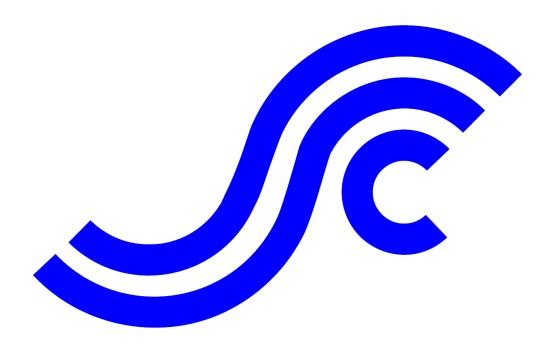
SSC-474

STRUCTURAL ASSESSMENT OF AGED SHIPS

By G. Walker, B. Connell, and S. Kery



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STRUCTURAL ASSESSMENT OF AGED SHIPS

The drive to improve efficiency and load carrying capability has led to highly optimized ship structures often utilizing thinner and higher strength materials to minimize ship weight. This has resulted in increased inspection and maintenance requirements to ensure structural integrity throughout the life of the vessel. At the same time, there is increased pressure to reduce vessel downtime and maintenance costs, all contributing to increasing the risk of structural failure.

This report describes the development of an assessment process to predict the survivability of a corrosion-degraded ship in specific wave conditions. The method developed utilizes a ship specific 3-D hydrodynamic model to simulate the ship's rigid body dynamic response to wave conditions, measuring the resulting ship motions and pressure distribution on the hull. Pressure and acceleration data from the hydrodynamic model is then input into a 3-D finite element model of the degraded ship structure where the resulting stresses in stiffeners and plating are assessed against various failure modes, including buckling modes, which are calculated according to IACS Common Structural Rules. The results form the basis of a degraded ship strength assessment, which can be provided to a ship owner and operator to make operational and repair decisions.

We thank the authors and Project Technical Committee for their dedication and research toward completing the objectives and tasks detailed throughout this paper and continuing the Ship Structure Committee's mission to enhance the safety of life at sea.

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16. Abstract

This report describes the development of an assessment process to accurately predict the survivability of a corrosion-degraded ship in specific wave conditions. The method developed utilizes a ship specific 3-D hydrodynamic model to simulate the ship's rigid body dynamic response to wave conditions, measuring the resulting ship motions and pressure distribution on the hull. Pressure and acceleration data from the hydrodynamic model is then input into a 3-D finite element model of the degraded ship structure where the resulting stresses in stiffeners and plating are assessed against various failure modes, including buckling modes, which are calculated according to IACS Common Structural Rules. The results form the basis of a degraded ship strength assessment which can be provided to a ship owner and operator to make operational and repair decisions.

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Conversion Factors

(Approximate conversions to metric measures)

To convert from	to	Function	Value
LENGTH			
inches	meters	divide	39.3701
inches	millimeters	multiply by	25.4000
feet	meters	divide by	3.2808
VOLUME			
cubic feet	cubic meters	divide by	35.3149
cubic inches	cubic meters	divide by	61,024
SECTION MODULUS			
inches ² feet	centimeters ² meters	multiply by	1.9665
inches ² feet	centimeters ³	multiply by	196.6448
inches ³	centimeters ³	multiply by	16.3871
MOMENT OF INERTIA			
inches ² feet ²	centimeters ² meters ²	divide by	1.6684
inches ² feet ²	centimeters4	multiply by	5993.73
inches ⁴	centimeters ⁴	multiply by	41.623
FORCE OR MASS			
long tons	tonne	multiply by	1.0160
long tons	kilograms	multiply by	1016.047
pounds	tonnes	divide by	2204.62
pounds	kilograms	divide by	2.2046
pounds	Newtons	multiply by	4.4482
PRESSURE OR STRESS			
pounds/inch ²	Newtons/meter ² (Pascals)	multiply by	6894.757
kilo pounds/inch ²	mega Newtons/meter ²	multiply by	6.8947
	(mega Pascals)		
BENDING OR TORQUE			
foot tons	meter tons	divide by	3.2291
foot pounds	kilogram meters	divide by	7.23285
foot pounds	Newton meters	multiply by	1.35582
ENERGY			
foot pounds	Joules	multiply by	1.355826
STRESS INTENSITY			
kilo pound/inch² inch½(ksi√in) J-INTEGRAL	mega Newton MNm ^{3/2}	multiply by	1.0998
kilo pound/inch	Joules/mm ²	multiply by	0.1753
kilo pound/inch	kilo Joules/m ²	multiply by	175.3
1		1 / /	

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1 INTRODUCTION

1.1 Purpose

The purpose of this project is to develop an assessment process to accurately predict the survivability of a corrosion-degraded ship in specific wave conditions. The process could then be employed to assess degraded ship structures against specific sea conditions, thereby providing the ship owner and crew with more detailed information on which to make operational and repair decisions. This ultimately allows them to understand the risk of, and help minimize the probability of structural failure when operational requirements, budgets or schedule do not permit the full remediation of the degradation. It may also be useful when assessing when a specific hull needs to be removed from service and scrapped.

1.2 Background

The drive to improve efficiency and load carrying capability has led to highly optimized ship structures often utilizing thinner and higher strength materials to minimize light ship weight. This has resulted in increased inspection and maintenance requirements to ensure structural integrity throughout the life of the vessel. At the same time there is increased pressure to reduce vessel downtime and maintenance costs, all contributing to increasing the risk of structural failure.

Previous attempts to model strength-degraded ship structures have used dimensional and form factors to model the ship, which is subjected to various headings and sea states to estimate vertical, lateral, and torsional moments. The output is derived using numerical techniques and empirical data. These outputs are then input into various reliability models of the component failure modes which are analyzed in series to predict the probability of failure occurring. Ship management can then use this probability to decide whether to subject the vessel to a specific wave condition.

In contrast, the method developed and applied herein utilizes detailed 3-D models that are specific to one ship, thus allowing a more refined engineering analysis to support decisions on whether to limit the wave environments that the ship is allowed to encounter. The developed process utilizes a ship-specific 3-D hydrodynamic model to simulate the ship's rigid-body dynamic response to an array of wave conditions, and measures the resulting ship motions and hydrodynamic pressure distribution on the hull, in the time domain. Pressure and acceleration data from the hydrodynamic model are then input into a detailed 3-D finite element model (FEM) of the degraded ship structure. The resulting stresses in hull beams and plating are assessed against various failure modes, including buckling modes, which are calculated according to the IACS Common Structural Rules (Ref. 4).

1.3 Scope

The overall objective of the project is to develop a process for evaluating degraded ship structure under various seaway conditions. To meet this objective within the available time and funding constraints, simplifying approaches and assumptions were used. The key ones are listed below.

- 1) While the entire hull and deckhouse structure was included in the structural finite element model, only the ship's mid-body region was evaluated for structural failure. This was considered acceptable because this is the region where maximum wave-induced hull girder bending occurs.
- Green sea loads and bottom slamming were not addressed, because these are hard to quantify and model, and tend to occur far from the midships region where longitudinal hull girder stresses are highest.
- 3) Hydrostatic and sloshing pressures from liquids inside tanks were not modeled. The internal liquid pressure acting on the tank walls that also form the hull surface tend to cancel the external hydrostatic and hydrodynamic (wave) loading. Thus it is generally conservative to assume no internal pressure here. And since the interior tank bulkheads are often loaded by internal fluids on both sides, in which case the pressures largely cancel each other, fluid loads on interior bulkheads were neglected. This is also justified because the focus of this analysis is hull girder integrity, so bulkhead integrity was a secondary consideration.
- 4) To minimize the number of load cases, only seaway loads associated with bow/head seas in long crested waves were modeled. Luckily, ships tend to take this heading to the waves in a storm. Similarly, only one wave modal period was analyzed for each significant wave height. Modal periods that produce wavelengths close to the ship's length tend to be more critical.
- 5) This analysis utilized measured pressures and accelerations resulting from only 20-minute hydrodynamic runs, whereas longer and/or more runs are required to produce statistically significant maxima, and generate meaningful statistics on probability of exceedance for a given exposure time.
- 6) Corrosion is applied as a uniform percent reduction in plating and stiffener (web and flange) thicknesses throughout the entire ship. This doesn't reflect reality in terms of corrosion distribution but is conservative and vastly simplifies the analysis.
- 7) Service life (fatigue life) is not addressed in this project. Several years ago, there was an extensive structural evaluation performed on a variety of in-service U.S. Navy ships, as part of a joint NAVSEA-ABS project which included remaining fatigue life estimation. While fatigue life is affected by widespread corrosion, it was not shown to be as predominant an issue as loss of local hull strength which has an immediate impact on seaworthiness.

2 SHIP SELECTION

Several different hull forms were considered based upon the availability of seakeeping and structural model data.

The US Coast Guard's 378 Hamilton Class Cutter was initially proposed because it has documented in-service hull and corrosion evaluations available. However, no usable FEM or useful seakeeping model files were located. The Expeditionary Sea Base (ESB), a U.S. Navy Auxiliary ship, was chosen because of the availability of both FEA and seakeeping models along with several other advantages listed below:

- Commercial/Navy Hybrid
- Structure Designed to ABS SVR
- ABS Classed

General particulars of the ESB are shown in Table 2-1.

Length Overall	785.2	feet	239.3	meters
Length between Perpendiculars	765.1	feet	233.2	meters
Max Beam	164.0	feet	50.0	meters
Depth to Main Deck	50.7	feet	15.5	meters
Minimum Draft	31.2	feet	9.5	meters
Voyage Draft	34.3	feet	10.5	meters
Maximum Draft	39.4	feet	12.0	meters

Table 2-1: General Particulars for ESB Vessel

3 MODELS

3.1 Hydrodynamic Model

The numerical hydrodynamic modeling and analysis tool chosen for the project is the non-linear Rankine panel code initially developed at MIT by Dr. David Kring, and currently licensed to DNV-GL as the solver in their WASIM software. The particular versions of WASIM and its user interface (Hydro-D) used for this analysis were V5.1-03 and V4.5-08 respectively. As with the creation of any hydrodynamics model the process starts with input of the "offsets", i.e. X/Y coordinates, of points on a series of section cuts spanning the length of the hull form. Other similar codes such as Fredyn, Aegir or LAMPS could have been used but each different program and in many cases each version, uses a somewhat different custom input format. In the case of this study, the WASIM-compatible input files for the ESB hull form had already been developed. This was in the form of a text file that was loaded into WASIM and Hydro-D.

The WASIM software simulates three dimensional wave loading on the ship, computing both global responses and local loading on any displacement hull moving at forward speed. Data output includes:

- Ship Motions Summary
- Ship Accelerations Summary
- Shear Force and Bending Moment Statistics
- Hydrodynamic pressure distribution on the hull
- Plottable maximum and minimum shear forces and bending moments
- Extreme hogging and sagging values in the time series and 6 DOF accelerations at those time steps

The pressure distribution across the hull and acceleration at the ship's center of gravity from each wave selected are used as inputs to the FEA model of the degraded ship. The time step selected for each wave is that which maximizes the bending moment near midships. While midships is about 120m forward of the Aft Perpendicular (AP), as shown in Figure 3-1, the maximum occurred a little further forward of this, and this is the maximum that was used. Note that the absolute values of the bending moments are shown in this figure.

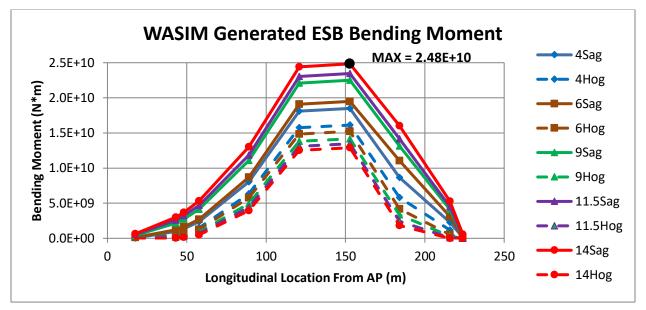


Figure 3-1: WASIM-Generated Bending Moment

The legend on the right hand side of the chart contains the significant wave height in meters followed by the type of bending moment on the hull (hogging or sagging). Thus: 4SAG is a 4 meter significant wave height that puts the ship in the sagging condition.

3.1.1 Hydrodynamic Pressure Distribution

The WASIM software allows the output of pressure distribution from the sea on the hull exterior but has restrictions on the number of panels that can be selected for pressure reporting. Either all panels must be selected, or the user may select up to 100 panels, with the latter decreasing output

file size and computing time. Instead of running the simulations with all panels selected, three different groups of 100 panels each, corresponding to the fore-hull, mid-hull, and aft-hull of the ship were chosen and the remaining panel pressures were interpolated after importing into the FEA model. Each simulation configuration is run three times where the only difference is which panel set was turned on. To ensure identical ship motions and pressure distributions were produced between the runs, the same wave component phase seed (start time) was used for each set of three runs. Statistical properties of the ship motions, i.e. displacements, velocities, and accelerations, and of the waves themselves, for one set of three runs were compared. The differences between them were zero out to at least 4 decimal places, therefore the waves and motions were considered statistically identical for all three runs in the set.

Figure 3-2 and Figure 3-3 below show the panels selected for pressure reporting (highlighted in red). Some are above the still waterline, but most are below, where the highest pressures occur.

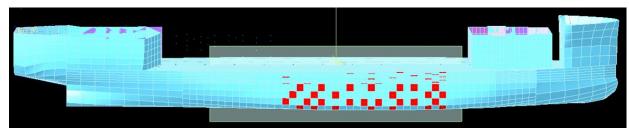
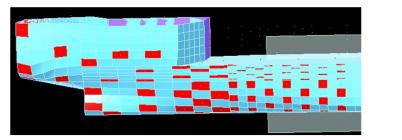


Figure 3-2: Mid-Hull 100 Panels (in Red) Where Pressure is Measured (WASIM Screengrab)



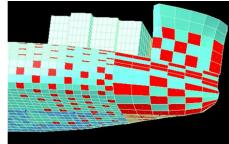


Figure 3-3: Aft-Hull and Fore-Hull 100 Panels (in Red) Where Pressure is Measured

3.1.2 Hydrodynamic Simulation Cases

Five different hydrodynamic simulation cases were analyzed, where the significant wave height and an associated wave modal period were varied between all cases, and the ship speed differs for some of these cases. The simulation cases were limited to head seas in long-crested waves to keep the number of inputs to the FEA model manageable.

The hydrodynamic simulations were also limited to a single draft condition. The AMCM Mission Loaded Departure condition was selected because it includes minimal sea water ballast in the tanks near midships, maximizing the hogging stresses, which are the most critical for the ESB, because the structural, machinery and outfitting weights are concentrated near the ends of the ship.

The run matrix of the modeled simulation cases is shown in Table 3–1.

Ship	Speed	H1/3	Tm	Wave Heading		Crested	Draft	Trim	Duration	Run	Run	Run
knots	m/s	m	seconds	Degrees	words		m		seconds	Bow	mid	aft
										100 pts	100 pts	100 pts
16	8.23	4	9.7	180	Head Seas	Long	9.5	Level	1200			
9	4.63	6	12.4	180	Head Seas	Long	9.5	Level	1200			
5	2.57	9	15	180	Head Seas	Long	9.5	Level	1200			
5	2.57	11.5	15.7	180	Head Seas	Long	9.5	Level	1200			
5	2.57	14	16.4	180	Head Seas	Long	9.5	Level	1200			

Table 3–1: Hydrodynamic Analysis Run Matrix

The significant wave heights used in the investigation range from the top of sea state 5 to the top of sea state 8. The Bretschneider wave spectrum was used with the modal period for each significant wave height corresponding to the most probable. The duration of each run was kept low (20 minutes) to save analysis time because hydrodynamic simulation accuracy and statistical significance was not the goal but rather the modeling method development.

For a full analysis the run durations would be longer and/or more numerous to make sure the outputs are statistically significant. Also, the output values would be adjusted using, for example, Ochi's Method described in Reference 1, based on the projected duration in the given sea condition, and the acceptable probability of exceedance.

Table 3–2 shows that the 6m wave case (in green) with a 12.4 second modal period has almost the same wavelength as the ship length, which is the classical design case used to check the longitudinal strength of a ship balanced atop a wave crest at midships, maximizing hogging, or supported near its ends by two wave crests, maximizing sagging. Shorter and longer period waves tend to be less critical for longitudinal strength. This becomes relevant when trying to understand why 'smaller' waves sometimes produce higher stresses in the structural analyses covered later in this report.

