 mfd.

Output Impedance: Less than 100 ohms, unbalanced to ground.

Output Rise and Fall Time: 2 microseconds maximum (from 10% to 90% amplitude level).

## Servo Tape Speed Control System (Speedlock)

### Frequency Standard Accuracy: ±0.01%, long term.

Speed Correction Range: ±2% of nominal.

METRIC CONVERSION TABLES

Servo Tape Speed Control System (con't)

### Time Displacement Error:

Tape Speed	Error
60 ips	100 microseconds
30 ips	150 microseconds
15 ips	200 microseconds

Synchronization Time: After 10-minute warmup.

Tape Speed	Time
60 ips	8 seconds
30 ips	6 seconds
15 ips	4 seconds

### Power Requirements

- Voltage: 105 to 125 volts, single phase, 48 to 62 cps AC (with Frequency Standard).
- Power Consumption: Less than 325 watts steady state for a 14-track record/reproduce system. Starting surges up to 400 watts may be encountered.

## Environment

Temperature: Operating: 5°C to 52°C (40°F to 125°F) Storage/non-operating: -30°C to 56°C (-20° to 150°F)

Altitude: Operating: 15,000 feet (4600 m). Non-operating: 50,000 feet (15,000 m).

Relative Humidity: 5 to 95%, non-condensing, both operating and nonoperating.

Vibration: Normal handling and transportation only.

### Physical Characteristics

Size: Portable case 24 inches (61 cm) high, by 18 inches (46 cm) wide, by 12<sup>1</sup>/<sub>2</sub> inches (31 cm) deep, for complete 14-track record/reproduce system and capstan servo.

Vertical Rack Space Required: Rack mounted version: Transport 241/2 inches (62.2 cm), electronics tray 51/4 inches. Each electronics tray accommodates up to 14 record or reproduce modules, plus 3 auxiliary modules.

Weight: Portable version: Approximately 110 lbs. (50 kg) for 7-track system.

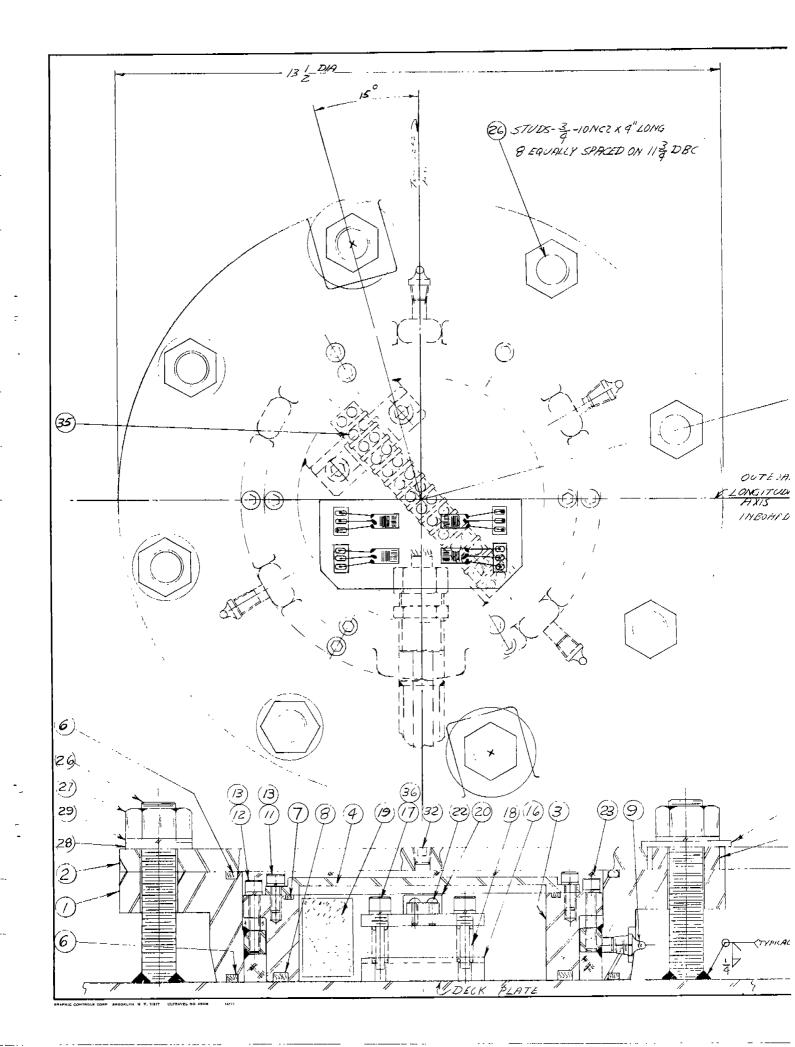
TAPE SPEEDS						TAPE DIMENSIONS (C	ontinued)			
ips	1% 3% 4.76 9.52	7½ 19.05 3	15 30 8.1 76.2	60 152.4	120 304.8	Length: feet 600 meters 185	1200 1800 366 549	2500 36 762 10		
TAPE DIMENSIC	NS					HEAD DIMENSIONS				
Reels: inches	14	101/5	7 53/4	5		Gap Scatter	Interstack Span	ting"	Track Width & S	pacing*
cm	35.56	26.67 17	7.78 14.62	2 12.70		microinches 100	inches 1.5		inches 0.05	
Widths: inches cm	14	· 1/2	<sup>3</sup> / <sub>4</sub> 1	2		mm 0.00254	стя 3.81 <u> —</u>			/ 1.772 (IRiG)
<b>L</b> III	0.03	5 1.27 1	.903 X.34	9.06		STANDARD PANELS F	OR 19-INCH (4	8.26 cm) R	ACK	
Base Thicknesses: i	nehes	1 mil	l.5 π	11		in. 13/4 33/5 51/4 cm 4.45 8.89 13.34 1	7 93/ 191/	14 153	· 171/ 101/ ·	01 DE