Ship LOA 239.3 meters Ship LBP 233.2 meters $H_{1/3}$ Tm Lambda seconds meters meters 9.7 146.9 12.4 240.0 6 9 15 351.2 11.5 15.7 384.7 419.8 14 16.4

Table 3–2: Comparison of Wavelength to Ship Length

A discussion of the range of conditions to model for a more complete analysis is included as Appendix A.

3.1.3 Hydrodynamic Data Output

The WASIM software allows for user-defined cut planes at which the program then calculates the 3-axis shear force and 3-axis bending moment time series. A cut plane was included near midships.

The maximum bending moments at the midship section over the course of the evaluated time series, for both hog and sag conditions, were identified. The pressure distribution at the associated time step was extracted for import to the FEA model. The 6DOF accelerations at the CG at this time step were also extracted for application to the FEA model. It is notable that the accelerations at the time of maximum hogging or sagging are not the maximum accelerations that occur throughout the whole time series.

3.2 Structural Model

3.2.1 FEMAP Model Grouping

The structural FEM used for the project began with a FEMAP v11.0.0 model of the ESB ship structure developed by NASSCO as a Detailed Design and Construction phase deliverable to the Navy. This model required substantial re-formatting to enable the analysis defined herein. For instance, the material and property cards required consolidation, and the element directionality and orientation were made common as required.

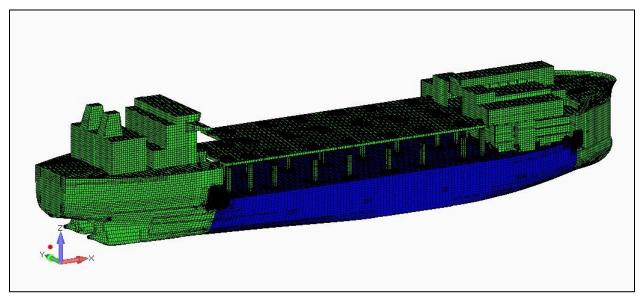


Figure 3-4: ESB Finite Element Model (Midbody analysis region in **BLUE**)

The final model consists of 335,159 plate and 170,857 beam elements. The main structural components such as the shell, main deck, inner-bottom, longitudinal and transverse bulkheads, and the deck framing were all formed into separate groups within FEMAP.

These groups were further divided into the five (5) major sections of the midbody of the ESB vessel with each section break at a main transverse bulkhead. (See Figure 3-5 and Figure 3-6) These sections are numbered from aft (1) to forward (5).

The node spacing is approximately 1.3m, which provides a good balance between results fidelity and analysis manageability. At least one plate element exists between longitudinal stiffeners, with a minimum of three (3) elements between primary supporting members.

The ship is not constrained to ground with any pinned or fixed connections. Rather, inertial relief is employed which acts equal and opposite to the net pressure load which otherwise would lift the ship vertically.

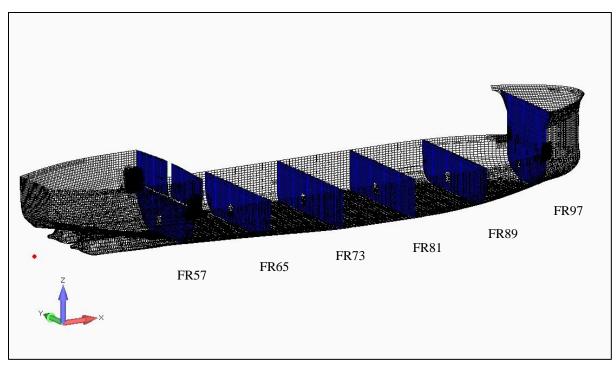


Figure 3-5: Main Transverse Bulkhead Locations

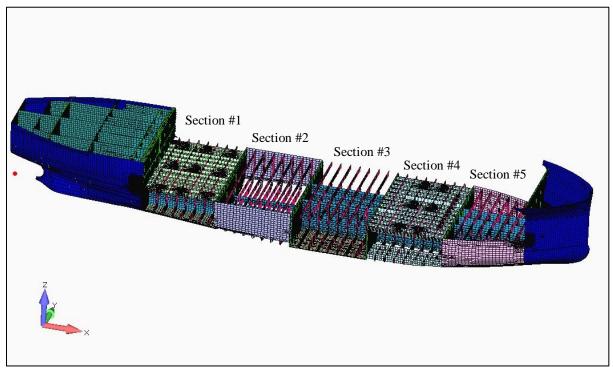


Figure 3-6: ESB Midbody Sections (Each with different groupings displayed)

In addition, as FEMAP allows for the grouping of groups, the five midbody sections are each composed of the different groups of structural elements. Furthermore, the five sections of the midbody can be combined into a single group containing all of the elements within the midbody.

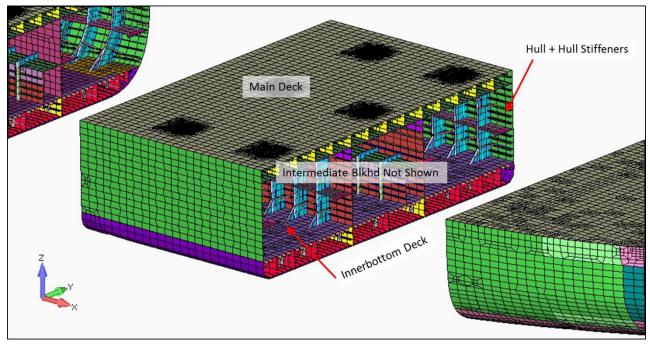


Figure 3-7: ESB Midbody Section Cutaway (Flight Deck not shown for clarity)

3.2.2 Units

The structural analysis of the ESB was performed using the metric system units shown in the table below:

Length	mm
Force	N
Mass	mT
Acceleration	mm/s ²
Pressure	MPa
Stress	MPa

Table 3–3: System of Units used for the Structural Analysis of the ESB

3.2.3 Material Properties

The ESB is constructed of A-36 (Mild Steel) and AH-36 (High Strength Steel), with the higher strength AH-36 specified in the midbody. Material properties used in the FEA model for the ESB are specified in Table 3–4 below. Figure 3-8 shows where each is used.

A-36 Steel						
Modulus of Elasticity	206000 MPa					
Poisson's Ratio	0.3					
Yield Stress	235 MPa					
AH-36	AH-36 Steel					
Modulus of Elasticity	206000 MPa					
Poisson's Ratio	0.3					
Yield Stress	355 MPa					

Table 3–4: Structural Material Specifications

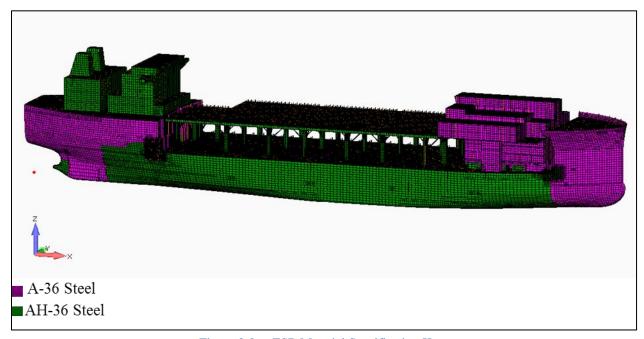


Figure 3-8: ESB Material Specification Key

3.2.4 Mass Modeling

To model the weight distribution of the AMCM Mission Loaded – Departure condition (9.5m draft) chosen for the study, the ship was divided into the 18 zones defined in the ESB Longitudinal Strength Assessment, Reference 3. The density of the steel in each zone was adjusted upward to match this loading condition's associated station weight, which includes not just steel but possibly ballast, fuel, machinery, outfitting, etc. To enable this process, structural groups were generated for each zone.

When the ship corrodes, the plating and stiffeners thin and therefore become lighter. To maintain a constant ship weight, the density in each zone is again adjusted to maintain the same weight in the zone, simulating the additional ballast that would be carried to achieve the desired draft. This process is repeated for each corrosion level analyzed.

The mass of the mission loaded ship at departure is 82,112mT. Table 3–5 shows the weight in each zone, which is plotted in Figure 3-9.

LOCA	TION	20.585	17	16	FR57	15	14	13	12	11
Approx	FRAME	AP	46	56	57	59	62	65	67.5	71.5
Dist fro	om AP	0	36.23	47.82	52.22	59.41	70.99	82.58	94.17	105.76
FEM WEIGHT		0	8676	4502	1814	2207	3147	3369	3702	3727
10	9	8	7	6	5	4	3	2	0	TOTAL
73	76	79	82	85	88	91	94	97	FP	
117.35	128.94	140.52	152.11	163.7	175.29	186.88	198.47	210.06	239.325	
4153	5337	5383	5545	5504	5625	6424	5671	4668	2658	82112

Table 3–5: ESB Longitudinal Weight Distribution Numbers

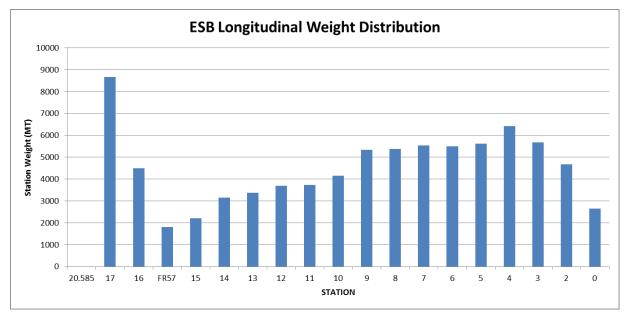


Figure 3-9: ESB Longitudinal Weight Distribution Graph

3.2.5 Corrosion Modeling

Corrosion is modeled at 0%, 25% (maximum allowable limit for renewal under Navy and ABS/IACS), 40%, 55%, and 70% as uniformly reduced plate & stiffener thicknesses across the whole ship (plating and both web and flange of stiffeners). This method of applying and modelling corrosion is conservative as it reduces the overall hull girder strength rather than reducing strength locally, increasing the ship's overall deflection and stress for a given load case. The higher percent wastages were included in this study in order to incorporate realistic situations where corrosion wastages may be in excess of 25% and the ship is required to be operating at sea.

The procedures and files used to parse the geometrical properties from the property card listings, and the steps required to corrode and then update the structure's inertial values and re-establish the proper mass are outlined in Appendix C.

3.2.6 Load Application

The wave pressure and body CG acceleration data from the WASIM seakeeping model must be translated into the FEMAP model and combined to produce the loadsets required for analysis. The process for importing the wave pressure and body CG acceleration data is outlined below:

- Mirror pressure inputs from port to starboard (for head seas only)
- Convert pressure and location units
- Import pressures at pseudo-node locations into FEMAP
- Expand pressure application to all submerged plating panels using FEMAP interpolation controls
- Generate display of wave pressure from loading input and inspect.
- Generate loadsets by combining body CG accelerations and wave pressure loads.

Figure 3-10 illustrates the location of the 300 pseudo-nodes representing the center of port-side pressure panels from WASIM (yellow marks). These pressure values are mirrored to the corresponding starboard side locations to represent the head seas conditions modeled and the units adjusted in an EXCEL file. Using the Data Surface Tool within FEMAP the discrete pressure locations are interpolated across the entire surface of the submerged hull. Proper selection of the built-in interpolation controls allows for the smooth pressure distribution shown in Figure 3-10. Details of this process and the remaining nine (9) hull pressure distributions examined as part of this analysis are included in Appendix C.

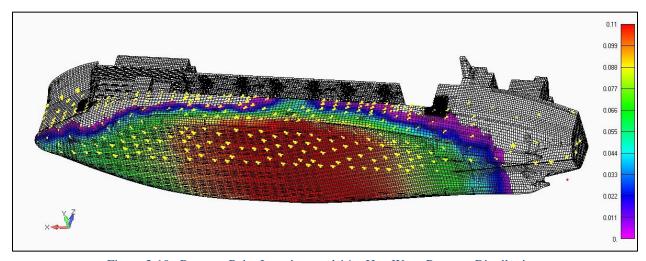


Figure 3-10: Pressure Point Locations and 14m Hog Wave Pressure Distribution

Table 3–6 contains the acceleration data of the ship's CG from the WASIM output. It is noted that these acceleration values are from the time step that produced the largest bending moment at the midship location for the given significant wave height and are not necessarily the highest acceleration during the 20 minute run.

The wave-induced pressure load is then combined with the 3 translational and 1 rotational body acceleration to form the ten (10) loadsets initially used in the analysis. Az is a combination of gravity (-1g) and the vertical acceleration. The acceleration values are low compared to typical structural design accelerations associated with long-term exposure.

WA	AVE	A _X	A _Y	Az	R _Y	
(m)	Туре		(rad/s²)			
14	HOG	-0.122	-0.119	-1.108	0.025	
14	SAG	0.180	0.067	-1.039	-0.004	
11 [HOG	-0.067	-0.077	-1.187	0.024	
11.5	SAG	0.139	0.063	-1.005	-0.005	
9	HOG	-0.096	-0.107	-1.084	0.023	
9	SAG	0.135	0.074	-1.050	-0.005	
6	HOG	-0.054	-0.061	-1.023	0.011	
b	SAG	0.088	0.068	-1.008	-0.010	
4	HOG	-0.006	-0.015	-1.044	-0.001	
	SAG	0.021	0.028	-0.983	-0.006	

Table 3–6: Acceleration Data

3.2.7 Load Cases

Initially, both hog and sag cases were run at both the baseline (0% corroded) and 25% corroded for all wave cases. After analyzing the response it was determined that in the maximum sag case the midbody sees much lower stresses than in the maximum hog condition. The reason for this is the ship selected for this project has a natural hog in still water. The low stresses in the main deck are unlikely to produce a buckling response. The higher wastage percentage runs were therefore limited to the maximum hog cases for the final runs, and no structural analysis was undertaken on the maximum sag cases. The final load cases analyzed are numbered and listed below in Table 3–7.

Table 3–7: Final Load Cases (All Hogging)

LOAD CASE	H _{1/3} (m)	Ship Speed (knots)	Percent Corroded
1	4	16	0
2	6	9	0
3	9	5	0
4	11.5	5	0
5	14	5	0
6	4	16	25
7	6	9	25
8	9	5	25
9	11.5	5	25
10	14	5	25
11	4	16	40
12	6	9	40
13	9	5	40
14	11.5	5	40
15	14	5	40
16	4	16	55
17	6	9	55
18	9	5	55
19	11.5	5	55
20	14	5	55
21	4	16	70
22	6	9	70
23	9	5	70
24	11.5	5	70
25	14	5	70

3.3 Yielding Criteria

An assessment against yielding criteria defined in the IACS Common Structural Rules was performed. The midbody sections are constructed of AH-36 Steel, therefore the mild steel base yield strength of 235 MPa is divided by the AH-36 material factor of .72 for an allowable stress of 326.4 MPa as described in Part 1, Chapter 3, Section 1, 2.2.1. This allowable stress criteria is compared against the Von Mises stress results from the FEA model to calculate a yielding evaluation ratio (FEA model stress/allowable stress).

3.4 Buckling Criteria

Buckling assessment is performed in accordance with the IACS Common Structural Rules.

3.4.1 Plate Buckling

The limit stress in the plating must satisfy four (4) separate interaction formulas. The equations in section 2.2.1 of Reference 4 are simplified and rewritten as 4 separate Buckling Coefficients (BC), the largest of which is the limiting case and which must remain less than unity to indicate a no-buckling response:

$$(\sigma_{x}/\sigma_{cx})^{e0} - B^{*}(\sigma_{x}/\sigma_{cx})^{e0/2} * (\sigma_{y}/\sigma_{cy})^{e0/2} + (\sigma_{y}/\sigma_{cy})^{e0} + (|\tau|/\tau_{c})^{e0} = BC_{1}$$

$$(\sigma_{x}/\sigma_{cx})^{2/Bp0.25} + (|\tau|/\tau_{c})^{2/Bp0.25} = BC_{2}$$

$$(\sigma_{y}/\sigma_{cy})^{2/Bp0.25} + (|\tau|/\tau_{c})^{2/Bp0.25} = BC_{3}$$

$$|\tau|/\tau_{c} = BC_{4}$$

The variables e0 and B, and Bp are geometry and material dependent factors as defined in Section 2.2.1 of Reference 4. The ultimate buckling stress terms (σ_{cx} , σ_{cy} , τ_c) are dependent on the stiffened panel edge conditions and the stiffener type (Tee, Bulb, Flat bar, etc) and are defined in Sect. 2.2.3 of the same reference.

3.4.2 Stiffener Buckling

The single buckling coefficient (BC) that determines the initiation of stiffener buckling is composed of three (3) stress components that are combined and compared to the material yield stress. These stress components are the effective axial stress (σ_a) acting at the midspan of the stiffener, the bending stress (σ_b) due to lateral pressure loading, and the stress due to torsional deformation (σ_w).

$$(\sigma_a + \sigma_B + \sigma_W) / F_{TY} = BC$$

The derivation of each stress term is described in detail in Appendix D. The computation of these variables was easily accomplished in an EXCEL spreadsheet.

4 STRUCTURAL ANALYSIS

Analysis of the FEMAP model is carried out with the NeiNastran solver (v10.1.0.410). As previously noted, the still water bending moment of ESB class vessel produces a hog response. This is mainly due to the ships unequal weight distribution with more weight concentrated in the ends. Therefore in small waves (whether analyzing the maximum hog or maximum sag case) the ship bridges over multiple waves and there is little difference in the plate or stiffener stress (or buckling) response from the still water condition. In fact, the 14m maximum sag wave is the only condition that produced a sag response in the ship. As this sag response is working against the still water hog condition it generates minimal stress in the hull and main deck as shown in Figure 4-1. Conversely, a hog wave reinforces the natural hog response of the ship, resulting in significant stresses as seen in Figure 4-2.

For the buckling analyses, the normal stress in the X (longitudinal) and Y (transverse) directions are utilized. From the 14m maximum hog von mises stress plot shown in Figure 4-3 it is clear that the main deck is in tension while the lower hull experiences compressive stress.

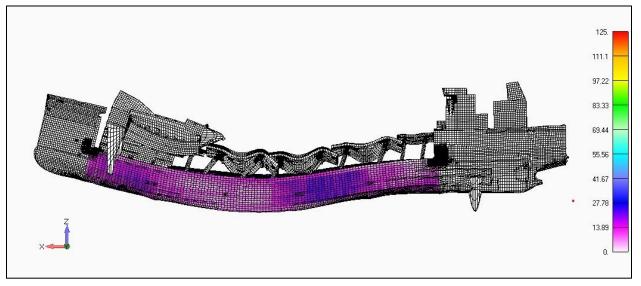


Figure 4-1: 0% Corroded (14m) Maximum Sag - Von Mises Stress Plot

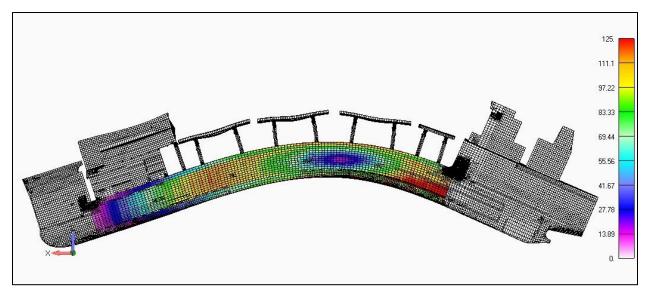


Figure 4-2: 0% Corroded (14m) Maximum Hog - Von Mises Stress Plot

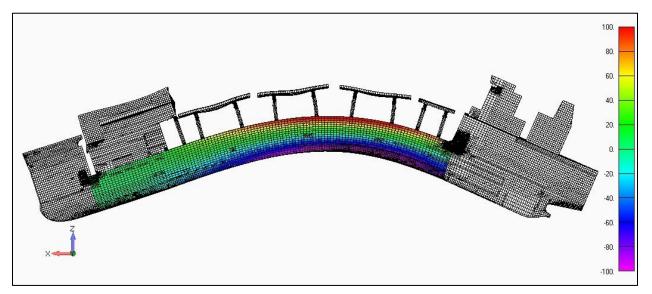


Figure 4-3: 0% Corroded (14m) Maximum Hog – Normal X Stress Plot

4.1 Model Plots and Stress Results

A maximum yielding assessment of the various groups in each midbody section are presented in

Table 4–1 below including the maximum ratio of calculated stress to allowable stress. Purple shading indicates where stresses exceed allowable and yellow shading indicates where they are close to exceeding allowable. Plots showing the 0% corrosion stress distribution in each of these structural groups are seen in Figure 4-4 through Figure 4-12. The 14m maximum hog load case typically produced the maximum von mises stresses at the various corrosion levels. The maximum stresses for the 70% corroded case far exceeded the material yield strength and therefore were not included in the results.

Table 4–1: Maximum Yielding Assessment Results

(÷roun		Midbody	0% Corr	oded	25	% Corro	ded	40	% Corro	ded	55% Corroded		
		Section	VM Stress Ratio				% Increase	VM Stress					
		1	161	0.49	216	0.66	34%	271	0.83	68%	355	1.09	% Increase 120%
Hull Plating 3		165	0.51	211	0.65	28%	257	0.79	56%	336	1.03	104%	
			125	0.38	161	0.49	29%	203	0.62	62%	278	0.85	122%
114111111	6	4	148	0.45	198	0.47	34%	251	0.77	70%	332	1.02	124%
	5		95	0.29	164	0.50	73%	254	0.78	167%	446	1.37	369%
	1		190	0.58	250	0.77	32%	308	0.94	62%	400	1.23	111%
		2	165	0.51	208	0.64	26%	255	0.78	55%	324	0.99	96%
Main Deck Upper Plating		3	143	0.44	184	0.56	29%	226	0.69	58%	291	0.89	103%
Willing Deck Opp	ci i iutilig	4	108	0.33	131	0.40	21%	159	0.49	47%	205	0.63	90%
		5	40	0.12	50	0.15	25%	60	0.18	50%	78	0.24	95%
		1	140	0.43	188	0.58	34%	234	0.72	67%	304	0.93	117%
		2	103	0.32	133	0.41	29%	165	0.72	60%	217	0.66	111%
Main Deck Low	zer Plating	3	105	0.32	133	0.41	27%	165	0.51	57%	216	0.66	106%
Willing Deck Bow	ci i iutilig	4	84	0.26	111	0.34	32%	139	0.43	65%	183	0.56	118%
		5	49	0.15	64	0.20	31%	80	0.25	63%	104	0.32	112%
		1	265	0.13	343	1.05	29%	425	1.30	60%	551	1.69	108%
		2	277	0.85	358	1.10	29%	443	1.36	60%	579	1.77	109%
Main Deck F	raminσ	3	236	0.72	305	0.93	29%	379	1.16	61%	503	1.54	113%
Willin Deck 1	Turring	4	205	0.63	278	0.85	36%	346	1.06	69%	465	1.42	127%
			103	0.32	131	0.40	27%	162	0.50	57%	215	0.66	109%
+		5 1	152	0.47	195	0.60	28%	235	0.72	55%	292	0.89	92%
		2	117	0.36	154	0.47	32%	192	0.72	64%	250	0.77	114%
Inner Bottom	Plating	3	87	0.27	113	0.35	30%	140	0.43	61%	183	0.56	110%
Haici Bottoni	1 Iutilig	4	71	0.22	94	0.29	32%	117	0.36	65%	154	0.47	117%
		5	53	0.16	69	0.21	30%	85	0.26	60%	112	0.34	111%
		1	163	0.50	208	0.64	28%	258	0.79	58%	337	1.03	107%
		2	206	0.63	271	0.83	32%	341	1.04	66%	451	1.38	119%
Inner Bottom	Framing	3	137	0.42	184	0.56	34%	229	0.70	67%	301	0.92	120%
maci bottom	i iuiiiiig	4	105	0.32	136	0.42	30%	171	0.52	63%	224	0.69	113%
		5	66	0.20	87	0.27	32%	109	0.33	65%	143	0.44	117%
		1	222	0.68	290	0.89	31%	365	1.12	64%	483	1.48	118%
		2	103	0.32	134	0.41	30%	168	0.51	63%	220	0.67	114%
Longitudinal B	Bulkheads	3	143	0.44	187	0.57	31%	233	0.71	63%	307	0.94	115%
Longitudina 2	ummeuus	4	200	0.61	259	0.79	30%	326	1.00	63%	429	1.31	115%
		5	110	0.34	143	0.44	30%	180	0.55	64%	235	0.72	114%
	Blkhd 64		86	0.26	112	0.34	30%	139	0.43	62%	181	0.55	110%
Transverse Frames & Blkhds	FR 65 -> 71	1	174	0.53	243	0.74	40%	303	0.93	74%	405	1.24	133%
	Blkhd 72	<u> </u>	73	0.22	100	0.31	37%	125	0.38	71%	166	0.51	127%
	FR 73 -> 79	2	182	0.56	257	0.79	41%	318	0.97	75%	421	1.29	131%
	Blkhd 80	T -	81	0.25	109	0.33	35%	137	0.42	69%	183	0.56	126%
	FR 81 -> 87	3	213	0.65	300	0.92	41%	375	1.15	76%	503	1.54	136%
	Blkhd 88		75	0.23	101	0.31	35%	126	0.39	68%	168	0.51	124%
	FR 89 -> 95	4	205	0.63	278	0.85	36%	346	1.06	69%	465	1.42	127%
	Blkhd 96		157	0.48	200	0.61	27%	246	0.75	57%	319	0.98	103%
	FR 97 -> 103	5	99	0.30	129	0.40	30%	162	0.50	64%	215	0.66	117%
	Blkhd 104		19	0.06	25	0.08	32%	31	0.09	63%	42	0.13	121%
						0.00							

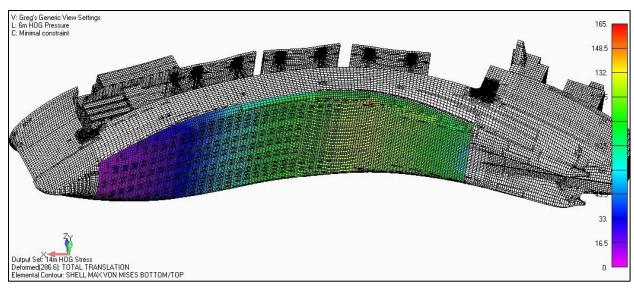


Figure 4-4: Hull Bottom Plating - 0% Corrosion - 14m Hog - Von Mises Stress

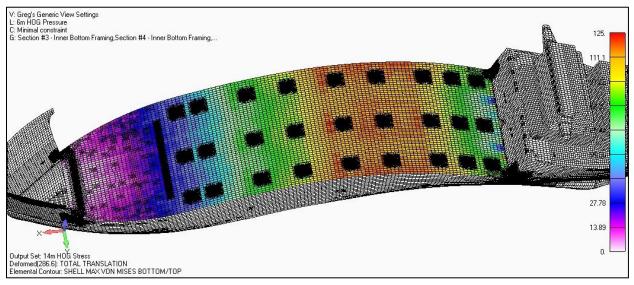


Figure 4-5: Main Deck Plating – 0% Corrosion – 14m Hog – Von Mises Stress

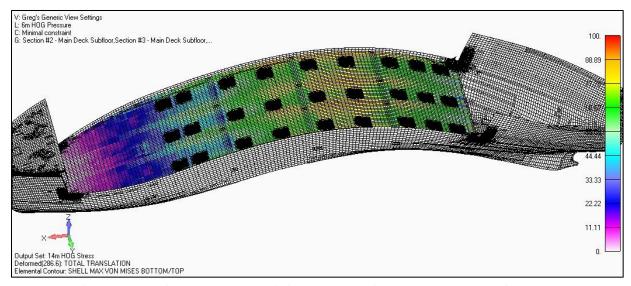


Figure 4-6: Main Deck Inner Top Plating - 0% Corrosion -14m Hog - Von Mises Stress

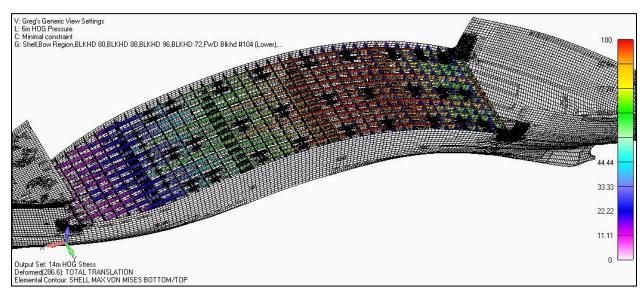


Figure 4-7: Main Deck Framing - 0% Corrosion – 14m Hog – Von Mises Stress

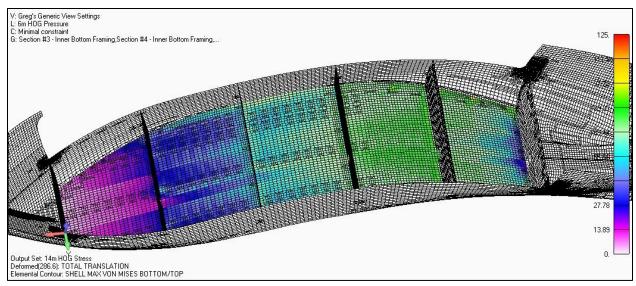
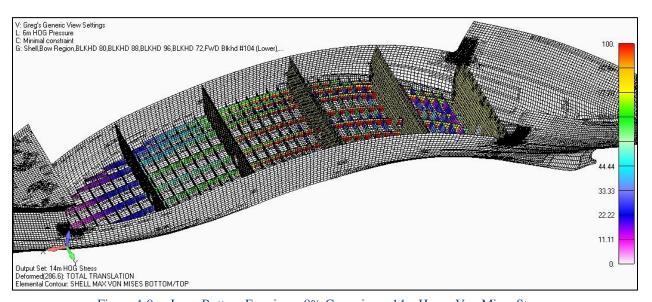


Figure 4-8: Inner Bottom Plating – 0% Corrosion – 14m Hog – Von Mises Stress



 $Figure\ 4-9:\quad Inner\ Bottom\ Framing -0\%\ Corrosion -14m\ Hog -Von\ Mises\ Stress$

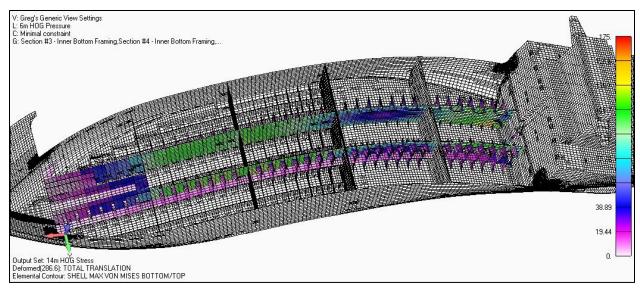
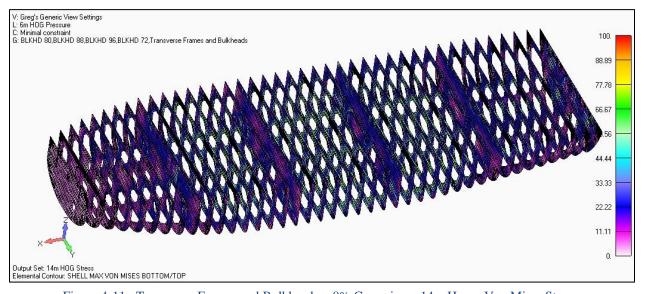


Figure 4-10: Long'l Blkhds – 0% Corrosion – 14m Hog – Von Mises Stress



Figure~4--11:~Transverse~Frames~and~Bulkheads-0%~Corrosion-14m~Hog-Von~Mises~Stress

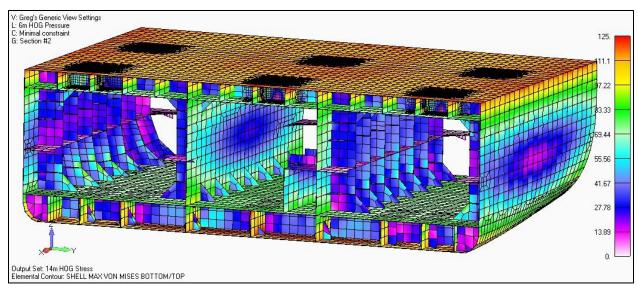


Figure 4-12: Section 2 – 0% Corrosion – 14m Hog – Von Mises Stress

4.2 Determining Buckling Capacities

Buckling capacities were determined using the IACS Common Structural Rules. The buckling coefficients (BC) were determined at each wave state and corrosion level for the maximum hog condition. A detailed explanation of the procedure employed to determine bucking coefficients is included in Appendix D.

4.2.1 Buckling Strength - Hull Bottom Longitudinal Stiffeners

The buckling coefficients calculated for the hull bottom longitudinal stiffeners in the various significant wave heights for corrosion levels of 0%, 25% and 40% are shown in Table 4–2. All are below 1.0 so are acceptable.