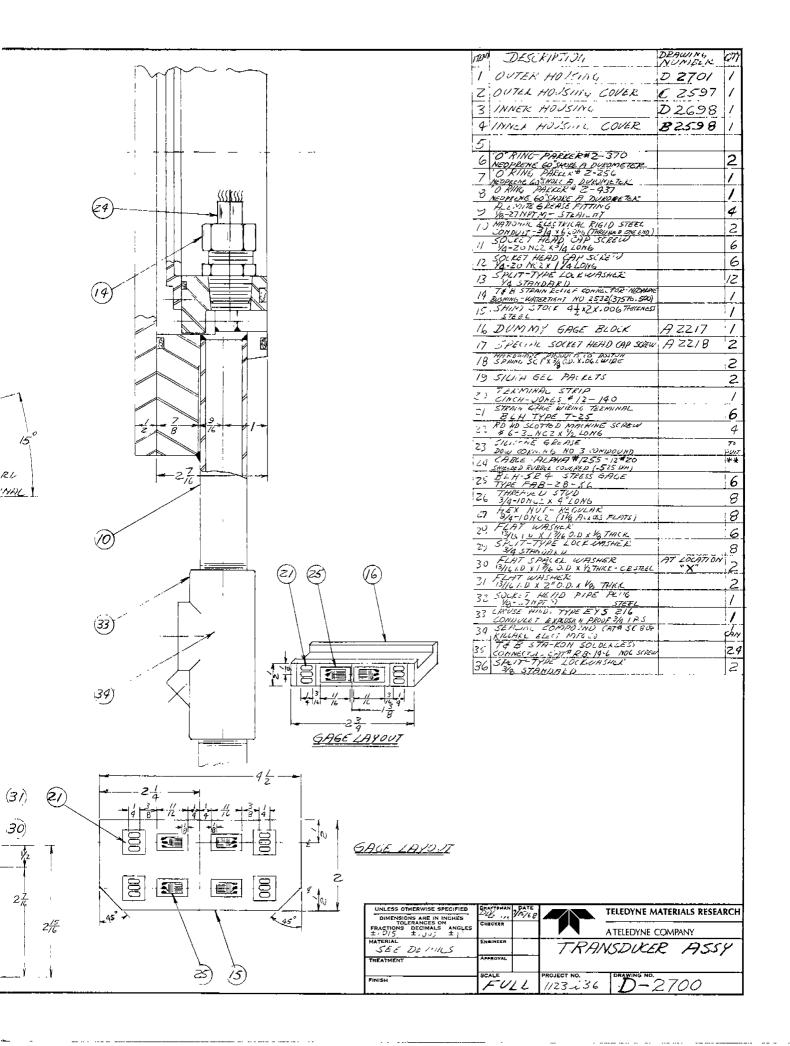
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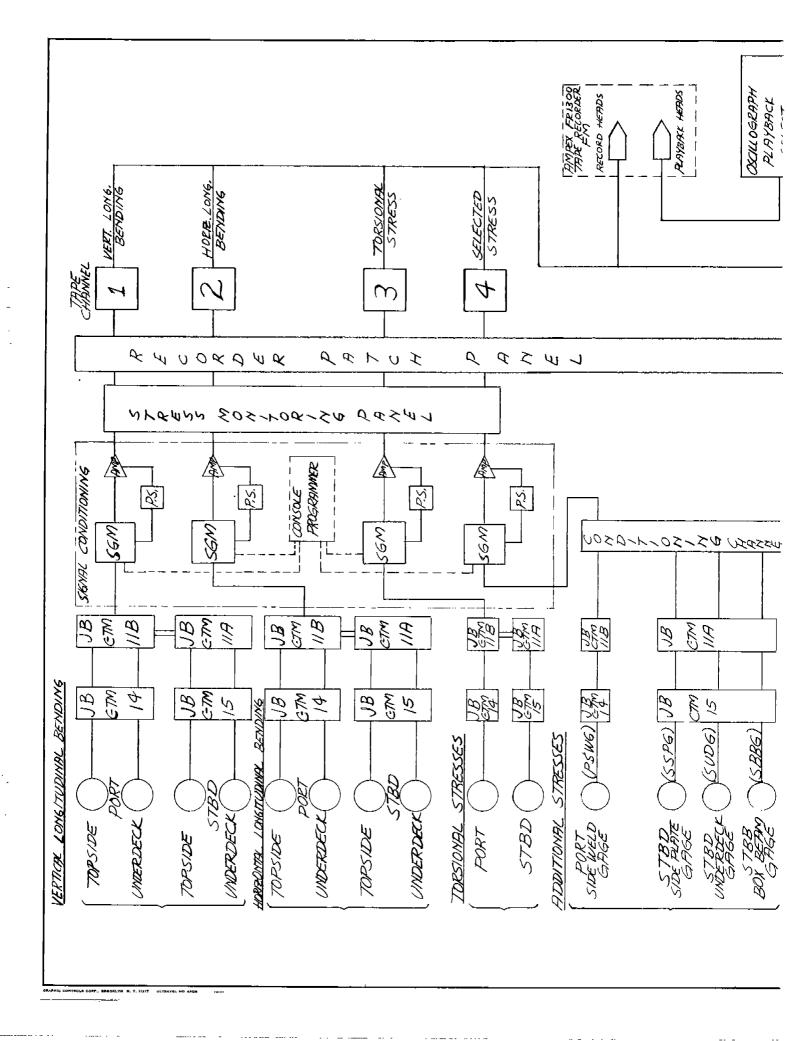
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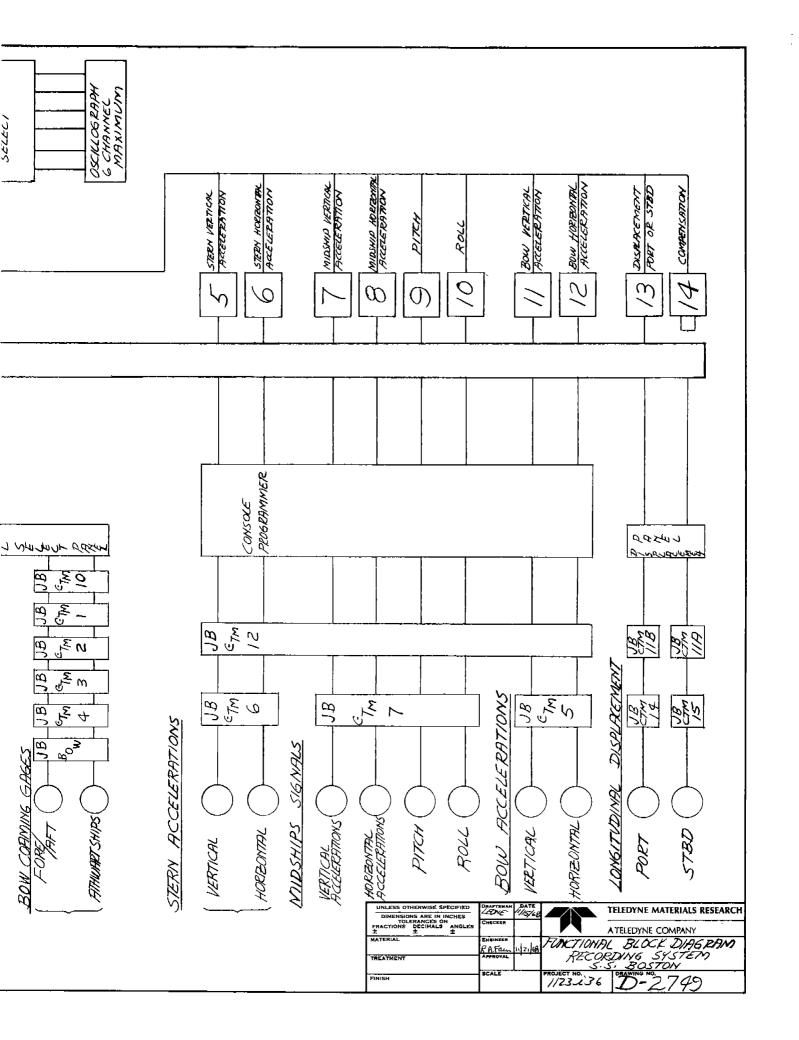
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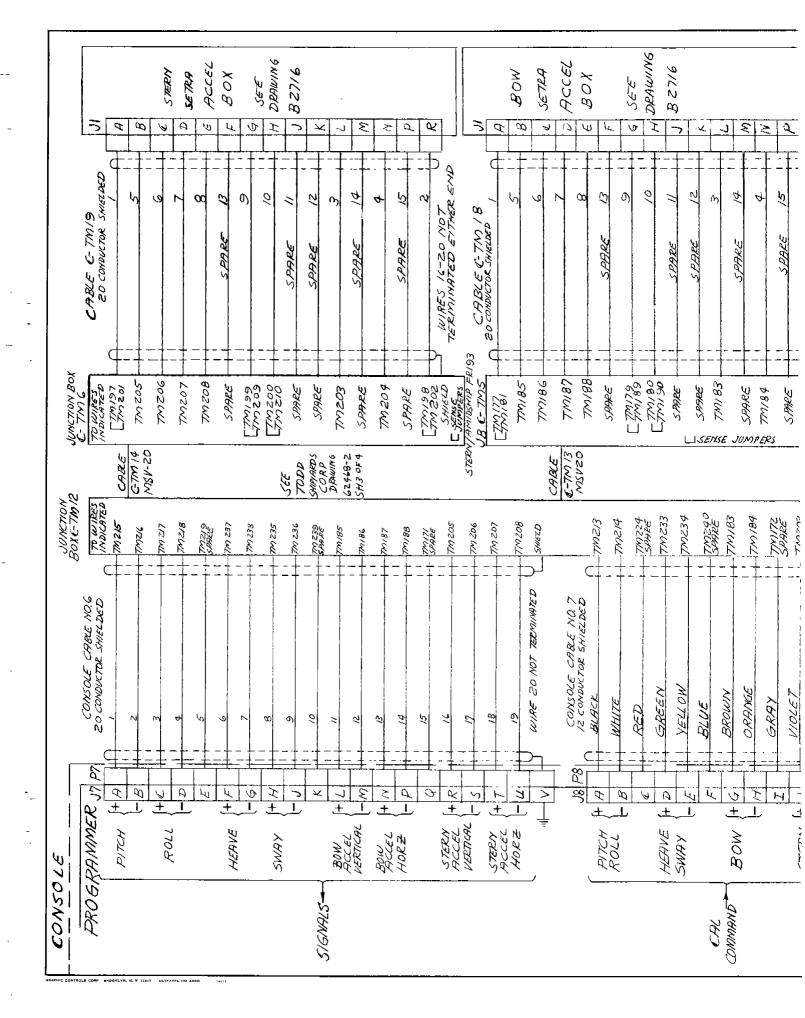
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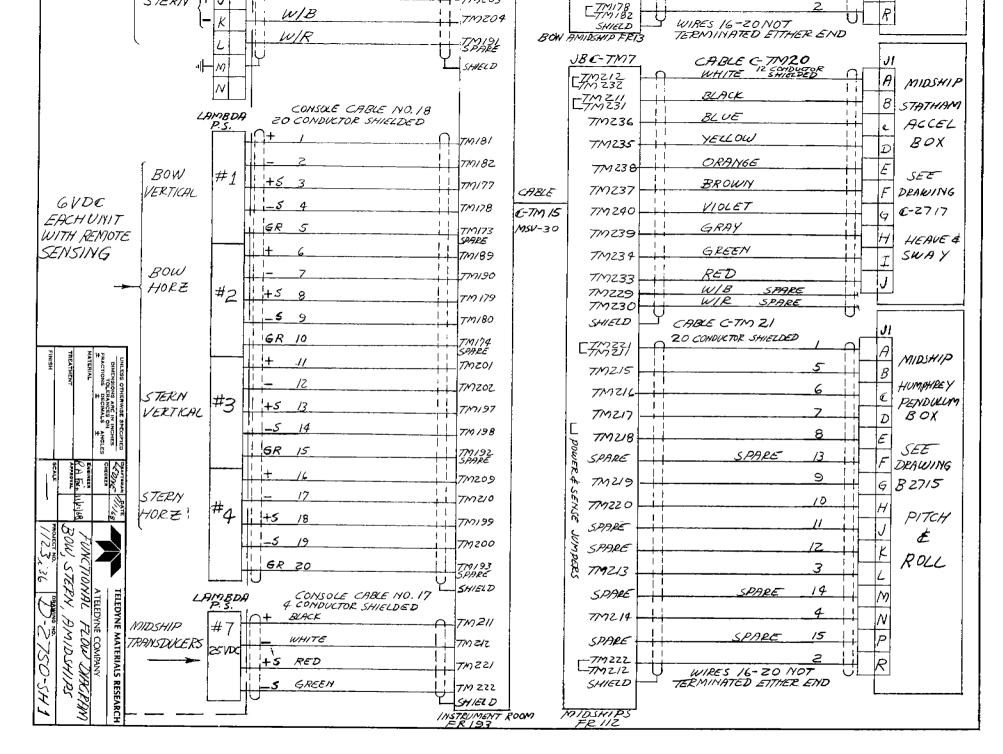