Table 4–2: ESB Hull Bottom Longitudinal Stiffener Buckling Response for 0%, 25% & 40% Corrosion

		CORROSION = 0%			CORROSION = 25%					CORROSION = 40%					
Long'l	14m	11.5m	9m	6m	4m	14m	11.5m	9m	6m	4m	14m	11.5m	9m	6m	4m
-27															
-26	0.496	0.404	0.354	0.235	0.233	0.627	0.508	0.443	0.290	0.287	0.801	0.650	0.567	0.372	0.372
-25	0.500	0.405	0.464	0.255	0.247	0.762	0.630	0.500	0.440	0.427	0.070	0.007	0.757	0.577	0.577
-24 -23	0.598 0.508	0.495 0.424	0.464 0.412	0.355 0.326	0.347 0.322	0.763 0.654	0.629 0.543	0.590 0.528	0.448 0.414	0.437 0.409	0.978 0.836	0.807 0.695	0.757 0.676	0.577 0.532	0.577 0.532
-23 -22	0.522	0.424	0.412	0.326	0.322	0.667	0.554	0.528	0.414	0.409	0.853	0.709	0.676	0.532	0.544
-21	0.522	0.433	0.424	0.555	0.551	0.007	0.554	0.555	0.424	0.410	0.055	0.705	0.031	0.544	0.544
-20	0.454	0.380	0.349	0.279	0.276	0.597	0.497	0.462	0.370	0.366	0.750	0.627	0.584	0.471	0.471
-19	0.461	0.368	0.354	0.287	0.289	0.604	0.487	0.466	0.372	0.371	0.758	0.614	0.589	0.472	0.472
-18	0.461	0.372	0.352	0.281	0.279	0.604	0.493	0.468	0.376	0.374	0.759	0.622	0.590	0.478	0.478
-17	0.463	0.387	0.357	0.276	0.276	0.608	0.492	0.472	0.355	0.350	0.763	0.621	0.597	0.453	0.453
-16															
-15	0.461	0.385	0.358	0.283	0.280	0.605	0.504	0.474	0.354	0.350	0.759	0.635	0.599	0.479	0.479
-14	0.461	0.385	0.354	0.280	0.277	0.605	0.504	0.469	0.372	0.368	0.759	0.635	0.593	0.473	0.473
-13 -12	0.456 0.457	0.380 0.380	0.354 0.350	0.279 0.274	0.276 0.271	0.598 0.598	0.497 0.498	0.469 0.463	0.370 0.364	0.367 0.361	0.751 0.752	0.626 0.627	0.593 0.586	0.471 0.463	0.471 0.463
-12	0.457	0.377	0.351	0.274	0.271	0.594	0.498	0.464	0.364	0.360	0.732	0.621	0.586	0.463	0.463
-10	0.455	0.377	0.348	0.273	0.268	0.597	0.495	0.460	0.360	0.355	0.749	0.624	0.582	0.458	0.458
-9	0.453	0.376	0.347	0.271	0.266	0.595	0.492	0.459	0.358	0.353	0.747	0.620	0.580	0.456	0.456
-8															
-7	0.449	0.372	0.347	0.271	0.267	0.589	0.489	0.460	0.359	0.353	0.740	0.615	0.581	0.458	0.458
-6	0.454	0.377	0.349	0.273	0.269	0.595	0.494	0.462	0.361	0.356	0.747	0.622	0.584	0.461	0.461
-5	0.456	0.379	0.353	0.277	0.272	0.598	0.497	0.466	0.366	0.360	0.751	0.626	0.589	0.466	0.466
-4	0.462	0.385	0.354	0.276	0.272	0.605	0.503	0.466	0.366	0.360	0.759	0.634	0.590	0.466	0.466
-3	0.462	0.385	0.357	0.280	0.276	0.605	0.504	0.473	0.371	0.366	0.760	0.634	0.597	0.473	0.473
-2	0.467	0.390	0.359	0.281	0.277	0.612	0.510	0.474	0.372	0.367	0.768	0.643	0.599	0.474	0.474
-1 0	0.468	0.390	0.363	0.285	0.281	0.614	0.512	0.480	0.378	0.372	0.771	0.644	0.607	0.481	0.481
1	0.470	0.392	0.362	0.285	0.281	0.616	0.514	0.480	0.377	0.372	0.774	0.648	0.607	0.480	0.480
2	0.467	0.390	0.362	0.272	0.281	0.613	0.511	0.480	0.358	0.353	0.770	0.644	0.606	0.456	0.456
3	0.469	0.391	0.361	0.282	0.278	0.614	0.512	0.474	0.373	0.368	0.771	0.645	0.599	0.476	0.476
4	0.463	0.386	0.359	0.282	0.278	0.607	0.505	0.474	0.374	0.368	0.762	0.636	0.599	0.476	0.476
5	0.463	0.386	0.355	0.278	0.274	0.607	0.505	0.469	0.368	0.363	0.762	0.636	0.593	0.469	0.469
6	0.456	0.379	0.354	0.277	0.273	0.598	0.497	0.468	0.367	0.362	0.752	0.626	0.592	0.468	0.468
7	0.452	0.375	0.350	0.274	0.270	0.594	0.492	0.464	0.363	0.357	0.746	0.620	0.586	0.463	0.463
8															
9	0.456	0.378	0.349	0.273	0.269	0.598	0.496	0.462	0.361	0.356	0.752	0.625	0.584	0.460	0.460
10	0.456	0.379	0.351	0.275	0.270	0.599	0.497	0.464	0.363	0.358	0.752	0.626	0.587	0.463	0.463
11 12	0.459 0.456	0.382 0.380	0.351 0.354	0.274 0.278	0.270 0.274	0.601 0.598	0.499 0.497	0.464 0.468	0.363 0.368	0.359 0.364	0.754 0.751	0.629 0.626	0.586 0.592	0.463 0.468	0.463 0.468
13	0.462	0.385	0.354	0.278	0.274	0.604	0.504	0.468	0.368	0.365	0.751	0.634	0.592	0.469	0.469
14	0.461	0.384	0.358	0.272	0.269	0.604	0.504	0.474	0.359	0.354	0.759	0.634	0.599	0.458	0.458
15	0.465	0.388	0.359	0.269	0.265	0.610	0.509	0.475	0.356	0.351	0.765	0.641	0.601	0.453	0.453
16															
17	0.463	0.374	0.359	0.272	0.274	0.608	0.496	0.475	0.353	0.348	0.764	0.626	0.600	0.450	0.450
18	0.465	0.371	0.352	0.278	0.277	0.610	0.491	0.467	0.372	0.370	0.765	0.620	0.590	0.472	0.472
19	0.460	0.371	0.355	0.285	0.287	0.603	0.491	0.464	0.372	0.369	0.757	0.619	0.586	0.472	0.472
20	0.457	0.382	0.351	0.264	0.262	0.599	0.500	0.465	0.351	0.348	0.752	0.630	0.587	0.447	0.447
21	0.533	0.435	0.434	0.335	0.220	0.667	0.554	0.530	0.422	0.447	0.053	0.700	0.000	0.543	0.543
22	0.522	0.435	0.424	0.335	0.330	0.667	0.554	0.539	0.423	0.417	0.853	0.709	0.690	0.543	0.543
23 24	0.508 0.599	0.424 0.496	0.412 0.465	0.325 0.356	0.321 0.348	0.653 0.764	0.542 0.630	0.527 0.591	0.413 0.449	0.408 0.439	0.835 0.979	0.694 0.809	0.675 0.759	0.531 0.578	0.531 0.578
25	0.333	0.430	0.403	0.330	0.340	0.704	0.030	0.331	0.449	0.439	0.373	0.009	0.733	0.576	0.376
26	0.496	0.405	0.355	0.236	0.234	0.628	0.510	0.445	0.292	0.289	0.803	0.652	0.569	0.375	0.375
27	2. 750	200	2.333			2.320				5.205	2.300	533 .	2.303	2.373	
MAX	0.599	0.496	0.465	0.356	0.348	0.764	0.630	0.591	0.449	0.439	0.979	0.809	0.759	0.578	0.578

Figure 4-13 and Figure 4-14 show how these bottom stiffener buckling coefficients vary along the length and width of the midbody for the 14m hog wave with no corrosion.

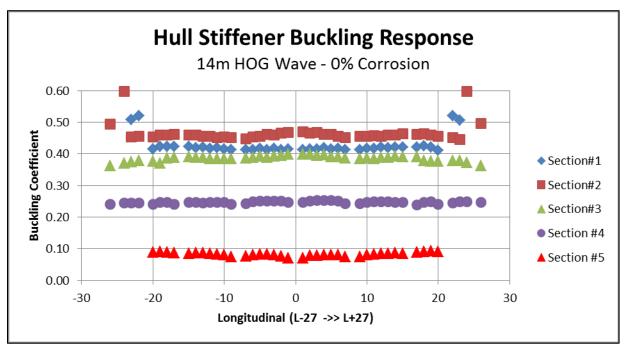


Figure 4-13: Hull Bottom Stiffener Buckling Response – 14m – 0% Corrosion

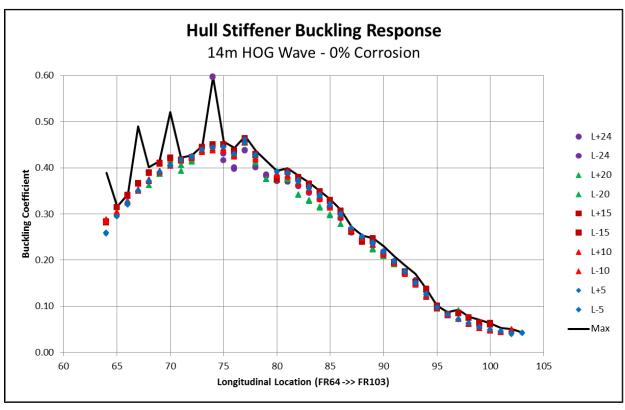


Figure 4-14: Hull Bottom Stiffener Buckling Response – 14m – 0% Corrosion

Figure 4-15 shows how the peak buckling coefficient in these stiffeners varies along the midbody length and for the different corrosion levels up to 55%. For the 55% corrosion case, some stiffeners are likely to buckle in the 14m hog wave condition because their buckling coefficient exceeds 1.0.

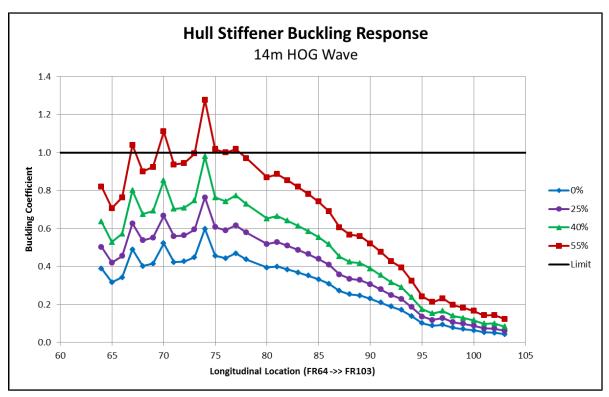


Figure 4-15: Hull Bottom Stiffener Buckling Response – 14m – 0% Corrosion

4.2.2 Buckling Strength - Hull Bottom Plating

The buckling coefficients calculated for the hull bottom plating in the various significant wave heights for corrosion levels of 0%, 25%, 40% and 55% are shown in Table 4–3. At or above 40% wastage the peak buckling coefficients are over 1.0 regardless of wave height and therefore indicate buckling failure.

Table 4–3: Hull Bottom Plating Buckling Response

1	0% CORROSION			25% CORROSION			40% CORROSION			55% CORROSION										
Long'l	14m	11.5m	9m	6m	4m	14m	11.5m	9m	6m	4m	14m	11.5m	9m	6m	4m	14m	11.5m	9m	6m	4m
-27	0.121	0.092	0.085	0.065	0.061	0.593	0.456	0.426	0.331	0.313	1.780	1.391	1.309	1.031	0.980	6.123	4.871	4.622	3.703	3.533
-26	0.111	0.081	0.079	0.058	0.055	0.542	0.404	0.393	0.294	0.280	1.633	1.241	1.210	0.924	0.882	5.644	4.374	4.276	3.333	3.194
-25	0.113	0.084	0.070	0.050	0.047	0.555	0.420	0.351	0.254	0.241	1.676	1.292	1.091	0.806	0.766	5.790	4.549	3.884	2.937	2.801
-24	0.118	0.089	0.074	0.054	0.051	0.576	0.442	0.371	0.278	0.263	1.739	1.356	1.150	0.878	0.833	6.015	4.776	4.094	3.188	3.036
-23	0.122	0.093	0.077	0.059	0.055	0.594	0.461	0.388	0.299	0.282	1.791	1.410	1.200	0.939	0.890	6.187	4.956	4.264	3.398	3.232
-22	0.120	0.091	0.074	0.057	0.053	0.588	0.454	0.376	0.292	0.275	1.772	1.391	1.164	0.917	0.868	6.119	4.886	4.149	3.323	3.159
-21	0.112	0.085	0.069	0.050	0.047	0.551	0.425	0.347	0.255	0.241	1.666	1.305	1.080	0.809	0.768	5.779	4.606	3.861	2.952	2.812
-20	0.121	0.090	0.075	0.053	0.050	0.583	0.442	0.371	0.263	0.248	1.748	1.349	1.144	0.823	0.783	5.992	4.710	4.041	2.978	2.841
-19	0.097	0.072	0.059	0.041	0.042	0.479	0.364	0.301	0.212	0.213	1.461	1.129	0.947	0.682	0.660	5.114	4.028	3.419	2.525	2.408
-18	0.093	0.069	0.060	0.044	0.043	0.463	0.351	0.303	0.226	0.224	1.414	1.092	0.947	0.720	0.715	4.949	3.895	3.410	2.647	2.628
-17	0.090	0.067	0.064	0.052	0.053	0.445	0.334	0.323	0.265	0.268	1.363	1.040	0.987	0.817	0.825	4.770	3.714	3.550	2.910	2.936
-16 -15	0.089	0.065	0.060	0.049	0.050	0.438	0.329	0.309	0.252	0.257	1.342	1.025	0.965	0.778	0.791	4.708	3.666	3.486	2.815	2.818
-15	0.109 0.094	0.079	0.078	0.059	0.056	0.522	0.385	0.381	0.288	0.273	1.559	1.171	1.159	0.874	0.833	5.322	4.077	4.036 4.002	3.094	2.965 3.117
-14	0.094	0.070	0.071	0.054	0.052	0.469	0.358	0.361 0.352	0.277	0.270 0.271	1.433	1.111	1.120	0.874	0.854 0.855	5.025 5.280	3.968 4.124	3.912	3.184 3.142	3.117
-13	0.101	0.075	0.070	0.052	0.052	0.498	0.375	0.352	0.273	0.271	1.702	1.160	1.095	0.002	0.000	5.836	4.124	4.353	3.346	3.313
-12	0.110	0.082	0.081	0.057	0.055	0.545	0.414	0.404	0.300	0.290	1.650	1.275	1.242	0.922	0.897	5.732	4.515	4.333	3.421	3.265
-10	0.115	0.086	0.078	0.060	0.057	0.566	0.431	0.397	0.307	0.292	1.708	1.322	1.227	0.963	0.919	5.911	4.661	4.360	3.484	3.335
-9	0.113	0.000	0.073	0.068	0.064	0.599	0.458	0.439	0.345	0.327	1.804	1.400	1.347	1.075	1.020	6.235	4.927	4.758	3.857	3.675
-8	0.128	0.097	0.091	0.071	0.067	0.630	0.484	0.454	0.359	0.340	1.890	1.477	1.393	1.115	1.059	6.508	5.176	4.905	3.990	3.802
-7	0.132	0.100	0.092	0.072	0.068	0.648	0.498	0.460	0.366	0.345	1.942	1.517	1.406	1.133	1.072	6.674	5.305	4.945	4.043	3.840
-6	0.133	0.100	0.092	0.072	0.067	0.650	0.498	0.459	0.364	0.343	1.950	1.518	1.404	1.128	1.067	6.698	5.309	4.936	4.026	3.825
-5	0.127	0.095	0.086	0.066	0.062	0.621	0.471	0.431	0.334	0.315	1.867	1.442	1.326	1.043	0.989	6.428	5.057	4.678	3.746	3.563
-4	0.121	0.090	0.081	0.061	0.057	0.593	0.447	0.407	0.311	0.294	1.788	1.372	1.257	0.977	0.926	6.171	4.827	4.451	3.524	3.353
-3	0.116	0.087	0.077	0.057	0.054	0.570	0.432	0.387	0.293	0.276	1.725	1.327	1.201	0.924	0.876	5.964	4.679	4.263	3.346	3.183
-2	0.114	0.086	0.070	0.050	0.047	0.561	0.431	0.353	0.258	0.244	1.696	1.325	1.099	0.819	0.778	5.879	4.675	3.925	2.988	2.847
-1	0.111	0.084	0.067	0.048	0.045	0.545	0.418	0.341	0.248	0.235	1.650	1.287	1.062	0.790	0.749	5.722	4.544	3.796	2.885	2.747
0	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000
1	0.105	0.078	0.063	0.044	0.045	0.516	0.391	0.318	0.229	0.236	1.566	1.208	0.996	0.728	0.748	5.442	4.279	3.571	2.686	2.748
2	0.112	0.085	0.071	0.054	0.051	0.552	0.427	0.361	0.278	0.262	1.669	1.313	1.120	0.876	0.829	5.799	4.643	4.005	3.188	3.029
3	0.118	0.089	0.074	0.056	0.055	0.574	0.445	0.375	0.287	0.285	1.734	1.363	1.161	0.905	0.893	6.005	4.804	4.136	3.285	3.240
4	0.120	0.091	0.076	0.057	0.058	0.586	0.454	0.381	0.294	0.297	1.767	1.389	1.179	0.924	0.931	6.109	4.887	4.195	3.344	3.366
5	0.116	0.087	0.074	0.060	0.060	0.568	0.434	0.377	0.306	0.309	1.716	1.334	1.165	0.958	0.966	5.938	4.701	4.142	3.458	3.483
6	0.112	0.084	0.076	0.060	0.061	0.549	0.418	0.386	0.306	0.312	1.663	1.287	1.192	0.961	0.975	5.764	4.543	4.231	3.468	3.510
7	0.112	0.083	0.077	0.063	0.063	0.547	0.415	0.389	0.320	0.323	1.657	1.279	1.201	0.999	1.008	5.743	4.518	4.259	3.592	3.621
- 8 9	0.105 0.101	0.080	0.079	0.063	0.063	0.515 0.498	0.401	0.398	0.321	0.321	1.566	1.232 1.236	1.229 1.196	1.004 0.971	1.003 0.970	5.440 5.271	4.359 4.373	4.353 4.244	3.612 3.501	3.608 3.495
10	0.101	0.080	0.077	0.058	0.060	0.498	0.403	0.377	0.295	0.309	1.603	1.230	1.170	0.930	0.970	5.557	4.310	4.244	3.364	3.328
11	0.107	0.078	0.075	0.054	0.057	0.545	0.405	0.376	0.295	0.291	1.650	1.219	1.170	0.930	0.863	5.713	4.416	4.139	3.175	3.138
12	0.111	0.081	0.075	0.055	0.053	0.552	0.412	0.375	0.276	0.272	1.672	1.270	1.164	0.888	0.857	5.784	4.479	4.137	3.226	3.119
13	0.113	0.082	0.076	0.056	0.053	0.552	0.412	0.383	0.286	0.274	1.670	1.268	1.187	0.905	0.869	5.780	4.476	4.214	3.282	3.160
14	0.113	0.083	0.074	0.054	0.051	0.557	0.416	0.375	0.277	0.265	1.685	1.284	1.163	0.879	0.842	5.831	4.530	4.133	3.195	3.068
15	0.110	0.080	0.072	0.051	0.049	0.540	0.402	0.361	0.265	0.253	1.638	1.243	1.124	0.844	0.807	5.674	4.392	4.003	3.074	2.949
16	0.104	0.075	0.067	0.047	0.045	0.510	0.377	0.338	0.243	0.231	1.551	1.168	1.054	0.777	0.743	5.387	4.141	3.766	2.847	2.728
17	0.101	0.074	0.061	0.041	0.041	0.496	0.371	0.308	0.214	0.216	1.509	1.151	0.966	0.692	0.691	5.247	4.084	3.460	2.551	2.550
18	0.100	0.073	0.061	0.049	0.050	0.491	0.368	0.303	0.247	0.252	1.495	1.144	0.951	0.763	0.778	5.208	4.066	3.419	2.724	2.771
19	0.099	0.073	0.064	0.049	0.049	0.491	0.369	0.326	0.255	0.254	1.495	1.146	1.018	0.808	0.807	5.210	4.071	3.651	2.953	2.948
20	0.099	0.073	0.067	0.051	0.051	0.484	0.362	0.342	0.265	0.263	1.476	1.126	1.064	0.840	0.833	5.142	4.003	3.805	3.062	3.040
21	0.106	0.077	0.069	0.053	0.052	0.520	0.388	0.352	0.275	0.272	1.580	1.202	1.095	0.869	0.861	5.479	4.251	3.908	3.162	3.134
22	0.103	0.080	0.074	0.056	0.055	0.506	0.403	0.377	0.290	0.284	1.539	1.240	1.167	0.914	0.897	5.353	4.391	4.151	3.312	3.254
23	0.108	0.080	0.073	0.055	0.054	0.530	0.400	0.371	0.285	0.279	1.609	1.235	1.151	0.899	0.881	5.581	4.370	4.097	3.264	3.201
24	0.113	0.082	0.077	0.057	0.054	0.551	0.409	0.385	0.289	0.274	1.669	1.263	1.195	0.915	0.871	5.783	4.463	4.243	3.316	3.168
25	0.120	0.088	0.083	0.063	0.059	0.589	0.442	0.418	0.321	0.304	1.777	1.357	1.290	1.007	0.958	6.136	4.776	4.559	3.626	3.461
26	0.132	0.098	0.093	0.072	0.068	0.641	0.487	0.465	0.365	0.345	1.922	1.483	1.421	1.131	1.074	6.594	5.182	4.984	4.029	3.843
27	0.135	0.102	0.094	0.073	0.069	0.660	0.507	0.469	0.372	0.351	1.972	1.540	1.431	1.149	1.088	6.751	5.367	5.013	4.086	3.884
MAX	0.135	0.102	0.094	0.073	0.069	0.660	0.507	0.469	0.372	0.351	1.972	1.540	1.431	1.149	1.088	6.751	5.367	5.013	4.086	3.884

Figure 4-13 through Figure 4-20 graphically show various aspects of bottom plate buckling response.

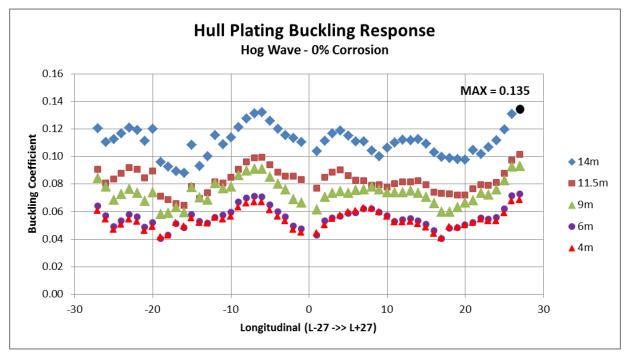


Figure 4-16: Hull Bottom Plating Buckling Response vs Transverse Location – 0% Corrosion

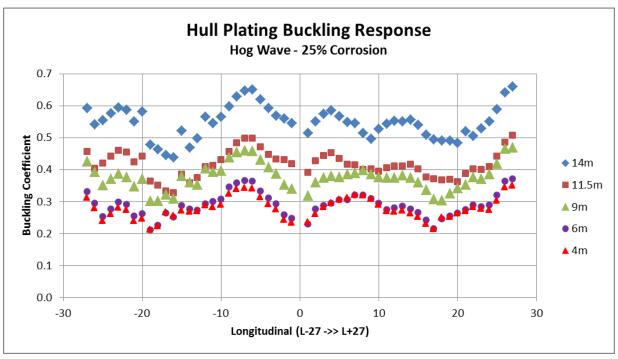


Figure 4-17: Hull Bottom Plating Buckling Response vs Transverse Location – 25% Corrosion

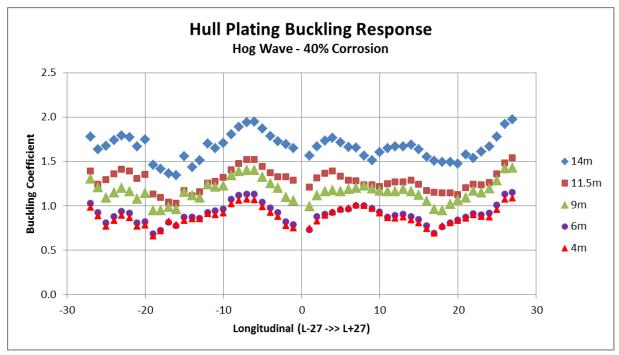


Figure 4-18: Hull Bottom Plating Buckling Response vs Transverse Location – 40% Corrosion

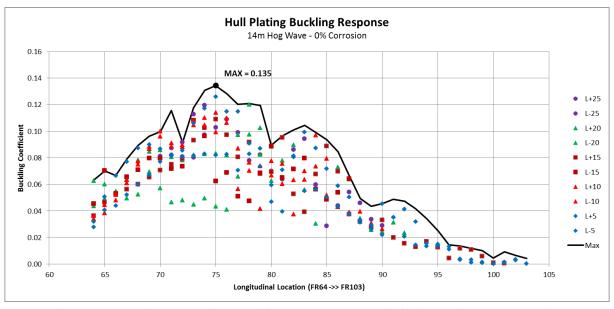


Figure 4-19: Hull Bottom Plating Buckling Response vs Longitudinal Location – 0% Corrosion

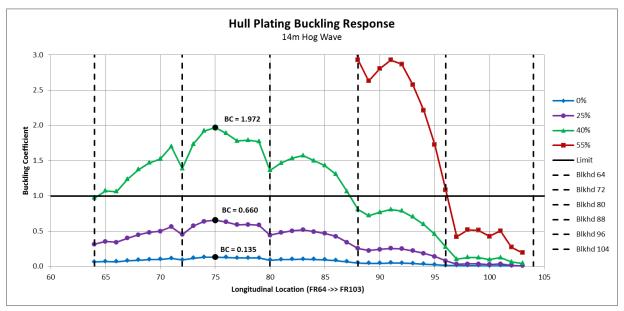


Figure 4-20: Hull Bottom Plating Buckling Response – 14m Hog

5 STRENGTH ASSESSMENT

An assessment of the analyzed failure modes for the example ESB ship indicates that corrosion levels above 25% (maximum allowable limit for renewal under Navy and ABS/IACS) may compromise the seaworthiness of the ship in the modeled conditions and duration. At these higher corrosion levels the buckling capacity of the hull bottom plating decreases significantly, and was the driving failure mode in our limited analysis. As seen in Figure 4-18, at 40% corrosion, calculated buckling coefficients for the hull plating exceed 1.0 for all wave conditions analyzed. At the 25% corrosion level (Figure 4-17) calculated hull plating and stiffener buckling coefficients remain under 1.0 in all wave conditions.

As seen in Table 4-1, at a 25% corrosion level, the maximum stress ratios (calculated stress/allowable) are below 1.0 in all but the main deck framing group. These higher stress values are not global, but located around unreinforced openings in the longitudinal main deck framing. Calculated stress is above the allowable in the unreinforced openings for the 14m hog wave condition, but under the allowable limit for the 11.5m hog wave condition. See Figure 5-1 and Figure 5-2 below.

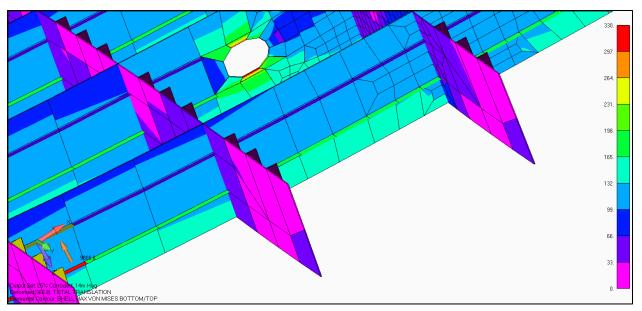


Figure 5-1: Unreinforced Opening in Longitudinal Deck Framing - 25% Corrosion - 14m Hog

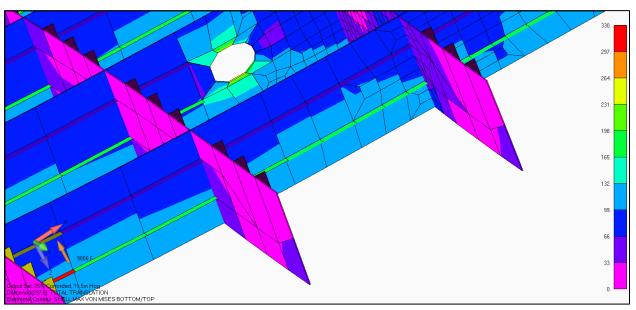


Figure 5-2: Unreinforced Opening in Longitudinal Deck Framing - 25% Corrosion - 11.5m Hog

6 CONCLUSIONS

In our limited study of the ESB ship, with uniform corrosion beyond the typical 25% limit, hull bottom plate buckling coefficients rise dramatically, so that even in the lower sea states buckling of the hull plating is possible. A more thorough investigation may reveal other failure locations with less than 25% wastage. Future research on this topic could consider and evaluate the residual strength of a ship structure with localized corrosion damage. Localized and non-uniform structural corrosion and pitting are probably more common than uniform corrosion across the entire hull structure, but is very case-specific.

The approach developed herein to assess a degraded ship structure can be expanded and then used to develop a safe operating envelope for a ship's hull structure with various degrees of corrosion. While many simplifications of scope and assumptions were made for this project, a more thorough assessment of a degraded ship structure can be accomplished, but would require modeling the ship's actual corrosion levels, more seaway conditions, more headings and more ship loading conditions, amplifying loadings to account for expected exposure times, and investigating more structural components such as internal tank bulkheads and their internal fluid loadings. In addition, green seas, whipping, and slamming effects may need to be addressed. This more rigorous assessment, while possible, would be a costly and time consuming effort.

Appendix A Range of Seakeeping Analysis Conditions Recommended for a Full Analysis

The runs matrix required for a specific ship assessment will vary significantly depending on the vessel size and type. For example, a large ship like the ESB will have minimal susceptibility in low sea state conditions that might be fatal to a 90 foot long fishing vessel.

There are a number of parameters that should be included in the assessment matrix.

- Drafts: Loading conditions normally encountered by the vessel in question including at least a typical maximum draft and a typical minimum draft condition.
- Headings: All vessel headings from head sea to following seas in at least 30 degree increments. If the program used provides artificial nulls for roll, sway and yaw in head and following seas, then there are two choices to mitigate that concern.
 - o Angles of 15 degrees and 165 degrees can be substituted for 0 and 180 for head and following seas such that some small amount of roll, sway and yaw are excited
 - o If the software supports it, run the head and following seas in short crested seas where the wave components are coming from a spread of directions, typically using cosine squared spreading. This will produce reasonable motions in head and following seas but in general the maximum pitch motions will be reduced by about 20% from the long crested case.
- Speeds: The normal navigation speed of the ship should be modeled as well as the speed the Captain usually selects for rough weather. It may come out of the analysis that a slower or faster speed in rough weather will reduce the hull girder stresses by a significant amount. On ships with active ride control fins, speeding up a few knots may actually reduce the stresses and the added lift of the ride control fins can reduce the motions and slamming.
- Water depth considerations:
 - o If a ship is in liner service in waters shallow enough for 10 to 12 second waves to feel the bottom, then a depth sensitive seakeeping model should be used.
 - o If the ship is in liner service on a western shore or where there is not much continental shelf, it may be necessary to model both a wind sea and swell component to the wave field using the Ochi-Hubble 6 parameter spectrum or similar.
- Wave conditions:
 - Most naval architecture methods in use today utilize mathematical wave spectra to model the wave field. There are many different types, most were developed in the 1950's through 1980's based on very limited data sets from a single location on the planet. The advantage of the Bretschneider, Pierson-Moskowitz, Ochi-Hubble, ITTC, ISSC, or JONSWOP spectra is that everyone setting up an analysis with the same spectral form and same input parameters should get similar results.

It must also be decided what significant wave heights to model. Figure A-1 shows wave energy divided up into sea state bins on the left hand panel and by 1m intervals on the right hand panel.

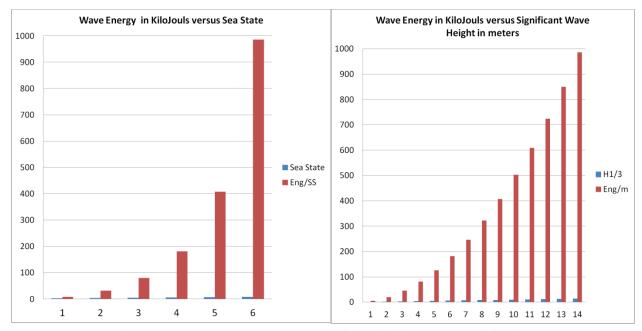


Figure A-1: Wave Energy Vs Sea State and 1m Significant Wave Height Bins

The left hand view shows that sea state is too coarse a measure to allow a meaningful search for a threshold for safe operations. The 1m steps in the right hand panel show much better granularity for finding a realistic limiting case.