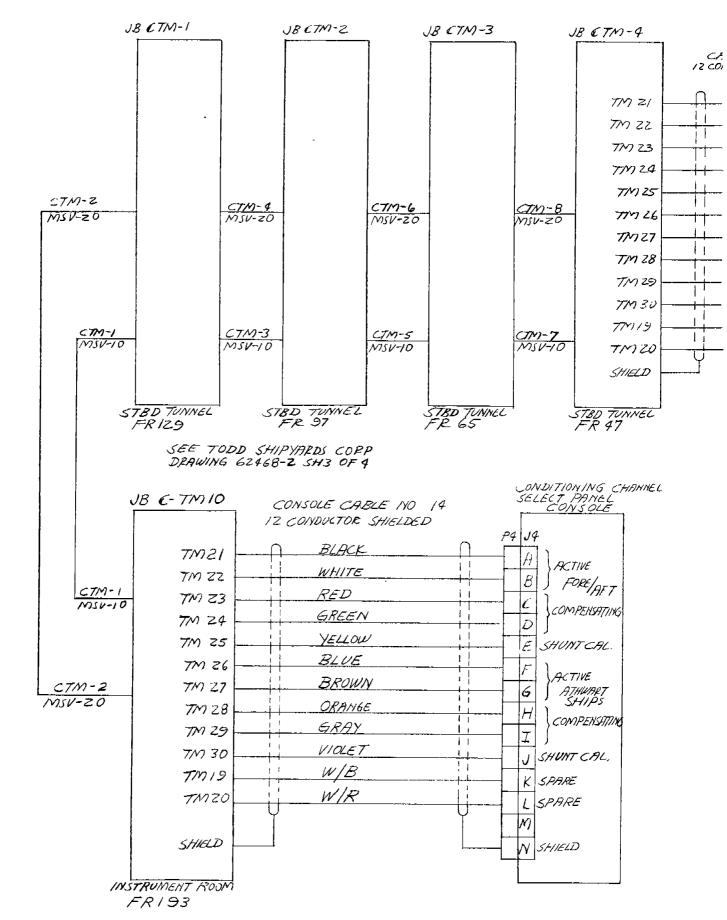




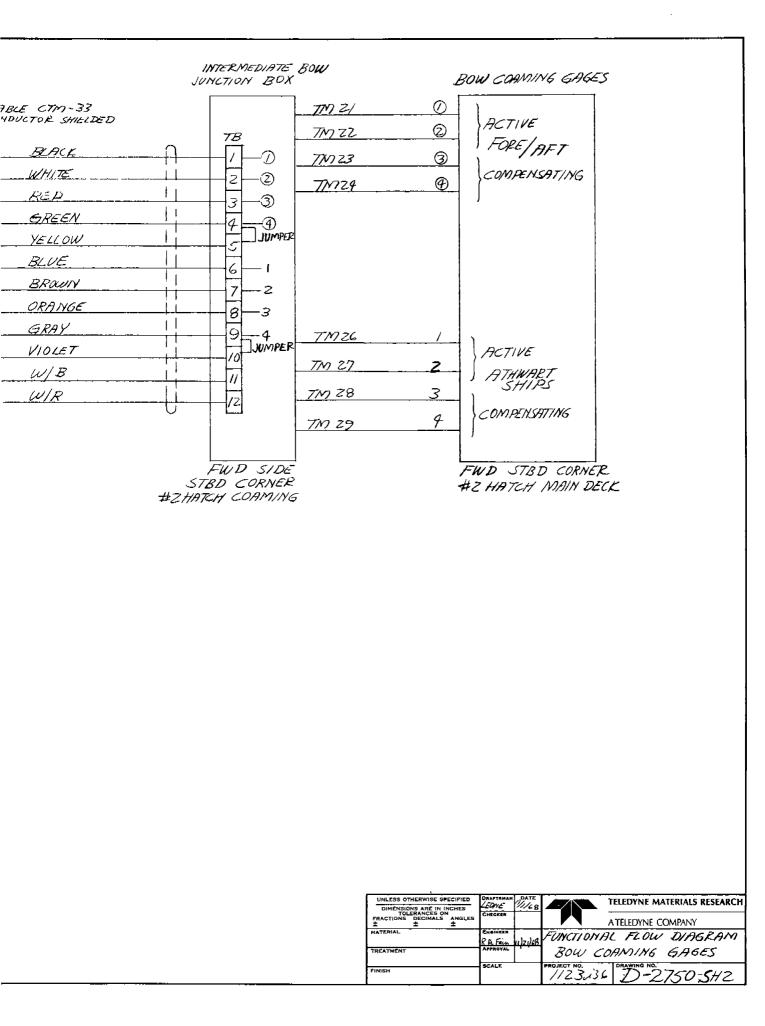


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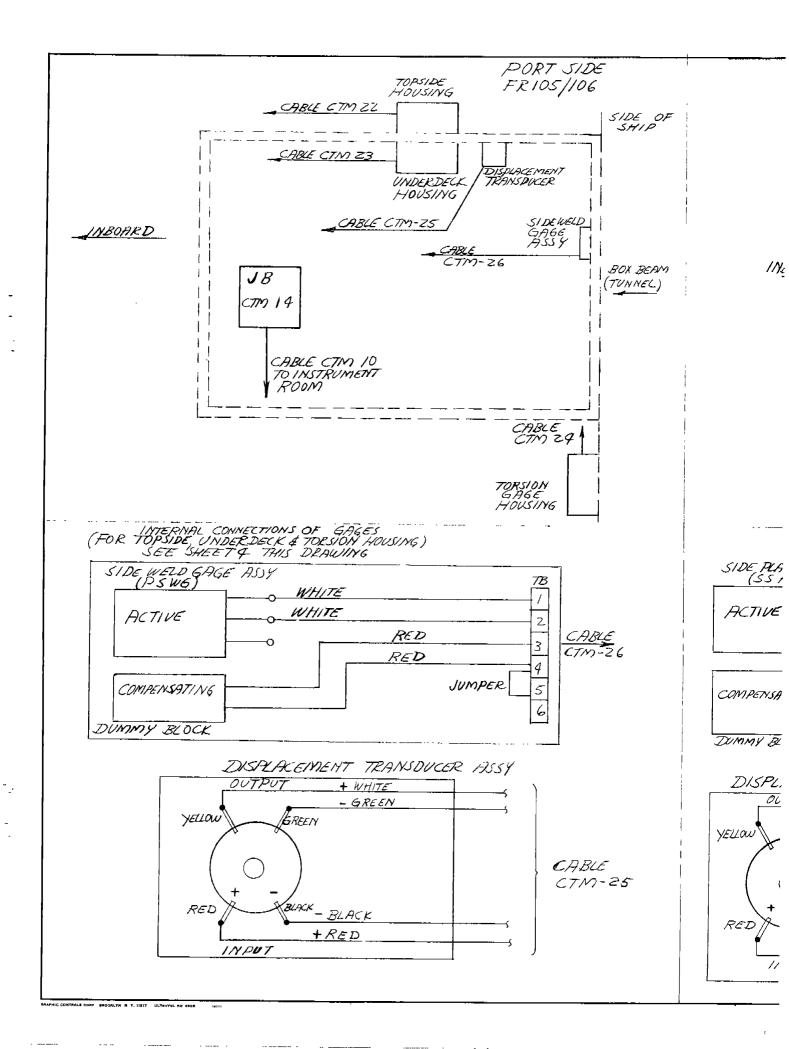


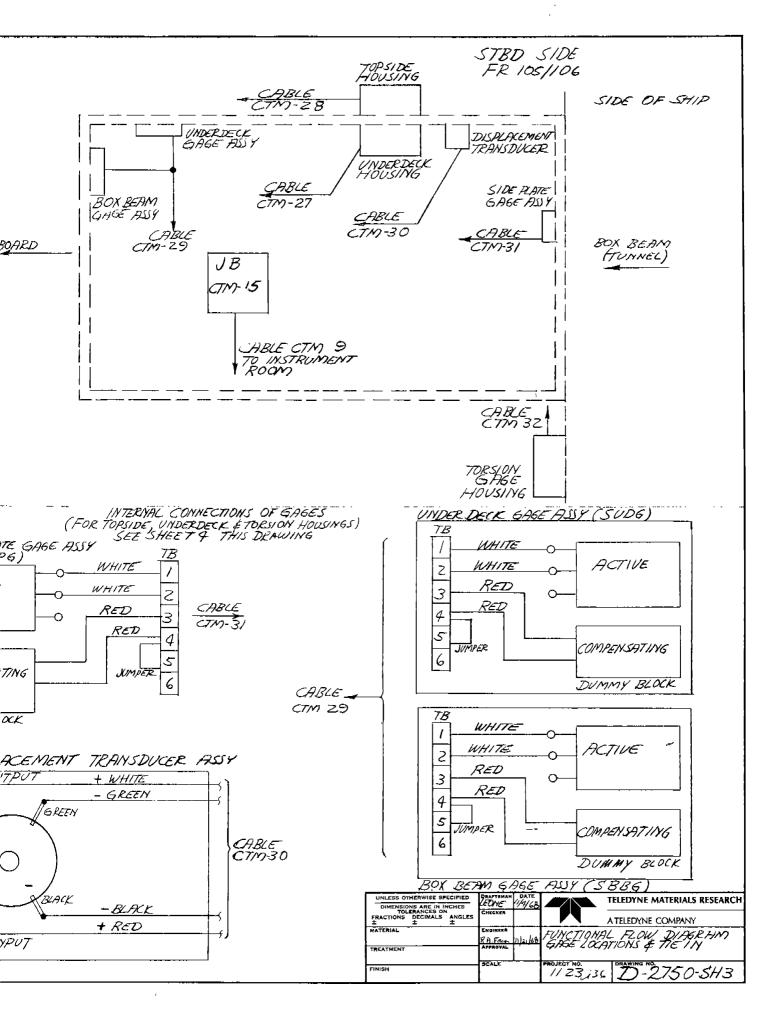
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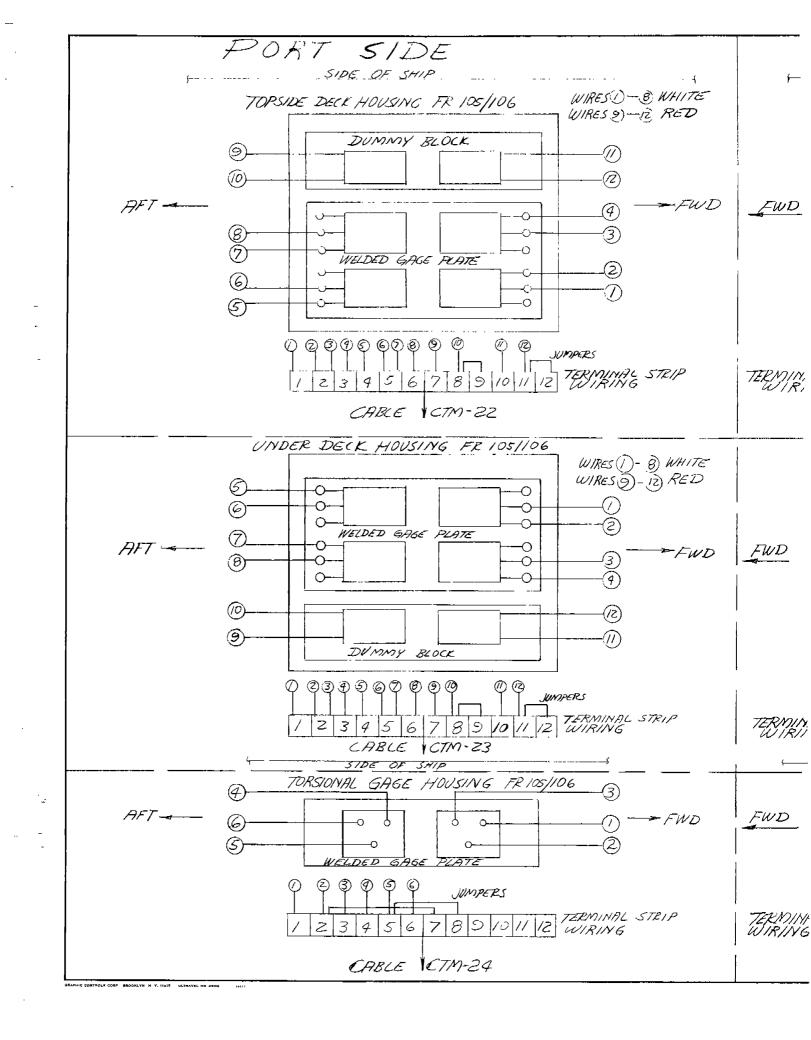