While this suggests that a lot of modeling is necessary, that is not necessarily the case. For a ship the size of the ESB, anything below about the top of sea state 5 at 4m significant wave height is irrelevant. If the study starts there and works up a few sets at a time, the limit can be reached before one gets up to 14 m wave or higher.

Appendix B Hydrodynamic Pressure Distributions

Plots of nine of the ten WASIM-derived hull pressure data sets acting on the FEM are shown in Figure B-1 through Figure B-9. (The tenth is included as Figure 3-10 in the report body.)

From the pressure distribution, it is readily evident that a hog wave shows maximum pressure acting near the hull center, whereas a Sag wave shows the pressure peaking near the fore and aft ends of the ship. In addition, the wave shape can also be identified by the height reached by the wave near the bow and transom areas. The magnitude of the pressure (0.1 MPa) acting on hull bottom is approximately the same for the smaller wave sizes.

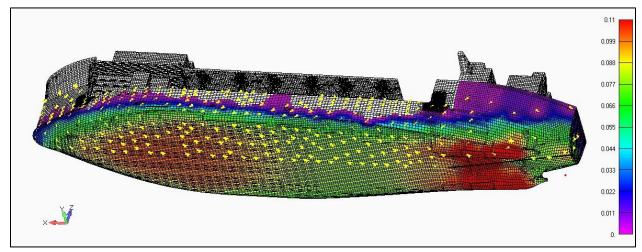


Figure B-1: 14m Sag Wave

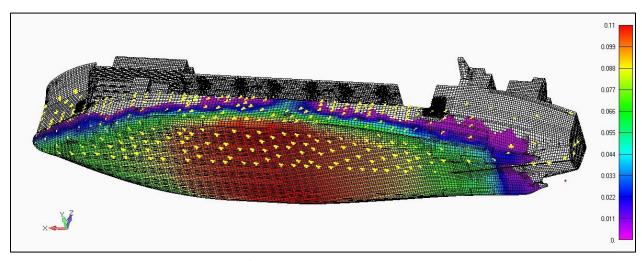


Figure B-2: 11.5m Hog Wave

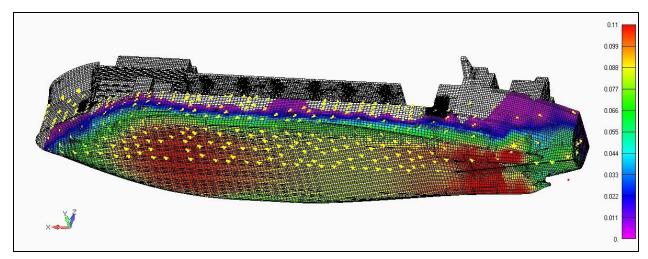


Figure B-3: 11.5m Sag Wave

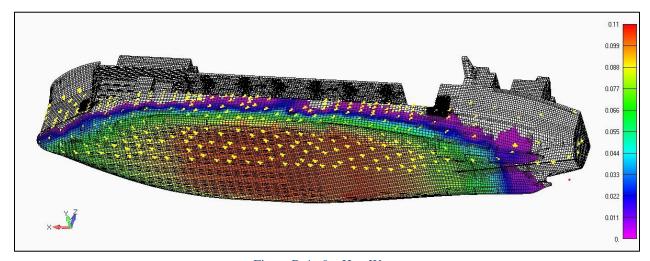


Figure B-4: 9m Hog Wave

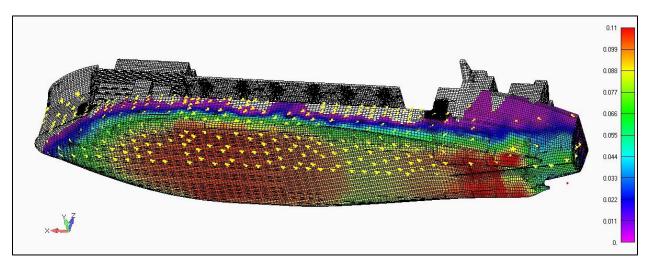


Figure B-5: 9m Sag Wave

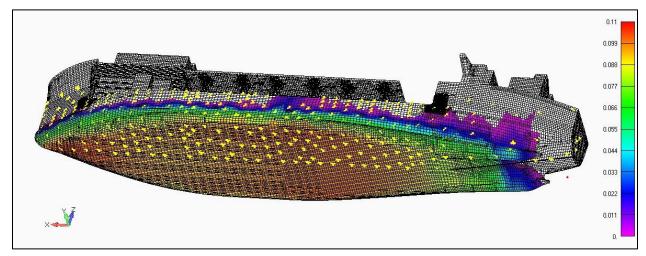


Figure B-6: 6m Hog Wave

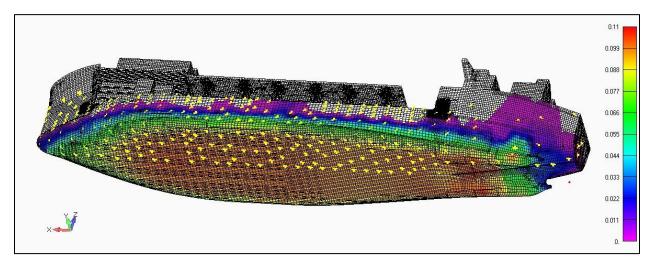


Figure B-7: 6m Sag Wave

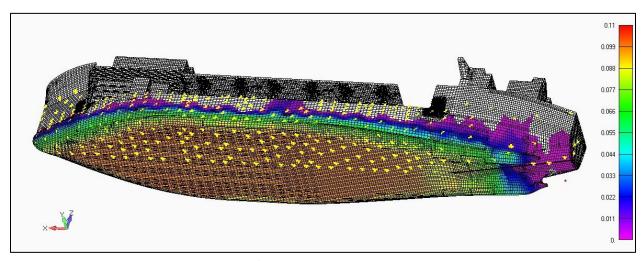


Figure B-8: 4m Hog Wave

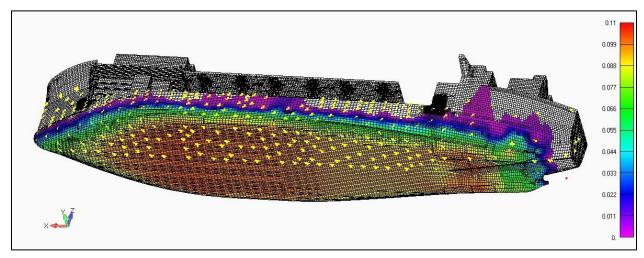


Figure B-9: 4m Sag Wave

Appendix C Structural Model Preparation Procedures

C.1 Procedure for Mapping WASIM Pressure into FEMAP Model

C.1.1 Input Data

The 300 data points received from WASIM are in column format containing the X, Y, and Z position of the panel center, and the corresponding pressure value. See Table C-1. They represent a random distribution of points along the hull, port side only.

4m wave case 6m wave case 9m wave case 11.5m wave case 14m wave case Label xpress ypress zpress Hogging Sagging Hogging Sagging Hogging Sagging Hogging Sagging Hogging Sagging Panel_Cnt_1 230.420 1.994 14 963 225.333 Panel Cnt 2 5.707 13.956 Panel_Cnt_3 13.957 Panel_Cnt_4 Panel_Cnt_5 230 420 1 994 12 944 0 0 12.949 219.936 9.087 86998.02 92178.55 90412.12 79695.84 Panel_Cnt_80 1.320 80999.23 86233.95 168.707 23.103 91690.41 83991.38 77098.93 83157.82 Panel Cnt 81 196 027 16 105 2.071 72650 27 81944 36 65892.51 84192.74 66411 35 61777 77 65683 63 50640 09 74689 91 44561 47 Panel_Cnt_82 185.191 18.610 1.007 87584.11 92288.78 82113.01 86587.93 83640.06 62053.08 Panel_Cnt_83 174 154 20.130 0.447 97662 18 96662.4 89373 3 91095.81 92816.84 85562.66 98509 64 78898 04 88711.6 75675 49 0.741 87779.11 92813.32 82247.21 91467.96 76602.77 83628.66 86197.71 Panel Cnt 84 190.539 15.201 82191.13 66543.53 59985.57 179.569 16.987 92774.13 92925.68 94453.08 85644.2 91938.3 72739.88 Panel_Cnt_85 0.143 98192.14 97657.78 98919.23 78575.85 Panel_Cnt_86 198 717 11 635 0.649 86609 19 92718 91 80751 64 94448 46 77922.09 73310 95 78699 61 65925.84 88337.84 56044 6 97046.84 93965.52 70996.17 184.983 13.792 0.100 96165.8 92919.45 95991.75 77419.62 93943.51 Panel Cnt 87 92311.84 84820.79 15.267 168.358 0.003 101451.8 96858.9 96403.9 93216.1 100245.9 92508.93 105122 91170.41 97053.15 90078.74 90557.11 90935.88 82758.79 75454.08 Panel Cnt 89 190 436 10.606 0.111 94624.93 96299.53 94392.45 92322.29 94979 41 68140.02 Panel_Cnt_91 173.833 12.137 0.000 0 0 0 0 0 0 0 1381.183 0 Panel_Cnt_93 0.006 96354.83 95425.64 93282.2 96860.56 99513.7 81278.15 75037.44 Panel_Cnt_94 Panel Cnt_95 190 393 5.899 0.000 96235 58 96266 76 93350 35 94125 08 94400 05 84920 66 95700.85 78856 78 99079 45 71880 03 179.305 6.547 0.000 99459.26 95757.91 97842.69 92411.7 100765.7 89095.26 104282.6 86088.31 100179.4 80877.73 184.834 3,770 0.000 97901.85 95757.65 96585.05 92721.84 98428.3 87558 97 100912.2 82914.12 76828.66 Panel Cnt 96 100875.5 Panel Cnt 97 195.927 1.103 0.000 94312.98 96304.54 90512.85 95822.16 90295.33 82607.45 91240.85 77019.93 98224.16 68610.7 Panel_Cnt_98 190.375 1.180 0.000 95908.2 94049.68 93710.6 96669.55 79883.84 100422.9 73103.55 Panel_Cnt_99 179 273 1 310 0.000 99488 18 95393.45 98404 3 92140.85 101484.2 89424 6 104907 6 86879 27 1011853 81696 67 91313.78 99164.11

Table C-1: Raw WASIM Position and Pressure Data

The WASIM data should be reviewed for accuracy by inspecting both the EXCEL pressure listing (Table C-1) as well as the graphical hull pressure distribution. In our analysis, it was determined that rows 91, 191, and 291 were erroneous. So they were removed from the data set by hiding the rows. In addition, the WASIM pressure was divided by 1e6 to obtain MPa, and the position converted to mm – the unit of FEMAP.

C.1.2 Data Surface Production

This EXCEL-formatted WASIM wave pressure data is simply copied to the starboard side (now creating 600 data points) and pasted into the FEMAP's Data Surface Tool (Arbitrary 3-D Coordinate Data Surface). All ten wave forms are loaded and made available for subsequent use. An example is seen in Figure C-1.

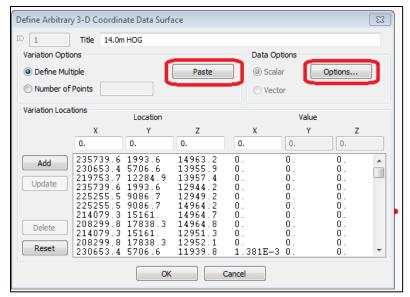


Figure C-1: FEMAP's "Data Surface Editor" Menu

Options regarding the percentage and minimum number of locations to include are available. Based primarily on visual inspection, these values were set to 0 and 4 – respectively as seen in Figure C-2.

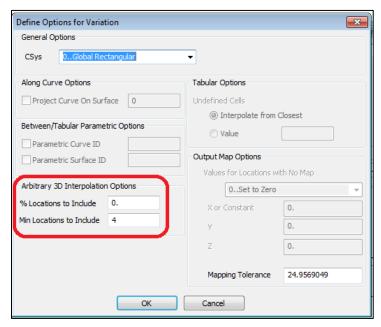


Figure C-2: FEMAP's "Define Options for Variation" Menu

C.1.3 Loadset Generation

To transform the wave pressure data into a loadset, the user must first generate a new loadset name via "Model – Load – Create/Manage Set..." from the FEMAP menu bar.

To apply the pressure load, the user next choses "Model – Load – Elemental..." from the FEMAP menu bar. The grouping of plate elements upon which the wave pressure acts, namely the outer hull, is then selected from the "Entity Selection" menu as seen in Figure C-3. Note in Figure C-3 that the hull elements can be also be visualized by selecting the paintbrush icon.

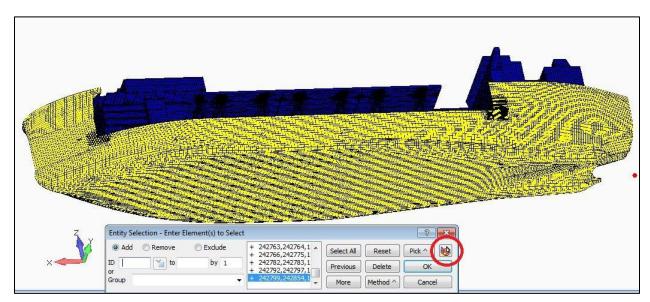


Figure C-3: FEMAP's Entity Selection Menu

Upon approval of the "Entity Selection" menu, a "Create Loads on Elements" menu similar to that shown in Figure C-4 will next appear. The pressure must be set to unity, and the Method radio button set to Data Surface. From the Data Surface drop-down the data surface desired chosen.

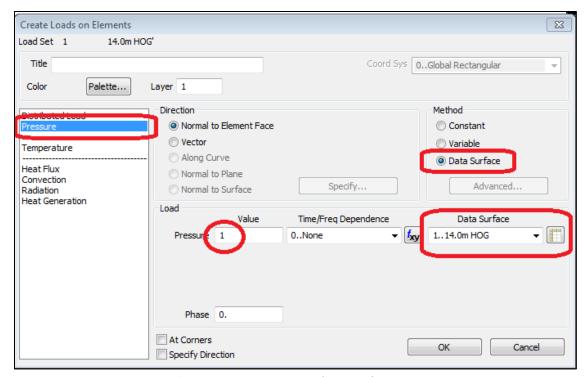


Figure C-4: FEMAP's Load Generation Menu

Next the face and side upon which the pressure acts is selected from the "Face Selection" menu as being the face 1, the front face. See Figure C-5. This face corresponds to the outer surface of the hull.

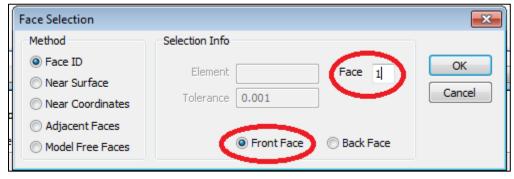


Figure C-5: FEMAP's Face Selection Menu

Asside from pressure loads, body loads (from ship motion accelerations) are also simultaneously applied to the model. The X, Y and Z accelerations that occur in the hydrodynamic model at the same time that the peak hog condition occurs for each sea state are used in the structural model. These accelerations act on the modeled mass of the elements to produce inertial forces. The applied accelerations associated with each wave condition are shown

Rotational Accel Linear Acceleration Wave **Sea State** Ht (m) X (Long) Y (Trnsv) Z (Down) Resultant Units RY (Pitch) Units 0.122 0.119 0.108 0.202 G's 1.412 Deg/s² 8 14 1196.4 1167.0 mm/s² 0.025 Rad/s² 1059.1 1978.6 Deg/s² 0.067 0.077 0.187 0.213 G's 1.392 8 11.5 657.0 2089.2 mm/s² 0.024 Rad/s² 755.1 1833.8 Deg/s² 0.096 0.107 0.084 0.166 G's 1.322 7 9 Rad/s² 941.4 mm/s² 1049.3 823.7 1632.7 0.023 Deg/s² 0.054 0.061 0.023 0.085 G's 0.646 6 6 Rad/s² 529.6 598.2 225.5 830.1 mm/s² 0.011 0.015 Deg/s² 0.044 G's 0.006 0.047 0.061 5 4 mm/s² Rad/s² 58.8 147.1 431.5 459.7 0.001

Table C-2: Accelerations at time of MAX HOG Wave

C.1.4 Additional Checks

From the X,Y, and Z WASIM position data, geometry points were generated and imported into the FEMAP model. This was done to ensure that the 300 data points describing the hull pressure panels from WASIM matched the hull profile within FEMAP. In our case, it was immediately obvious that a translation in the longitudinal direction was required to match at the vertical transom. The reasons for this fixed offset remain unclear – thus pointing to the benefit of this check.