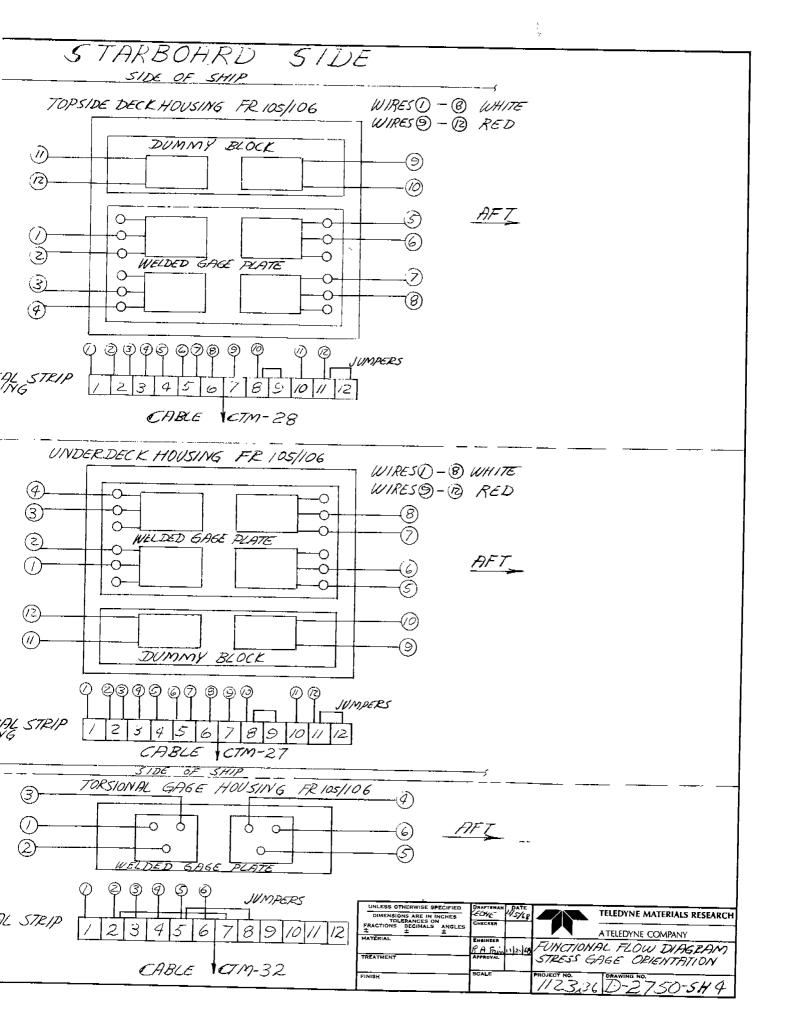
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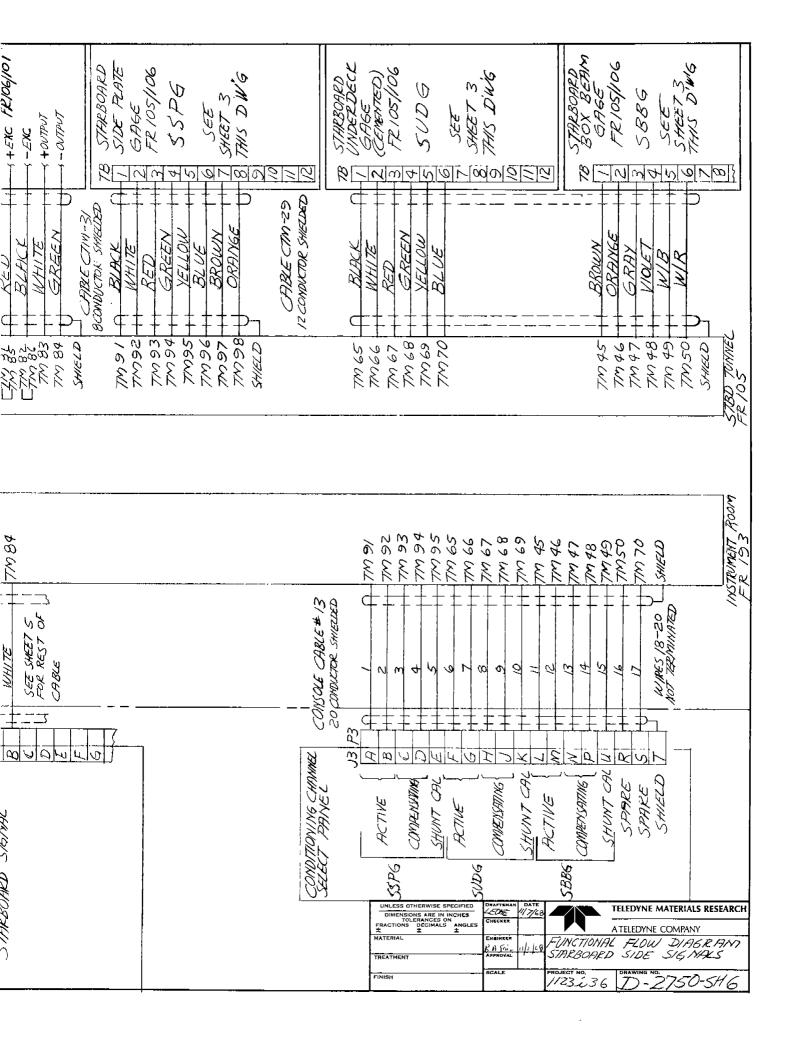
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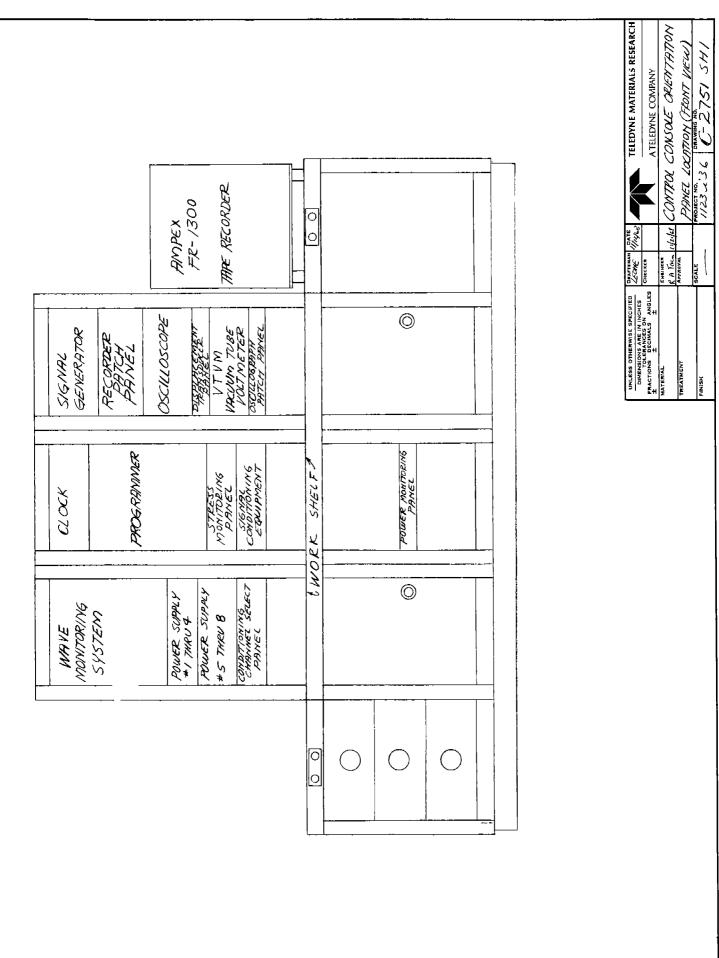