Through the actions described above, the WASIM derived pressure acting on the elements of the hull outer surface becomes an input loadset within FEMAP. To visualize and examine the pressure distribution as seen in Figure 3-10, an output set of each input pressure load set was developed. This is accomplished by first activating the desired loadset, then generating the output set by selecting from the FEMAP menu bar "Model" – "Output" – "From Load…". This brings up the "Select Type of Load" menu seen in Figure C-6. Selecting the Pressures radio button will then populate the output with the active input loadset.

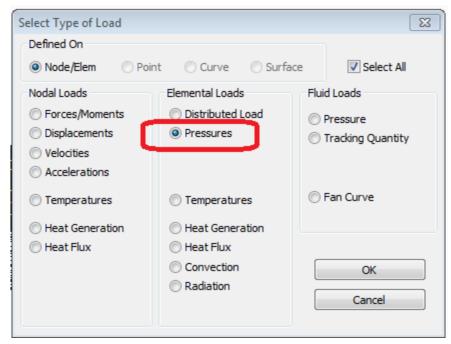
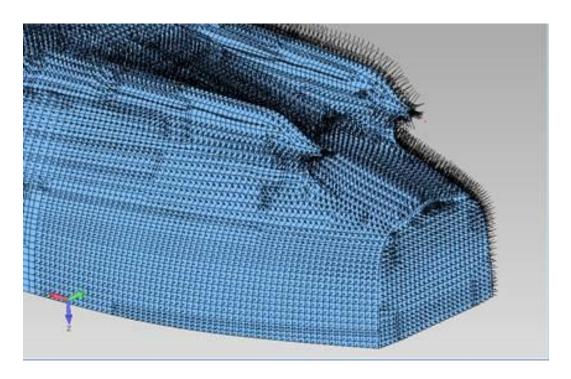


Figure C-6: FEMAP's "Select Type of Load" Menu

Finally, one should also inspect the NASTRAN generated Solve file to ensure that the pressure acts in the positive (inward) sense, in order to prevent applying suction to hull. This can be verified by displaying the pressure vectors (see picture below). The analyst should also confirm that the loads act on the outer rather than the inner surface. This can be accomplished by examining the file listing to ensure the pressure is applied to surface 1, and confirm that surface 1 is the exterior.



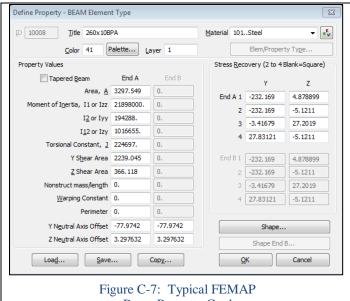
C.2 Procedure for Updating Corrosion Level

To update the plate and stiffener property id (PID) cards for each corrosion level, one could manually adjust the appropriate thickness to the desired value. However, to ease this effort, an EXCEL spreadsheet (PID_CONVERTOR.XLSX) and a FEMAP based macro are employed.

For shell properties the process is simpler. A listing of all PIDs is read into EXCEL from the NASTRAN *.NAS input file for an un-corroded vessel, searched and sorted for PSHELLs, and then scaled by the desired corrosion factor. The resulting data is transferred from EXCEL to a *.NAS file and then imported into FEMAP, thus replacing the existing PSHELL PIDS.

FEMAP's property and cross section menus for a typical PBEAM (with 0% corrosion) is shown in Figure C-7 with the corresponding NASTRAN PID card shown in Table C-2. From the information contained on the commented "Property Shape" and "Property Orientation" lines the pertinent element type and dimensions can be extracted. These values are scaled to the corrosion level desired and output as commented "Property Shape" and "Property Orientation" lines. The remaining fields in the PBEAM card are set to zero.

These updated property cards are then copied from EXCEL into a *.NAS input file and then imported into FEMAP. When the PIDs are imported, and because the id was not changed, they will replace the existing area, inertia, and other properties for the PIDs as seen in Figure C-7 with zeros. A macro is then executed that opens each property card in turn, and from the "Define Property" menu seen in Figure C-7 the macro selects the "Shape" button. From the "Cross Section Definition" menu the "Change Shape" button is enabled by the macro, resulting in the repopulation of the zeros on the PID card with the pertinent corroded area, inertia, and other quantities. See Table C-4.



Beam Property Card

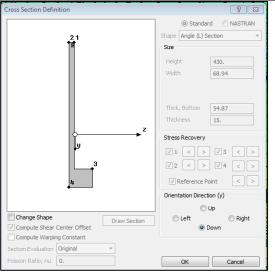


Figure C-8: FEMAPs "Cross Section Definition" Menu

Table C-3: PID10008, 0% Corroded

```
$ Femap Property 10008 : 260x10BPA

$ Femap PropShape 10008 : 11,0,260.,32.323,0.,0.,31.248,10.

$ Femap PropOrient 10008 : 11,0,3.,5.,6.,3.,1.,5.,-232.1688,4.878899

PBEAM 10008 1013297.5492.1898+7 194288.1016655. 224697. 0.+

+ -232.1694.878899-232.169 -5.1211-3.41679 27.201927.83121 -5.1211+

+ YESA 1. +

.6790028.1110273 +

-77.97423.297632-77.97423.297632
```

Table C-4: PID10008 - 25% Corrosion - Zero'd Shape

```
$ Femap Property 10008 : 260x10BPA
$ Femap PropShape 10008 : 11,0,260,32.323,0,0,23.436,7.5
$ Femap PropOrient 10008 : 11,0,3,5,6,3,1,5,-232.1688,4.878899
                                                 0.
PBEAM 10008 101 0. 0. 0.
                                         0.
                                                           0.+
                        0.
                               ο.
                                       0.
          0.
                 0.
                                             0.
                                                           0.+
          YESA
                  1.
                                                             +
```

Table C-5: PID 10008 – 25% Corrosion – Updated Shape

C.3 Procedure for Output Results File Preparation

From each analysis run the forces, moment or stress response of the desired beam and shell elements can be recovered from the FEMAP output. Although many methods can be employed, the use of FEMAP's data table has been used.

A listing of the desired output data is produced by first enabling the separate Data Table display window. From FEMAPs menu bar the user selects "List – Output – Results to Data Table" and selects the defaults from the "Send Results to Data Table" as shown in Figure C-9.

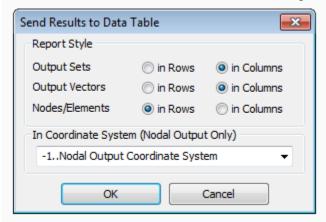


Figure C-9: FEMAP's "Send Results to Data Table" menu

From the "Results to Add to Data Table" menu that appears next select the desired output set from the available listing contained in the left hand side drop down menu. Using the Quick Filter the check boxes for the desired output stress vectors from the available listing are selected. For shells, the Normal-X, Normal-Y, and Shear-XY stresses are desired. As both the top and the bottom face of the shell are required, the output vector identifiers are 7020, 7021, and 7023 for the top, and 7420, 7421, and 7423 for the bottom face. An example is shown in Figure C-10.

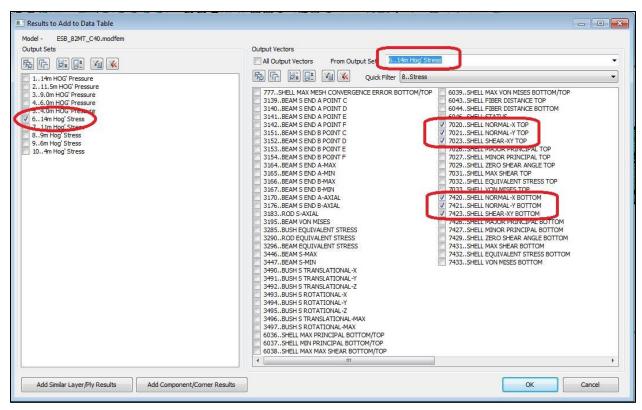


Figure C-10: FEMAP's "Results to Add to Data Table" menu

The next step is to identify which elements to recover from the "Entity Selection" menu. The grouping RECOVERED is used in Figure C-11 – which is all of the plate and shell elements within the 5 major midbody sections and contains 211,128 elements.

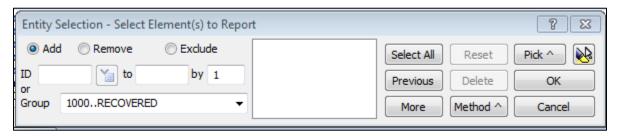


Figure C-11: FEMAP's "Entity Selection..." menu

The stress results are automatically deposited into the data table, an example of which is seen in Figure C-12.

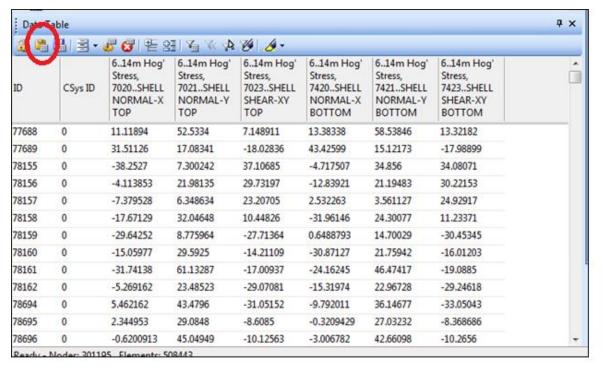


Figure C-12: FEMAP's "Data Table" Stress Output Listing Example

Selecting the highlighted Copy to Clipboard button allows for the pasting of the data into an EXCEL file.

To enable use by subsequent spreadsheet via the VLOOKUP command., these EXCEL stress output files are given a unique identifying name. The scheme used is as follows:

```
LCxxHyy.XLSX where
```

LC simply designates loadcase

xx=Wave size (ie: 14, 11, 09, 06, or 04)

yy=Corrosion level (ie: 0%, 25%, 40%, 55%, or 70%)

For example:

LC14H00 means 14m hog wave, corrosion level 0%

LC11S55 means 11.5m sag wave, corrosion level 55%

LC09H70 means 9m hog wave, corrosion level 70%

In addition, the tab is labeled "Shells", as it contains the stress results for the shell elements and is required in subsequent lookup calls.

C.4 Procedure for Establishing Stiffener Layout

To determine the buckling response of a given stiffener, its relative position within the ship, its length, its geometric and material properties, and the stress in the shell elements that adjoin said stiffener must first be developed. To this end, an EXCEL spreadsheet has been developed that determines the stiffener's layout beginning with a listing of the element ID, along with its associated material ID and the two endpoints (node IDs) for every stiffener element in the region of interest. Note that this listing is by definition element ID-ordered.

Similar files were developed for each of the major structural components (ie: hull, main deck, longitudinal and transverse bulkheads, etc). These files are labeled as MD_Layout, or Hull_Layout, etc. Since as indicated, hull buckling is the predominate response for this ship (due to its natural hog), only this spreadsheet has been employed at this time.

From the two node IDs of the stiffener, a lookup table (NODE_LISTING.XLSX) is called to determine the X, Y, and Z position of the two nodes. Based on the node's position the stiffener elements are grouped into the proper vertical region (Main deck, hull, etc), the proper transverse location (L-27 thru L+27) and the proper longitudinal location (based on its location relative to the transverse frames FR64 thru FR103). Because of the variable mesh size, a counter is also employed to determine the number of stiffener/beam elements within each longitudinal zone. (ie: between any two transverse frames).

In addition to locating/grouping the stiffener elements, the two nodes of each stiffener element are also used to determine the element ID (EID) of those shell elements that adjoin said node. Additional checks using the four (4) nodes of the shell element are required to ensure that the shell element is within the zone of interest. From the shell EID, a lookup is used to recover the shell property ID (PID), while another lookup is employed to recover the stress in the plating for any given load set.

The normal X, normal Y and shear XY stress values for the shell elements that adjoin each side of the stiffener element(s) are then averaged based on the number recorded by the counter. Thus a <u>single representative stiffener and associated shell stress</u> is developed and which forms the input to the stiffener buckling response calculations.

The results are copy paste/values into a separate results file. This file is named ESB STRESS.XLSX. and is used in subsequent stiffener buckling calculations.

The four files necessary to perform the stiffener preparation and parsing operation are:

1. NODE_LISTING.XLSX

This file is a listing of all nodes in the ship. It was found advantageous to round the Y values. The format is NODE ID, X, Y, Z. A sample listing is seen in Table C-5.

X Υ Ζ **GID** -3568 -8028 -2676 -5352 -6244 -8931 -1784 -9812 -7582

Table C-6: EXCEL File "NODE LISTING.XLSX" - Node Positions

2. BREAKOUT.XLSX

This file is a listing of the SHELL or BEAM elements in each structure. The EID, PID and associated node ID's are then parsed from the listing. A sample listing of the PLATE data is seen in Table C-6.

PID N1 N2 N3 N4 FID Index PLATE Quad 4-noded Element 81232 65879 66803 66809 66436 81232 Formulation None AttachTo Property Color Laver Nodes 4-noded Element 81233 PLATE Quad Formulation None AttachTo Color Laver Property Nodes Element 81234 PLATE Quad 4-noded None Formulation Color Layer AttachTo Property Nodes

Table C-7: EXCEL File: "BREAKOUT.XLSX" – Element Data

3. LC14H70.XLSX

4. The stress output for the loadcase in question is contained in the EXCEL file that was previously generated, a sample of which is shown in Table C-7.

19..4m HOG Stress, 19..4m HOG Stress 19..4m HOG Stress, 19..4m HOG Stress, 19..4m HOG Stress, 19..4m HOG Stress **CSys ID** ID 7020..SHELL 7021..SHELL 7023..SHELL SHEAR 7420..SHELL 7421..SHELL 7423..SHELL SHEAR **NORMAL-Y BOTTOM NORMAL-X TOP NORMAL-Y TOP** XY TOP NORMAL-X BOTTOM XY BOTTOM 77688 1.881182 22.53294 3.227229 25.61096 5.628337 0 2.812437 5.868919 5.323185 -8.970127 77689 0 11.85451 -9.064221 17.50307 0.5559489 17.01995 18.34676 78155 0 -19.74559 20.05169 -0.5277855 78156 0 -0.5639009 9.160798 14.57978 -5.400321 8.5143 14.99051 -2.374883 78157 0 -3.028555 -0.6664723 12.0074 2.206941 13.02245 -8.402686 13.21946 6.518071 -16.02189 9.200357 7.18394 78158 0 78159 0 -14.52372 2.437006 -14.70547 1.304045 5.010872 -16.44111 78160 0 -6.876542 11.74947 -7.513249 -15.26734 7.712004 -8.776855 78161 0 -10.81825 21.87727 -10.01136 -15.35836 30.73282 -8.911184 78162 0 -1.408593 10.18745 -13.82635 -7.009713 9.701918 -14.06519 78694 0 2.156883 18.62933 -14.39856 -4.121954 15.89563 -15.16602 78695 0 1.345544 9.774034 -2.458685 -0.03283681 8.636638 -2.346073 78696 1.39056 19.40382 -3.090589 0.06864493 17.93862 -3.168826 0 78697 0 -0.1580466 8.706961 0.391422 -0.8928239 7.810345 0.3647613 20.08133 78698 0 -1.884951 -2.687165 -3.582863 18.41158 -2.552238 78699 0 -10.47664 13.50282 -2.218727 -5.13237 14.49423 -2.609998 78700 O -12.03758 7.169945 -2.840601 2.215847 14.80852 -2.579219 78701 0 -5.456103 17.79278 1.792179 -2.314472 18.29318 1.303926 78702 0 -5.248883 12.09352 -2.736423 -4.656025 10.82621 -2.493225 78703 0 -5.443654 11.959 1.059864 -9.188404 8.621764 0.831319 78704 -3.218144 4.922673 -0.7277763 -5.384417 3.23007 -0.9007836

Table C-8: EXCEL File "LC04H25.XLSX" - Stress Output

5. ESB_PRESSURE.XLSX

For hull buckling, the average value of the external wave pressure acting on every hull shell element is required. This pressure is recovered from each of the input pressure load sets and is loaded into a separate tab within the EXCEL file. As sample from the tab labeled as "14mHOG" is seen in Table C-8. It is noted that the external pressure is not required for panel buckling as its effects are included in the stress resultants.