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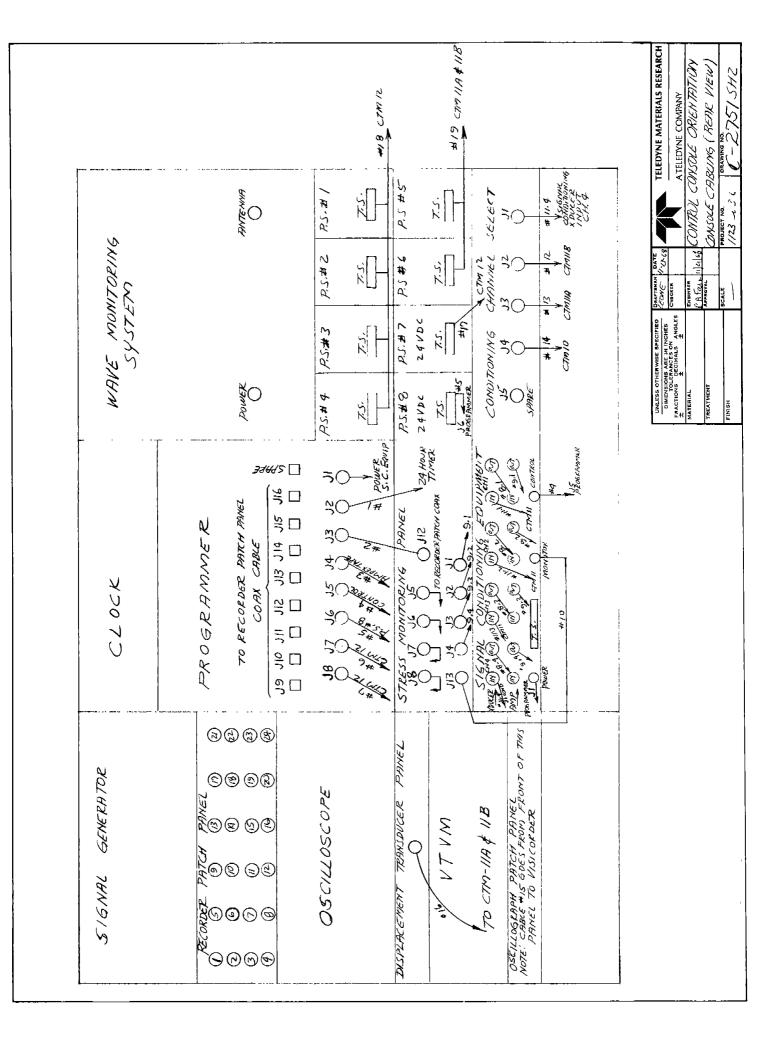
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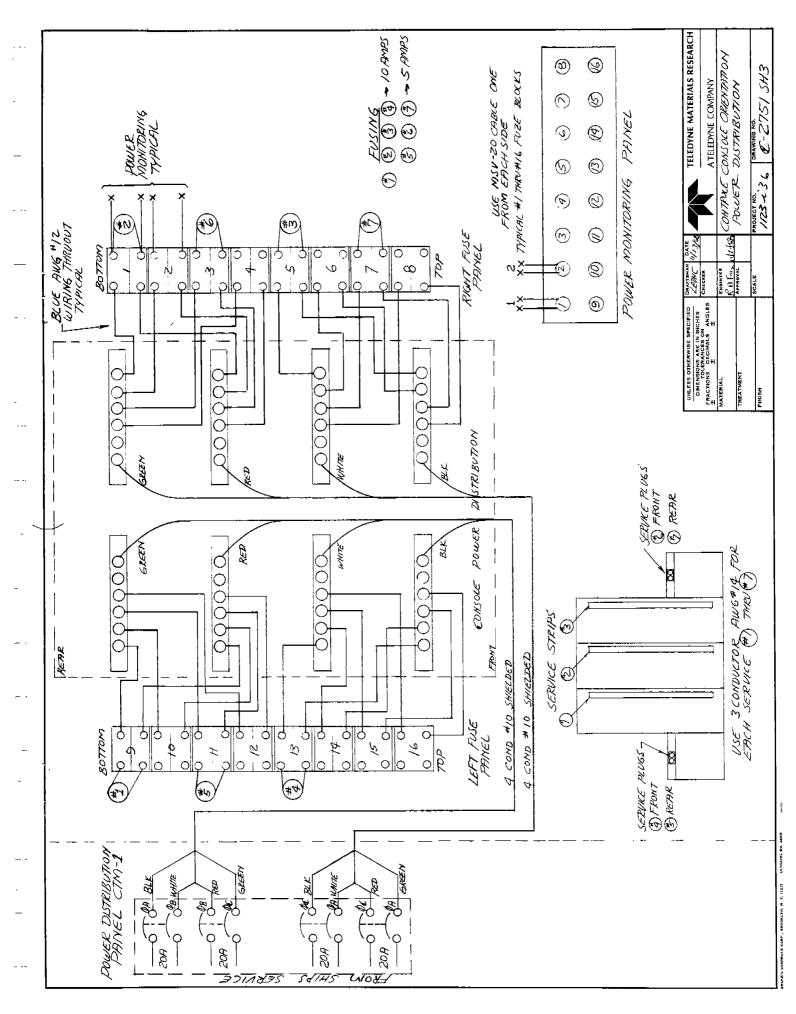