ID	COLOR	LAYER	FACE ID	PRESSURE	PHASE
27416	10	1	1	0.003396	0
27417	10	1	1	0.002683	0
27418	10	1	1	0.001177	0
27422	10	1	1	0.00096	0
27750	10	1	1	0.003396	0
27751	10	1	1	0.002683	0
27752	10	1	1	0.001177	0
27756	10	1	1	0.00096	0
28529	10	1	1	0.004939	0
28530	10	1	1	0.005011	0
28537	10	1	1	0.004387	0
28538	10	1	1	0.003673	0
28539	10	1	1	0.001748	0
28540	10	1	1	0.00149	0
28541	10	1	1	0.001353	0

Table C-9: EXCEL File "ESB PRESSURE.XLSX" - Hull Pressure

C.5 Procedure for Establishing Plate Layout

The procedure for defining the layout and stress within each equivalent plate panel (EPP) is performed similar to the procedure used for the stiffeners. A listing of the shell elements is first obtained from file BREAKOUT.XLSX. From the shell EID, the location of each of the four (4) nodes is recovered (again from NODE_LISTING.XLSX), from which the region or location of the individual element may be established.

The regions (EPPs) are classified using a multi-digit guide signifying the frame location plus the longitudinal location of the panel. The frames range from 64 to 103 while the longitudinals range from +27 to -27. Thus -6414 would indicate the EPP forward of frame 64, and to the port side of longitudinal L-27.

Also from the EID, the top and bottom stress for each element is parsed from the desired output file. Using the element counter for each region the top and bottom stress for all elements within a given equivalent panel region are averaged, resulting in a single stress representation for the EPP.

The resulting stress in the EPP for each loadset can be copied to file ESB_STRESS.XLSX for future use in the buckling calculations.

C.6 Procedure For Calculation Of Panel And Stiffener Buckling

The buckling calculations are contained in the files PLATE_BUCKLING.XLSX and STIFFENER_BUCKLING.XLSX and follow the rules as established in IACS Common Structural Rules. The generation of the plate or stiffener buckling coefficient (BC) requires the use of two files:

1. For stiffeners: ESB_STRESS.XLSX For plates: PLATE LAYOUT.XLSX

This file contains the averaged stress (and pressure) in the equivalent panel or stiffener.

2. PID PROPS.XLSX

This file contains the stiffener properties (ie: T_{WEB} , T_{FLANGE} , H_{WEB} , H_{FLANGE}) or the plate properties (Thickness). As these properties are affected by the corrosion level, a separate tab is used for each corrosion condition. An example of the stiffener and plate property listing for the first ten (10) properties is shown in Table C-9 and Table C-10 for a corrosion level of 0%.

PID J MID -AREA -I12 🗔 Description Type 🔻 Heigh -Widtl-Tweb 3297 549 2 1898+7 260x10BPA 32 323 31 248 4294.715 3.8355+7 300x11BPA 40.156 34.117 1.3333+8 2010446 EngineGirderFlange 1.4072+7 MasslessBeam 2153.004 62819.01 89658.98 200x9BPA 24.348 2.0345+7 2.0345+7 3.4355+7 MassLess Bar 1.457+9 7.8867+7 4541966 TR.FR.850X300x12/35MTA 8.2488+8 1052409 TR.FR.800x100x13/25MTA 5.3569+8 1195803 TR.FR.650x150x13/25MTA 3729.972 2.1165+7 323307 TR.FR.240x12BPA 40.95 29.36

Table C-10: EXCEL File: "PID PROPS.XLSX" - Stiffener Properties - Corrosion= 0%

Table C-11: EXCEL File: "PID PROPS.XLSX" – Shell Properties – Corrosion=0%

PID 🛒	MID	T 🔻	MID2 🚽	12I/T 🔻	MID3 -	J	TS/T 🔻
10001	101	25	101	0	101	0	0
10002	101	56.95353	101	0	101	0	0
10003	101	63.20698	101	0	101	0	0
10004	103	50	101	0	101	0	0
10005	103	50	101	0	101	0	0
10006	101	20	101	0	101	0	0
10007	101	42.89169	101	0	101	0	0
10014	101	12	101	0	101	0	0
10015	101	14	101	0	101	0	0
10016	101	19	101	0	101	0	0

Appendix D Buckling Calculations

D.1 Plate Buckling

Three separate buckling factors (K) are determined for a plate based on the normal stress acting in the plate's long direction (σ_X , Case #1), the plate's short (or transverse) direction (σ_Y , Case #2), or the shear stress (τ_{XY} , Case #15) in the plate. Each buckling factor is multiplied by a correction factor which is dependent on the plate's aspect ratio (panel length / width).

For a uniform compressive stress acting in the plate's long direction, the buckling factor is reduced to $K_X = 4.0$ * F_{Long} , where the correction factor F_{Long} is determined based on the stiffener type and end supports as detailed in Figure D-2. The critical buckling stress is equal to the plating yield strength multiplied by the reduction factor C_X as outlined in Figure D-1.

Case	Stress ratio ψ		Buckling factor K	Reduction factor C
1	$K_{x} = F_{lo}$		$\frac{8.4}{\psi + 1.1}$	When $\sigma_x \le 0$: $C_x = 1$ When $\sigma_x > 0$:
$\psi \cdot \sigma_s$	$0>\psi>-1$	$K_x = F_{lo}$	$_{ong}$ [7.63 – ψ (6.26 – 10 ψ)]	$C_x = 1 \text{ for } \lambda \le \lambda_c$ $C_x = c \left(\frac{1}{\lambda} - \frac{0.22}{\lambda^2}\right) \text{ for } \lambda > \lambda_c$
	ψ≤-1	$K_{x} = F_{lo}$	$_{\text{ong}} [5.975(1-\psi)^2]$	where: $c = (1.25 - 0.12 \psi) \le 1.25$ $\lambda_c = \frac{c}{2} \left(1 + \sqrt{1 - \frac{0.88}{c}} \right)$

Figure D-1: Plate Buckling Factor (K_X)

		Table 2	: Correction factor F _{long}	
	Structural e	element types	F _{long}	С
Unstiffene	d Panel		1.0	N/A
Stiffened	Stiffener no	ot fixed at both ends	1.0	N/A
Panel	Stiffener	Flat bar (1)		0.10
	fixed at both ends	Bulb profile	$F_{long} = c + 1$ for $\frac{t_w}{t_p} > 1$	0.30
	both chas	Angle profile		0.40
		T profile	$F_{long} = c \left(\frac{t_w}{t_p}\right)^3 + 1 \text{ for } \frac{t_w}{t_p} \le 1$	0.30

Figure D-2: Plate Buckling Correction Factor (F_{Long})



If the uniform compressive stress acts in the plate's short direction, the buckling factor K_Y reduces to $K_Y=F_{TRAN}*(1+1/\alpha^2)^2$. While the correction factor F_{TRAN} is equal to unity, the reduction factor C_Y is governed by the relationships defined below in Figure D-3.

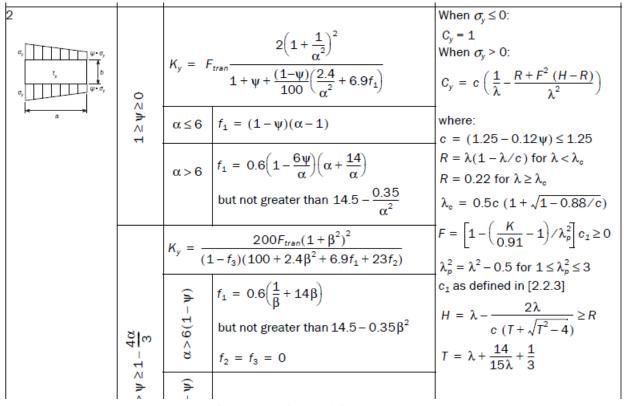


Figure D-3: Plate Buckling Factor (K_Y)

For shear stress loading of the plate, the buckling factor $K\tau$ is a function of the plate geometry, while the critical shear stress reduction factor $C\tau = 1$ for $\lambda < 0.84$, and to $0.84/\lambda$ for $\lambda > 0.84$, where λ is the reference degree of slenderness.



Case		Aspect ratio α	Buckling factor K
15 t_{p} t_{p} t_{p}	-	$K_{\tau} = \sqrt{3}$	$\overline{3}\left[5.34 + \frac{4}{\alpha^2}\right]$



D.2 Stiffener Buckling

The ultimate buckling capacity for stiffeners is developed not from the recovered beam stresses in the stiffener itself, but rather from the stress response of the adjoining plating.

The buckling response is a function of three stress quantities according to the following interaction formula:

$$BC = (\sigma_a + \sigma_b + \sigma_w) / F_{TY}$$

1. Axial stress

Predominate response.

Function of plate and stiffener geometry.

Directly proportional to plating normal stress-X.

$$\sigma_{a} = \sigma_{x} \frac{s t_{p} + A_{s}}{b_{eff1} t_{p} + A_{s}}$$

2. Bending Stress

Function of lateral deformation (w) and lateral load (Pz)

Function of external lateral pressure (P)

Function of stiffener and plate geometry

: Bending stress in the stiffener, in N/mm²:

$$\sigma_b = \frac{M_0 + M_1}{10007}$$

: Net section modulus of stiffener, in cm3, in

be taken as:

$$M_1 = C_i \frac{|P| s \ell^2}{24 \times 10^3}$$
 for continuous stiffener

$$M_1 = C_i \frac{|P| s \ell^2}{8 \times 10^3}$$
 for sniped stiffener

$$M_0 = F_E \left(\frac{P_z w}{c_f - P_z} \right)$$
 with $c_f - P_z > 0$



 P_z : Nominal lateral load, in N/mm², acting on the stiffener due to stresses, σ_x , σ_y and τ , in the attached plating in way of the stiffener mid span:

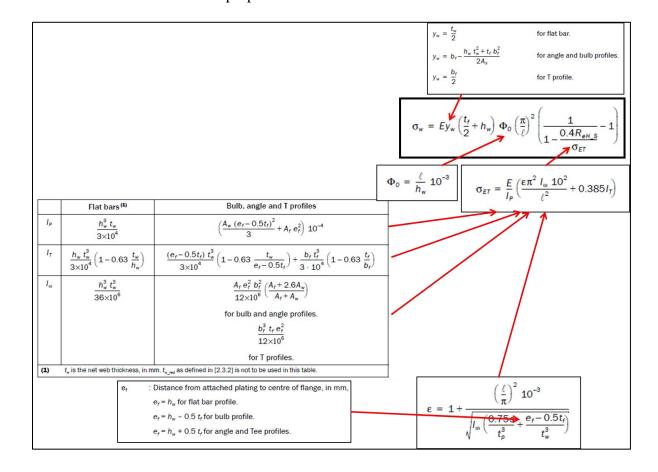
$$P_z \, = \, \frac{t_p}{s} \left(\sigma_{x \text{I}} \left(\frac{\pi \, s}{\ell} \right)^2 + 2 \, \text{c} \, \gamma \, \sigma_{y} + \sqrt{2} \tau_{\text{I}} \right)$$

$$\sigma_{xl} = \gamma \sigma_x \left(1 + \frac{A_s}{st_p} \right)$$
 but not less than 0

$$\tau_1 = \gamma |\tau| - t_p \sqrt{R_{eH_p} E\left(\frac{m_1}{a^2} + \frac{m_2}{b^2}\right)}$$
 but not less than 0

3. Torsional Deformation Stress

Function of fixity of ends Function of stiffener and plate geometry Function of material properties





Appendix E ESB Buckling Response

In a hogging condition, the bottom and lower sides of the ship's hull will be in compression while the upper sides and Mission Deck experience a tensile condition. As stated previously, the natural (still-water) hog of the ship coupled with hogging from waves is the driving loading condition. The buckling coefficients seen in the following figures are therefore for the bottom and lower side plating and stiffeners of the ship in hogging conditions.

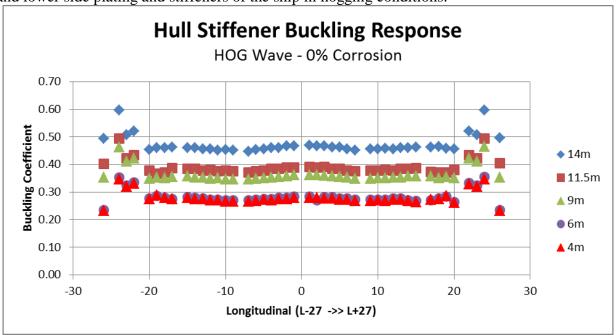


Figure E-1: Hull Stiffener Buckling Response – Hog Wave - 0% Corrosion

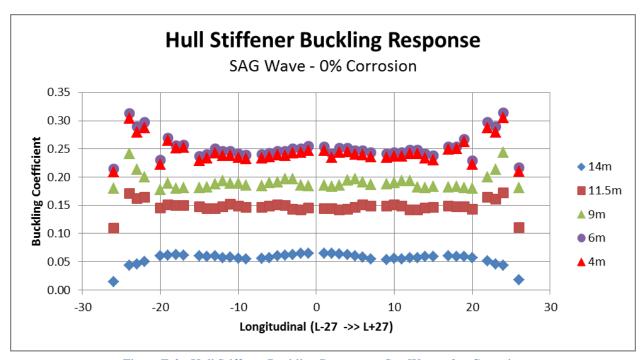


Figure E-2: Hull Stiffener Buckling Response – Sag Wave - 0% Corrosion



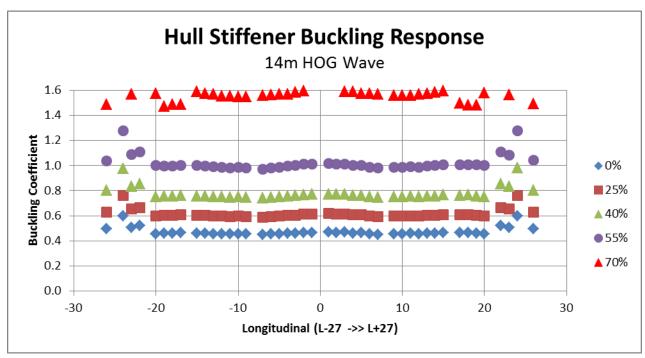


Figure E-3: Hull Stiffener Buckling Response for Various Corrosion Levels – 14m Hog Wave

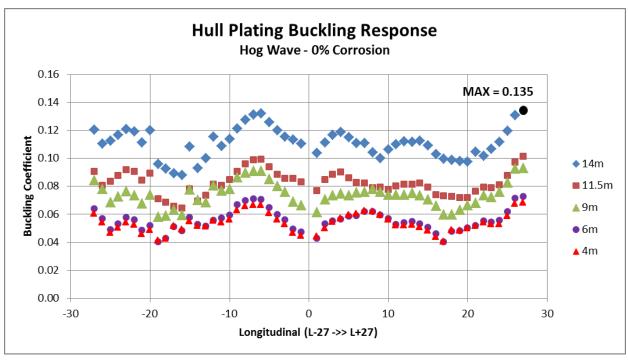


Figure E-4: Hull Plating Buckling Response - Hog Wave - 0% Corrosion



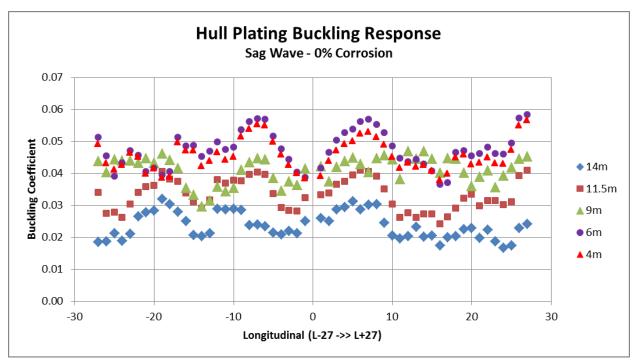


Figure E-5: Hull Plating Buckling Response – Sag Wave - 0% Corrosion

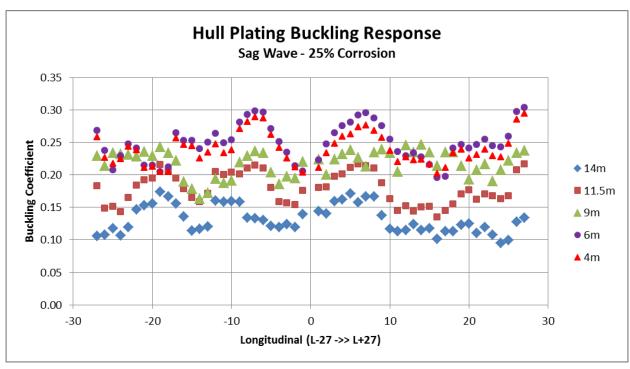


Figure E-6: Hull Plating Buckling Response – Sag Wave - 25% Corrosion