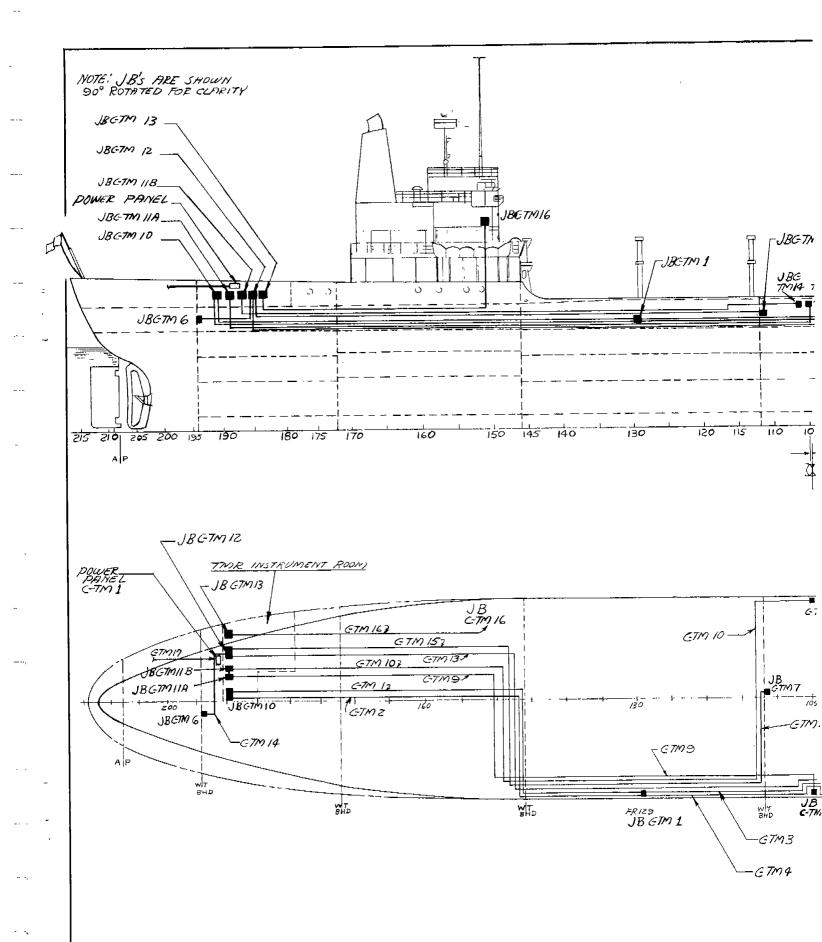
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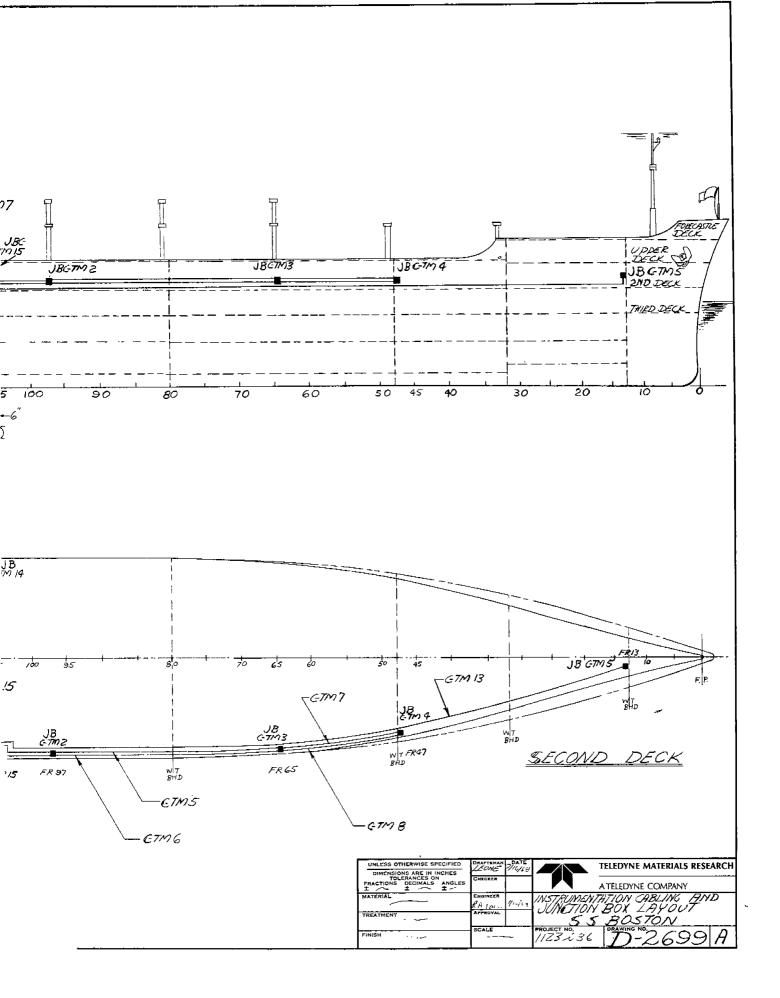


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